# Dynamical Algebraic Combinatorics, Asynchronous Cellular Automata, and Toggling Independent Sets Automata 2021

#### Alex McDonough

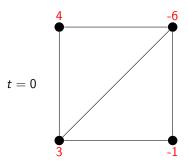
Joint work with Laurent David (UT Dallas), Colin Defant (Princeton), Mike Joseph (Dalton State), and Matthew Macauley (Clemson)

Department of Mathematics
Brown University -> University of California, Davis

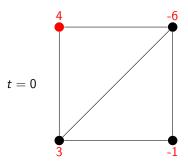
13 July, 2021



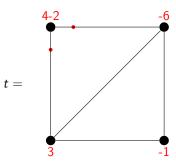
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



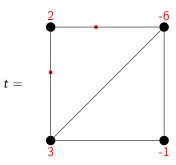
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



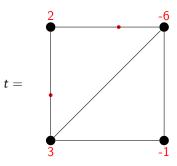
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



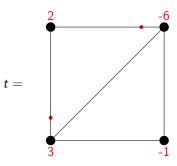
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



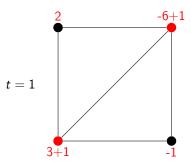
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



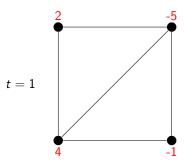
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



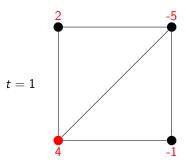
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



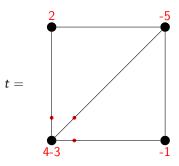
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



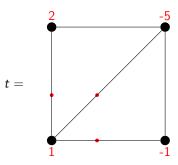
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



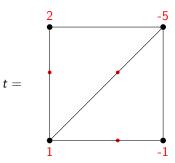
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



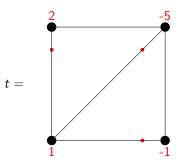
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



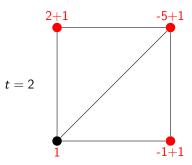
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



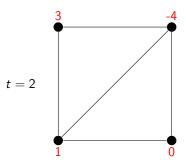
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



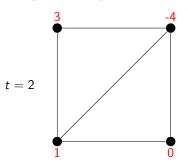
• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.

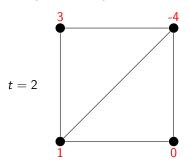


• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



• If the object and action come from algebraic combinatorics, then the study of this system is called **dynamical algebraic combinatorics** (DAC).

• In general, to have a **discrete dynamical system** we need an *object* and an *action* which changes the object for every discrete time step.



- If the object and action come from algebraic combinatorics, then the study of this system is called **dynamical algebraic combinatorics** (DAC).
- Some popular DAC problems can be cast and analyzed as automata networks.

# Dynamical Algebraic Combinatorics & Cellular Automata

 DAC and CA theory are fairly separate fields; they were developed to answer different kinds of questions, and there is not a lot of overlap of researchers.

# Dynamical Algebraic Combinatorics & Cellular Automata

- DAC and CA theory are fairly separate fields; they were developed to answer different kinds of questions, and there is not a lot of overlap of researchers.
- However, despite evolving independently, there is a lot of overlap in the structures that are studied.

# Dynamical Algebraic Combinatorics & Cellular Automata

- DAC and CA theory are fairly separate fields; they were developed to answer different kinds of questions, and there is not a lot of overlap of researchers.
- However, despite evolving independently, there is a lot of overlap in the structures that are studied.





Images from Wikipedia

#### **Posets**

#### Definition

A partially-ordered set or poset is a set P together with a relation  $\leq$  that is:

- reflexive: x < x for all  $x \in P$ .
- antisymmetric: If  $x \le y$  and  $y \le x$ , then x = y.
- transitive: If  $x \le y$  and  $y \le z$ , then  $x \le z$ .

#### **Posets**

#### Definition

A partially-ordered set or poset is a set P together with a relation  $\leq$  that is:

- reflexive: x < x for all  $x \in P$
- antisymmetric: If  $x \le y$  and  $y \le x$ , then x = y.
- transitive: If  $x \le y$  and  $y \le z$ , then  $x \le z$ .

#### Example

• Consider ordered pairs where  $(a, b) \le (c, d)$  if  $a \le c$  and  $b \le d$ .

$$(3,2) \leq (3,7)$$

$$(4,3) \leq (7,8)$$

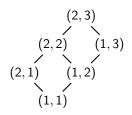
(3,4) and (7,2) cannot be compared.

# Hasse Diagrams

#### Definition

Each poset has an associated graph called a **Hasse diagram**.

- The elements of *P* form the vertices of the diagram.
- If  $x \le y$ , we write y higher up than x.
- If x < y and there is no z such that x < z < y, we connect x and y with an edge and say y covers x (written x < y).



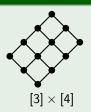
The poset  $P = [2] \times [3]$ .

# More Examples of Hasse Diagrams

# Example (Products of two chains)



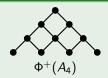




### Example (Type A positive root posets)





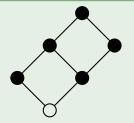


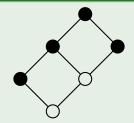
# **Up-sets of Posets**

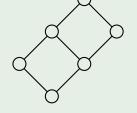
#### Definition

• An **up-set** (or **order filter**) of a poset P is a subset  $U \subseteq P$  such that if  $x \in U$  and  $x \le y$ , then  $y \in U$ .

#### Example







some up-sets of  $[2] \times [3]$ 

#### Rowmotion

- Let P be a poset and  $\mathcal{U}(P)$  be the set of up-sets.
- We define a group action on  $\mathcal{U}(P)$  called **rowmotion**.

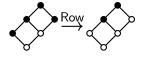
#### Rowmotion

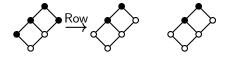
- Let P be a poset and  $\mathcal{U}(P)$  be the set of up-sets.
- We define a group action on  $\mathcal{U}(P)$  called **rowmotion**.
- Given  $U \in \mathcal{U}(P)$ , perform the following 3 steps:
  - $\bullet$   $\nabla$ : Take the minimal elements.
  - $\bullet$   $\Delta^{-1}$ : Saturate downward.
  - Θ: Take the complement.
- We call the result Row(U)

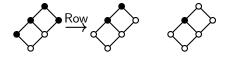
#### Rowmotion

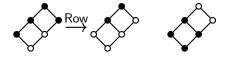
- Let P be a poset and  $\mathcal{U}(P)$  be the set of up-sets.
- We define a group action on  $\mathcal{U}(P)$  called **rowmotion**.
- Given  $U \in \mathcal{U}(P)$ , perform the following 3 steps:
  - $\bullet$   $\nabla$ : Take the minimal elements.
  - $\triangle$   $\Delta^{-1}$ : Saturate downward.
  - Θ: Take the complement.
- We call the result Row(*U*)

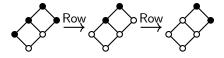
# Example $\Delta^{-1}$ $\Theta$

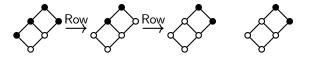


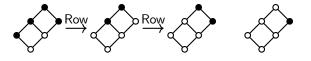


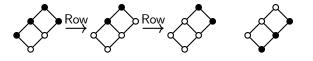


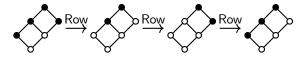


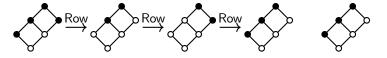


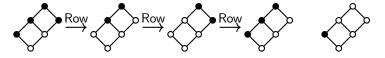


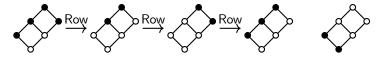


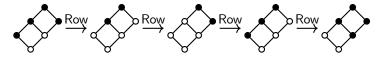


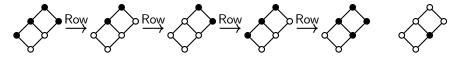


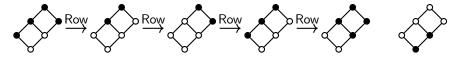


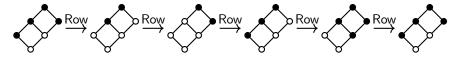


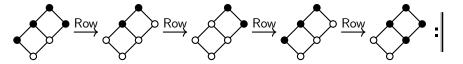






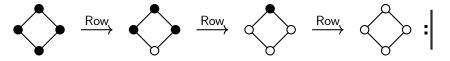


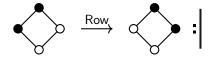




10/36

On [2]  $\times$  [3], up-set rowmotion is periodic with period 5.





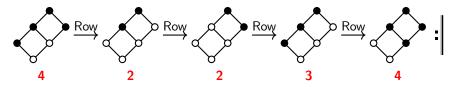
On [2]  $\times$  [2], up-set rowmotion is periodic with period 4.

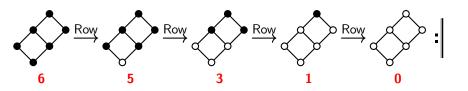
### Theorem (Brouwer–Schrijver 1974)

On  $[a] \times [b]$ , rowmotion is periodic with period a + b.

12 / 36

# Cardinalities in $[2] \times [3]$





# Cardinalities in $[2] \times [3]$

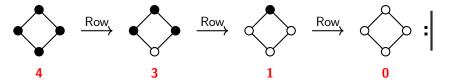
#### Average cardinality: 3

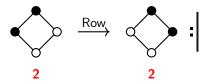
# Cardinalities in $[2] \times [3]$

### Average cardinality: 3

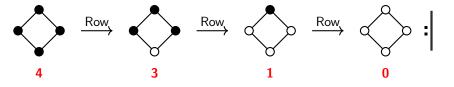
Average cardinality: 3

# Cardinalities in $[2] \times [2]$



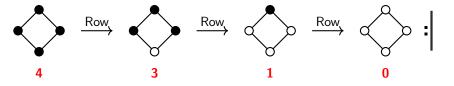


# Cardinalities in $[2] \times [2]$



#### Average cardinality: 2

# Cardinalities in $[2] \times [2]$



#### Average cardinality: 2

$$\begin{array}{c|c}
 & \underset{2}{\text{Row}} & \xrightarrow{\text{Row}} & \vdots \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\
 & & \\$$

Average cardinality: 2

## Theorem (Brouwer–Schrijver 1974)

On  $[a] \times [b]$ , rowmotion is periodic with period a + b.

## Theorem (Propp–Roby 2013)

On  $[a] \times [b]$ , the average cardinality of up-sets across any rowmotion orbit is ab/2.

## Theorem (Brouwer–Schrijver 1974)

On  $[a] \times [b]$ , rowmotion is periodic with period a + b.

## Theorem (Propp-Roby 2013)

On  $[a] \times [b]$ , the average cardinality of up-sets across any rowmotion orbit is ab/2. We say that the cardinality is **homomesic** (or ab/2-**mesic**) under the action of rowmotion.

## Theorem (Brouwer–Schrijver 1974)

On  $[a] \times [b]$ , rowmotion is periodic with period a + b.

## Theorem (Propp-Roby 2013)

On  $[a] \times [b]$ , the average cardinality of up-sets across any rowmotion orbit is ab/2. We say that the cardinality is **homomesic** under the action of rowmotion with average ab/2.

 In general a discrete dynamical system exhibits homomesy when the average of some statistic is constant over all orbits.

### Theorem (Brouwer–Schrijver 1974)

On  $[a] \times [b]$ , rowmotion is periodic with period a + b.

### Theorem (Propp-Roby 2013)

On  $[a] \times [b]$ , the average cardinality of up-sets across any rowmotion orbit is ab/2. We say that the cardinality is **homomesic** under the action of rowmotion with average ab/2.

- In general a discrete dynamical system exhibits homomesy when the average of some statistic is constant over all orbits.
- The homomesy phenomenon was first observed by Panyushev in 2007 and a shocking number of examples have been found since then.

## **Toggles**

## Definition (Cameron and Fon-Der-Flaass 1995)

Let  $\mathcal{U}(P)$  be the set of up-sets of a finite poset P. Let  $e \in P$ . Then the **toggle** corresponding to e is the map  $T_e : \mathcal{U}(P) \to \mathcal{U}(P)$  defined by

$$T_e(U) = \left\{ egin{array}{ll} U \cup \{e\} & ext{ if } e 
otin U \text{ and } U \cup \{e\} \in \mathcal{U}(P), \\ U \setminus \{e\} & ext{ if } e \in U \text{ and } U \setminus \{e\} \in \mathcal{U}(P), \\ U & ext{ otherwise.} \end{array} 
ight.$$

## **Toggles**

## Definition (Cameron and Fon-Der-Flaass 1995)

Let  $\mathcal{U}(P)$  be the set of up-sets of a finite poset P. Let  $e \in P$ . Then the **toggle** corresponding to e is the map  $T_e : \mathcal{U}(P) \to \mathcal{U}(P)$  defined by

$$\mathcal{T}_e(U) = \left\{ \begin{array}{ll} U \cup \{e\} & \text{if } e \not\in U \text{ and } U \cup \{e\} \in \mathcal{U}(P), \\ U \setminus \{e\} & \text{if } e \in U \text{ and } U \setminus \{e\} \in \mathcal{U}(P), \\ U & \text{otherwise.} \end{array} \right.$$

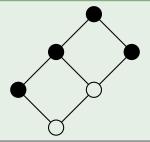
#### Definition

These toggles generate a group called the **toggle group** (also called the **dynamics group** by CA theorists).

### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.

### Example

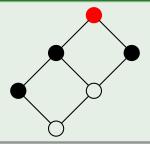


18 / 36

### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.

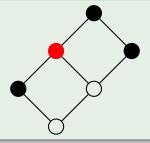
### Example



18 / 36

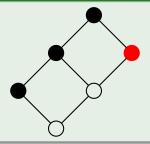
## Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



## Theorem (Cameron and Fon-Der-Flaass 1995)

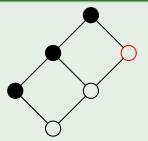
Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.

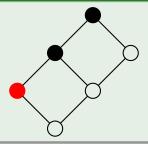
### Example



18 / 36

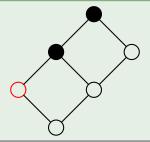
### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



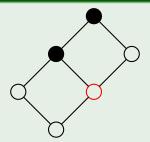
### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



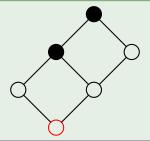
### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



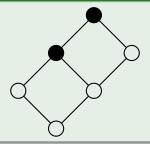
### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



### Theorem (Cameron and Fon-Der-Flaass 1995)

Applying the toggles  $T_e$  from top to bottom across the rows of P gives rowmotion on up-sets of P.



#### Rowmotion and Promotion

## Theorem (Striker–Williams 2012)

Applying the toggles  $T_e$  from left to right down the columns of P gives another known group action called **promotion**.

#### Rowmotion and Promotion

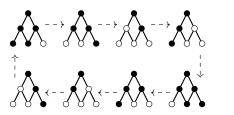
#### Theorem (Striker–Williams 2012)

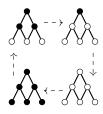
Applying the toggles  $T_e$  from left to right down the columns of P gives another known group action called **promotion**.

#### Corollary

There is an **equivariant bijection** between up-sets under the rowmotion group action and up-sets under the promotion group action.

#### Rowmotion and Promotion





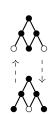
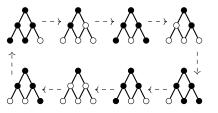
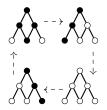


Figure: Rowmotion – toggle "by rows, top-to-bottom".





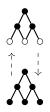


Figure: Promotion – toggle "by columns, left-to-right".

#### Rowmotion and Promotion

#### Theorem (Striker–Williams 2012)

Applying the toggles  $T_e$  from left to right down the columns of P gives another known group action called **promotion**.

#### Corollary

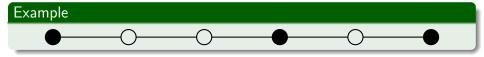
There is an **equivariant bijection** between up-sets under the rowmotion group action and promotion group action.

• The corollary follows from *Coxeter theory* (the two actions are *torically equivalent*).

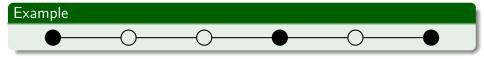
 Rowmotion and promotion aren't the only dynamical system that can be described by toggling.

22 / 36

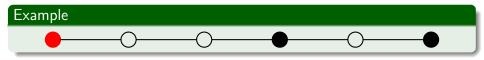
- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an **independent set** (set of nonadjacent vertices) on a path graph.



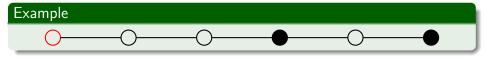
- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.



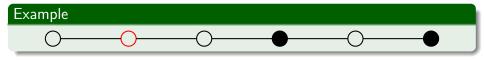
- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we toggle each vertex, switching its status if we still have a independent set.



- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we toggle each vertex, switching its status if we still have a independent set.

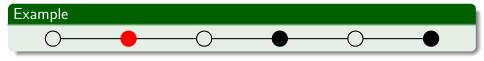


- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.

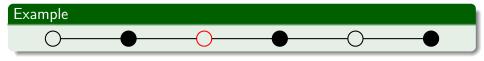


22 / 36

- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.

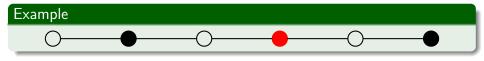


- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.

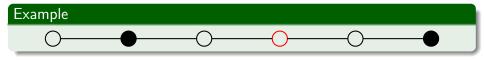


22 / 36

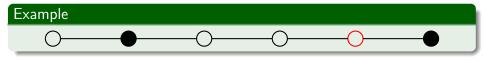
- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.



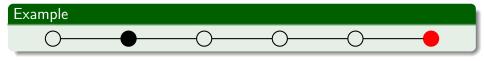
- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.



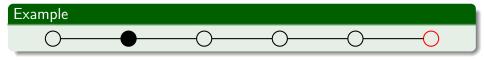
- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.



- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.

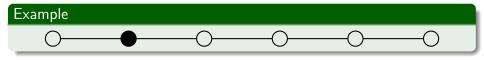


- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.

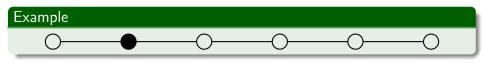


22 / 36

- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we **toggle** each vertex, switching its status if we still have a independent set.



- Rowmotion and promotion aren't the only dynamical system that can be described by toggling.
- Consider an independent set (set of nonadjacent vertices) on a path graph.
- From left to right, we toggle each vertex, switching its status if we still have a independent set.



• We end up with a new independent set and can repeat the process indefinitely.

• The dynamics of this kind of toggling are more easily seen on an array.

X	$v_1$	<i>V</i> <sub>2</sub>	<i>V</i> 3	<i>V</i> <sub>4</sub>	<i>V</i> <sub>5</sub>	<i>v</i> <sub>6</sub>
$x^{(0)}$	1	0	0	1	0	1
$x^{(1)}$	0	1	0	0	0	0
$x^{(2)}$	0	0	1	0	1	0
$x^{(3)}$	1	0	0	0	0	1
$x^{(4)}$	0	1	0	1	0	0
$x^{(5)}$	0	0	0	0	1	0
$x^{(6)}$	1	0	1	0	0	1
$x^{(7)}$	0	0	0	1	0	0
$x^{(8)}$	1	0	0	0	1	0
$x^{(9)}$	0	1	0	0	0	1
$x^{(10)}$	0	0	1	0	0	0

ullet Here, each row is a independent set of entries marked with 1s.

• The dynamics of this kind of toggling are more easily seen on an array.

X	$v_1$	<i>V</i> <sub>2</sub>	<i>V</i> 3	<i>V</i> 4	<i>V</i> <sub>5</sub>	<i>V</i> <sub>6</sub>
x <sup>(0)</sup>	1	0	0	1	0	1
$x^{(1)}$	0	1	0	0	0	0
$x^{(2)}$	0	0	1	0	1	0
$x^{(3)}$	1	0	0	0	0	1
$x^{(4)}$	0	1	0	1	0	0
$x^{(5)}$	0	0	0	0	1	0
$x^{(6)}$	1	0	1	0	0	1
$x^{(7)}$	0	0	0	1	0	0
$x^{(8)}$	1	0	0	0	1	0
$x^{(9)}$	0	1	0	0	0	1
$x^{(10)}$	0	0	1	0	0	0
Sum	4	3	3	3	3	4

• Here, each row is a independent set of entries marked with 1s.

• The dynamics of this kind of toggling are more easily seen on an array.

X	$v_1$	$v_2$	<i>V</i> 3	<i>V</i> 4	<i>V</i> <sub>5</sub>	<i>V</i> <sub>6</sub>
$x^{(0)}$	1	0	0	1	0	1
$x^{(1)}$	0	1	0	0	0	0
$x^{(2)}$	0	0	1	0	1	0
$x^{(3)}$	1	0	0	0	0	1
$x^{(4)}$	0	1	0	1	0	0
$x^{(5)}$	0	0	0	0	1	0
$x^{(6)}$	1	0	1	0	0	1
$x^{(7)}$	0	0	0	1	0	0
$x^{(8)}$	1	0	0	0	1	0
$x^{(9)}$	0	1	0	0	0	1
$x^{(10)}$	0	0	1	0	0	0
Sum	4	3	3	3	3	4

#### Theorem (Joseph-Roby 2018)

The sum vector always reads the same left-to-right as right-to-left.

• Here, each row is a independent set of entries marked with 1s.

• The dynamics of this kind of toggling are more easily seen on an array.

X	$v_1$	<i>V</i> <sub>2</sub>	<i>V</i> 3	<i>V</i> <sub>4</sub>	<i>V</i> <sub>5</sub>	<i>v</i> <sub>6</sub>
$x^{(0)}$	1	0	0	1	0	1
$x^{(1)}$	0	1	0	0	0	0
$x^{(2)}$	0	0	1	0	1	0
$x^{(3)}$	1	0	0	0	0	1
$x^{(4)}$	0	1	0	1	0	0
$x^{(5)}$	0	0	0	0	1	0
$x^{(6)}$	1	0	1	0	0	1
$X^{(7)}$	0	0	0	1	0	0
$x^{(8)}$	1	0	0	0	1	0
$x^{(9)}$	0	1	0	0	0	1
$x^{(10)}$	0	0	1	0	0	0
Sum	4	3	3	3	3	4

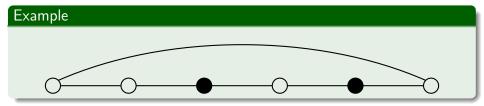
#### Theorem (Joseph-Roby 2018)

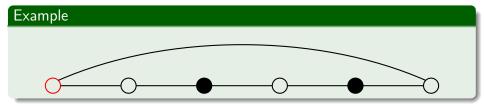
The sum vector always reads the same left-to-right as right-to-left.

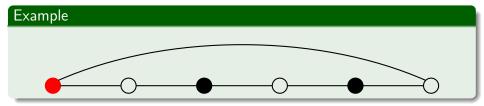
#### Theorem (Joseph-Roby 2018)

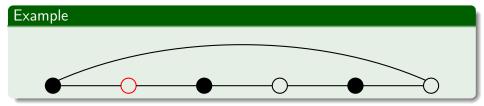
If you double the first entry in the sum vector and add the second, this gives the number of rows.

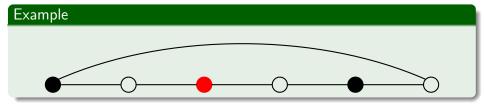
• Here, each row is a independent set of entries marked with 1s.

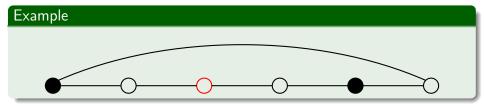


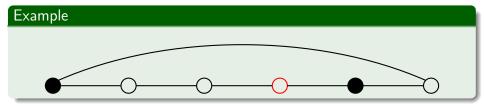


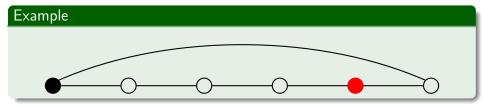


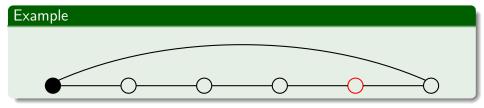


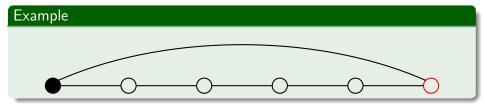


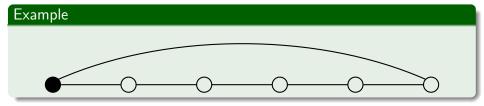




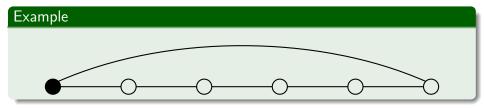








• Instead of working on a path graph, we can also toggle vertices on a cycle.



• This dynamical system is similar to the one on the path graph, but we no longer have "special" vertices.

• As before, we use an array for easier visualization.

X	$v_1$	<i>V</i> <sub>2</sub>	<i>V</i> <sub>3</sub>	<i>V</i> 4	<i>V</i> <sub>5</sub>	<i>v</i> <sub>6</sub>
$x^{(0)}$	0	0	1	0	1	0
$x^{(1)}$	1	0	0	0	0	0
$x^{(2)}$	0	1	0	1	0	1
$x^{(3)}$	0	0	0	0	0	0
$x^{(4)}$	1	0	1	0	1	0
$x^{(5)}$	0	0	0	0	0	1
$x^{(6)}$	0	1	0	1	0	0
$x^{(7)}$	0	0	0	0	1	0
$x^{(8)}$	1	0	1	0	0	0
$x^{(9)}$	0	0	0	1	0	1
$x^{(10)}$	0	1	0	0	0	0

• This system is the main focus of our ongoing work, and will be the star of Matthew Macauley's talk tomorrow!

• Whenever we toggle vertex  $v_i$ , its new state depends on the states of  $v_{i-1}$ ,  $v_i$ , and  $v_{i+1}$ . Let  $x_i$  be the pre-toggle state of  $v_i$  and  $T_i(x_{i-1}, x_i, x_{i+1})$  be the post-toggle state.

• Whenever we toggle vertex  $v_i$ , its new state depends on the states of  $v_{i-1}$ ,  $v_i$ , and  $v_{i+1}$ . Let  $x_i$  be the pre-toggle state of  $v_i$  and  $T_i(x_{i-1}, x_i, x_{i+1})$  be the post-toggle state.

$(x_{i-1},x_i,x_{i+1})$	111	110	101	100	011	010	001	000
$T_i(x_{i-1},x_i,x_{i+1})$	n/a	n/a	0	0	n/a	0	0	1

• Whenever we toggle vertex  $v_i$ , its new state depends on the states of  $v_{i-1}$ ,  $v_i$ , and  $v_{i+1}$ . Let  $x_i$  be the pre-toggle state of  $v_i$  and  $T_i(x_{i-1}, x_i, x_{i+1})$  be the post-toggle state.

• The  $2^8=256$  maps from  $\{0,1\}^3 \to \{0,1\}$  are called **elementary cellular** automaton (ECA) rules.

• Whenever we toggle vertex  $v_i$ , its new state depends on the states of  $v_{i-1}$ ,  $v_i$ , and  $v_{i+1}$ . Let  $x_i$  be the pre-toggle state of  $v_i$  and  $T_i(x_{i-1}, x_i, x_{i+1})$  be the post-toggle state.

- The  $2^8=256$  maps from  $\{0,1\}^3 \to \{0,1\}$  are called **elementary cellular** automaton (ECA) rules.
- If we repeatedly toggle the vertices in some fixed order using an ECA rule, we get an asynchronous cellular automata (ACA).

• Whenever we toggle vertex  $v_i$ , its new state depends on the states of  $v_{i-1}$ ,  $v_i$ , and  $v_{i+1}$ . Let  $x_i$  be the pre-toggle state of  $v_i$  and  $T_i(x_{i-1}, x_i, x_{i+1})$  be the post-toggle state.

- The  $2^8=256$  maps from  $\{0,1\}^3 \to \{0,1\}$  are called **elementary cellular** automaton (ECA) rules.
- If we repeatedly toggle the vertices in some fixed order using an ECA rule, we get an asynchronous cellular automata (ACA).
- An ACA is called togglable (or order independent) if each toggle is a bijection on the periodic points.

### Theorem (Macauley–McCammond–Mortveit 2008)

 $104\ \text{of the}\ 256\ \text{ECA}$  rules produce togglable ACAs.

### Theorem (Macauley–McCammond–Mortveit 2008)

104 of the 256 ECA rules produce togglable ACAs.

• When an ACA is togglable, each "toggle" map is an involution or identity.

#### Theorem (Macauley–McCammond–Mortveit 2008)

104 of the 256 ECA rules produce togglable ACAs.

- When an ACA is togglable, each "toggle" map is an involution or identity.
- Recall that these toggles generate a group called the toggle group.

#### Theorem (Macauley–McCammond–Mortveit 2008)

104 of the 256 ECA rules produce togglable ACAs.

- When an ACA is togglable, each "toggle" map is an involution or identity.
- Recall that these toggles generate a group called the toggle group.
- In 2011, Macauley, McCammond, and Mortveit classified the toggle groups associated with these togglable ACAs.

#### Theorem (Macauley–McCammond–Mortveit 2008)

104 of the 256 ECA rules produce togglable ACAs.

- When an ACA is togglable, each "toggle" map is an involution or identity.
- Recall that these toggles generate a group called the toggle group.
- In 2011, Macauley, McCammond, and Mortveit classified the toggle groups associated with these togglable ACAs.
- In 2015, Goles, Montalva-Medel, Mortveit, and Ramirez-Flandes generalized to block update orders.

#### Theorem (Macauley–McCammond–Mortveit 2008)

104 of the 256 ECA rules produce togglable ACAs.

- When an ACA is togglable, each "toggle" map is an involution or identity.
- Recall that these toggles generate a group called the toggle group.
- In 2011, Macauley, McCammond, and Mortveit classified the toggle groups associated with these togglable ACAs.
- In 2015, Goles, Montalva-Medel, Mortveit, and Ramirez-Flandes generalized to block update orders.
- In 2018, Salo proved a conjecture about ECA rule 57 and Defant further explored ECA rules 150 and 105.

• Toggle groups are all quotients of **Coxeter groups**.

- Toggle groups are all quotients of Coxeter groups.
- Coxeter groups can be defined geometrically in terms of *reflections*, but I will focus on the combinatorial perspective.

- Toggle groups are all quotients of **Coxeter groups**.
- Coxeter groups can be defined geometrically in terms of reflections, but I will
  focus on the combinatorial perspective.

#### Definition

A **Coxeter system** is a pair (W, S) where W is a group generated by the set  $S = \{s_1, \ldots, s_n\}$  with the presentation

$$W = \langle s_1, \dots, s_n \mid s_i^2 = 1, (s_i s_j)^{m_{ij}} = 1 \text{ for } i \neq j \rangle,$$

where  $m_{ij} = |s_i s_j| \in \{2, 3, \dots\} \cup \{\infty\}$ .

- Toggle groups are all quotients of Coxeter groups.
- Coxeter groups can be defined geometrically in terms of *reflections*, but I will focus on the combinatorial perspective.

#### Definition

A **Coxeter system** is a pair (W, S) where W is a group generated by the set  $S = \{s_1, \ldots, s_n\}$  with the presentation

$$W = \langle s_1, \dots, s_n \mid s_i^2 = 1, (s_i s_j)^{m_{ij}} = 1 \text{ for } i \neq j \rangle,$$

where  $m_{ij} = |s_i s_j| \in \{2, 3, \dots\} \cup \{\infty\}$ .

• Notice that  $s_i^2 = 1$  implies that each  $s_i$  can be thought of as a toggle.

# Coxeter Diagrams

• We can encode any Coxeter system as a **Coxeter diagram**.

# Coxeter Diagrams

• We can encode any Coxeter system as a **Coxeter diagram**.

#### Definition

A **Coxeter diagram** is a graph where edges may be weighted with positive integers or  $\infty$ .

- Each vertex corresponds to an involution  $s_i$ .
- For each  $i \neq j$ , let  $m_{ij} = \min_{k \geq 2} \{k \mid (s_i s_j)^k = 1\}$ .
- If  $m_{ij} \geq 3$ , connect  $s_i$  and  $s_j$  with an edge.
- If  $m_{ij} > 3$ , label this edge with  $m_{ij}$ .

# Coxeter Diagrams

• We can encode any Coxeter system as a **Coxeter diagram**.

#### Definition

A **Coxeter diagram** is a graph where edges may be weighted with positive integers or  $\infty$ .

- Each vertex corresponds to an involution  $s_i$ .
- For each  $i \neq j$ , let  $m_{ij} = \min_{k \geq 2} \{k \mid (s_i s_j)^k = 1\}$ .
- If  $m_{ij} \geq 3$ , connect  $s_i$  and  $s_j$  with an edge.
- If  $m_{ij} > 3$ , label this edge with  $m_{ij}$ .

#### Example



Figure: This is the Coxeter Diagram for the group  $A_5$ .

## Thanks for Listening! Merci de Votre Attention!



Image from Wikipedia

Be sure to attend Matthew Macauley's talk tomorrow at 15:30 for more cycle graph toggling!

#### Sources I



A. Brouwer and L. Schrijver.

On the period of an operator, defined on antichains.

Stichting Mathematisch Centrum. Zuivere Wiskunde, (ZW 24/74):1-13, 1974.



P. Cameron and D. Fon-Der-Flaass.

Orbits of antichains revisited.

European J. Combin., 16(6):545-554, 1995.



Matthew Cook.

Universality in elementary cellular automata.

Complex Systems, 15(1):1–40, 2004.



C. Defant.

Flexible toggles and symmetric invertible asynchronous elementary cellular automata.

Discrete Math., 341(9):2367-2379, 2018.



M. Develin, M. Macauley, and V. Reiner.

Toric partial orders.

Trans. Amer. Math. Soc., 368(4):2263-2287, 2016.



#### Sources II



H. Eriksson and K. Eriksson.

Conjugacy of Coxeter elements.

Electron. J. Combin., 16(2):#R4, 2009.



D. Einstein, M. Farber, E. Gunawan, M. Joseph, M. Macauley, J. Propp, and

S. Rubinstein-Salzedo.

Noncrossing partitions, toggles, and homomesies.

Electron. J. Combin., 23(3), 2016.



D. Einstein and J. Propp.

 $Combinatorial,\ piecewise-linear,\ and\ birational\ homomesy\ for\ products\ of\ two\ chains.$ 

ArXiV 1310.5294v3. 2018.



Eric Goles, Marco Montalva-Medel, Henning Mortveit, and Salvador Ramirez-Flandes. Block invariance in elementary cellular automata.

J. Cell. Autom. 10:119–135. 2015.



D. Grinberg and T. Roby.

Iterative properties of birational rowmotion.

ArXiV 1402.6178v6. 2014.



#### Sources III



S. Haddadan.

Some instances of homomesy among ideals of posets.

ArXiV 1410.4819v3, 2016.



M. Joseph and T. Roby.

Toggling independent sets of a path graph.

Electron J. Combin., 25(1):1-18, 2018.



M. Macauley and H.S. Mortveit.

Cycle equivalence of graph dynamical systems.

Nonlinearity, 22:421-436, 2009.



M. Macauley and H. Mortveit.

Posets from admissible Coxeter sequences.

Electron. J. Combin., 18(1):#R197, 2011.



M. Macauley, J. McCammond, and H.S. Mortveit.

Order independence in asynchronous cellular automata.

J. Cell. Autom., 3(1):37-56, 2008.

#### Sources IV



M. Macauley, J. McCammond, and H. Mortveit.

Dynamics groups of asynchronous cellular automata.

J. Algebraic Combin., 33(1):11-35, 2011.



Y. Numata and Y. Yamanouchi.

On the action of the toggle group of the Dynkin diagram of type A.

ArXiV 2103.16217, 2021.



T. K. Petersen.

Eulerian Numbers.

Springer, New York, 2015.



J. Propp and T. Roby.

Homomesy in products of two chains.

Electron. J. Combin., 22(3), 2015.



O. Pretzel.

On reorienting graphs by pushing down maximal vertices.

Order, 3(2):135-153, 1986.

#### Sources V



T. Roby.

Dynamical algebraic combinatorics and the homomesy phenomenon.

In Recent Trends in Combinatorics, pages 619-652. Springer, 2016.



V. Salo.

Universal gates with wires in a row.

ArXiV 1809.08050, 2018.



B. Schönfisch and A. de Roos.

Synchronous and asynchronous updating in cellular automata.

BioSystems, 51(3):123-143, 1999.



J. Striker.

The toggle group, homomesy, and the Razumov-Stroganov correspondence.

Electron. J. Combin., 22(2):P2-57, 2015.

Also available at ArXiV 1503.08898v2.



J. Striker.

Dynamical algebraic combinatorics: promotion, rowmotion, and resonance.

Notices Amer. Math. Soc., 64(6), 2017.



#### Sources VI



J. Striker and N. Williams.

Promotion and rowmotion.

European J. Combin., 33:1919-1942, 2012.



S. Wolfram.

Theory and applications of cellular automata. 1986.