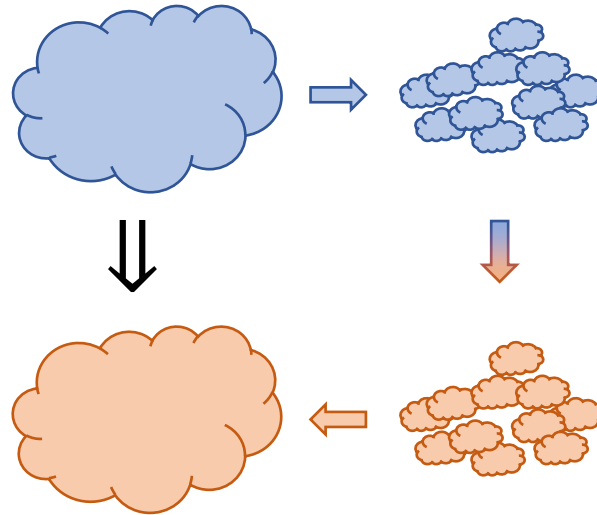


Cellular Automata and Kan Extensions

Alexandre Fernandez, Luidnel Maignan, Antoine Spicher

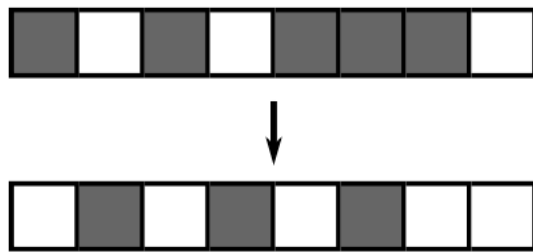
Global transformations

- Synchronous & local & deterministic systems

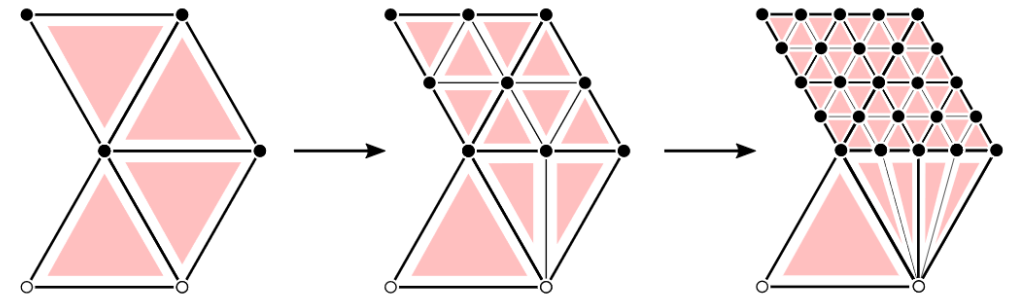


Global transformations

- Synchronous & local & deterministic systems
- Over **variety of structures**
 - groups, words, trees, graphs, ...

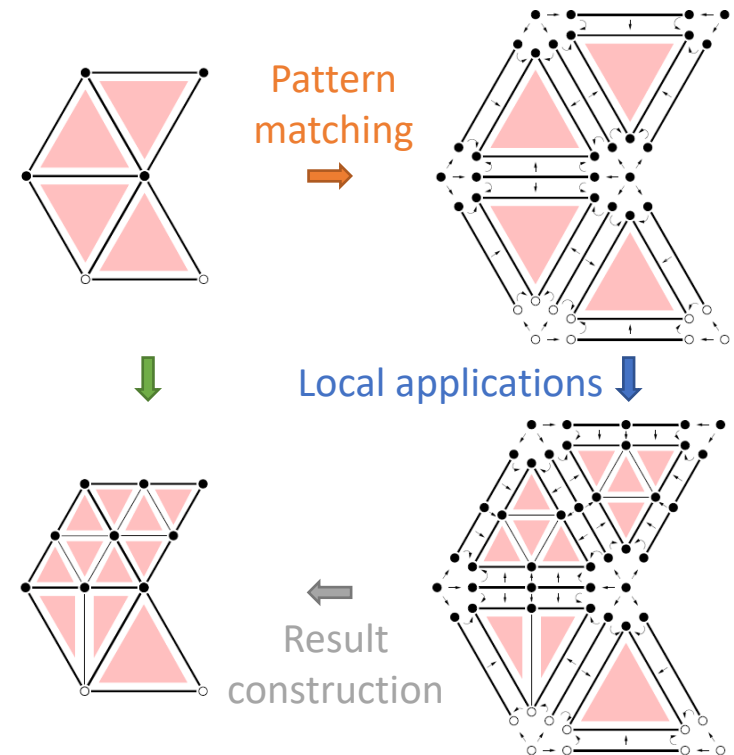


abaababa
↓
abaababaabaab
↓
abaababaabaababaababa



Global transformations

- Synchronous & local & deterministic systems
- Over variety of structures
 - groups, words, trees, graphs, ...
- Category theory



$$T(\mathcal{K}) = \text{Colim}(\mathbf{P} \circ \text{Proj}_{\mathbf{L}/\mathcal{K}})$$

Local vs Global relation

- In cellular automata :
 - Local behavior extended to global
 - Computational description
 - Continuous & uniform & shift equiv global behavior
 - Topological description

Local vs Global relation

- In cellular automata :
 - Local behavior extended to global
 - Computational description
 - Continuous & uniform & shift equiv global behavior
 - Topological description
 - Kan Extensions !
 - Categorical description

Outline

- Two ways to extend with an example
- The poset of sub-configurations
- The two extensions are kan extensions

Outline

- Two ways to extend with an example
- The poset of sub-configurations
- The two extensions are kan extensions

Traffic rule automaton

- Represents **traffic**, bi-infinite **road**

...



...

Traffic rule automaton

- Represents traffic, bi-infinite road
- Cars going to the **right**



Traffic rule automaton

- Represents traffic, bi-infinite road
- Cars going to the right



- A car goes right **when no car in front**

t

Traffic rule automaton

- Represents traffic, bi-infinite road
- Cars going to the right



- A car goes right when no car in front



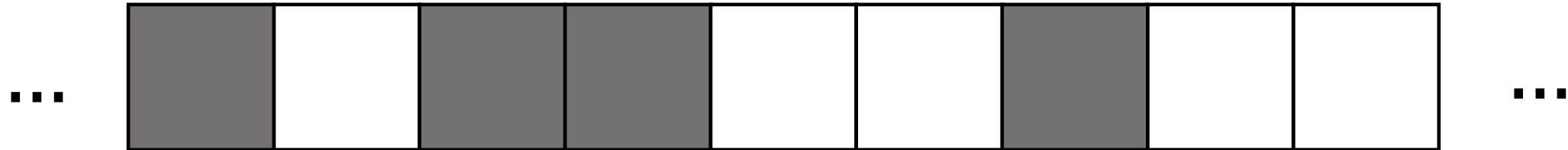
t



t + 1

Traffic rule automaton

- Represents traffic, bi-infinite road
- Cars going to the right



- A car goes right when no car in front



t



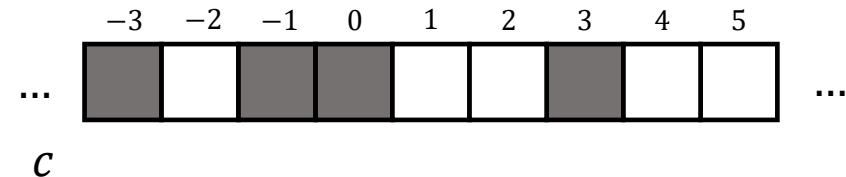
t + 1

Traffic rule automaton

- Q : Finite set of states
- G : Group (space)
- $c \in Q^G$: configurations
- $N \subseteq G$: finite neighborhood

$$Q = \{\square, \blacksquare\}$$

$$G = (\mathbb{Z}, +)$$



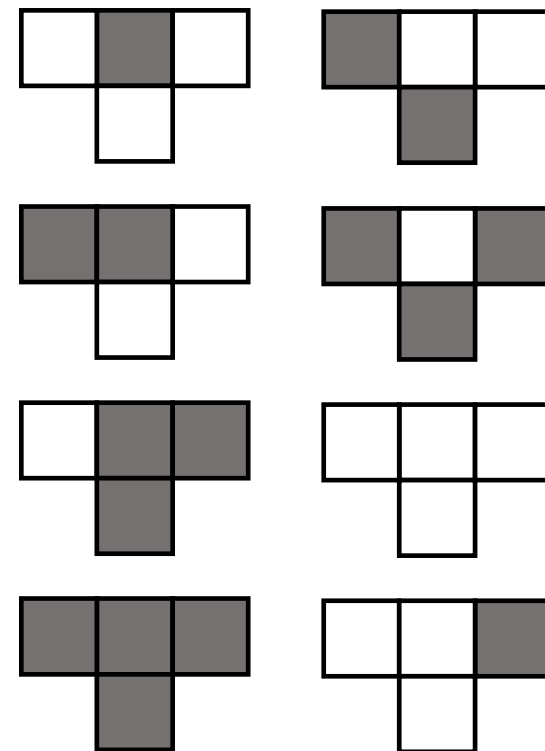
$$N = \{-1, 0, 1\}$$

Space time diagram



- Evolution for known part ?

Evolution Rules

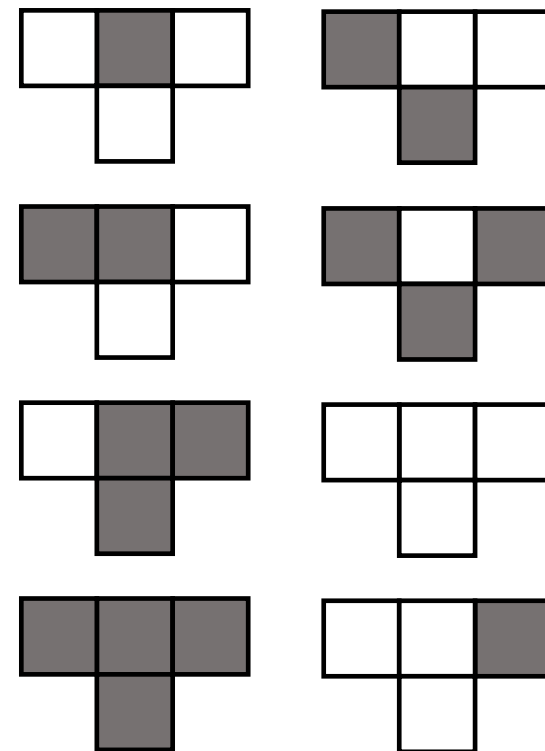


Space time diagram



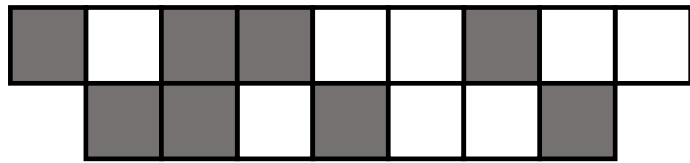
← State

Evolution Rules



- Evolution for **sub-configurations**

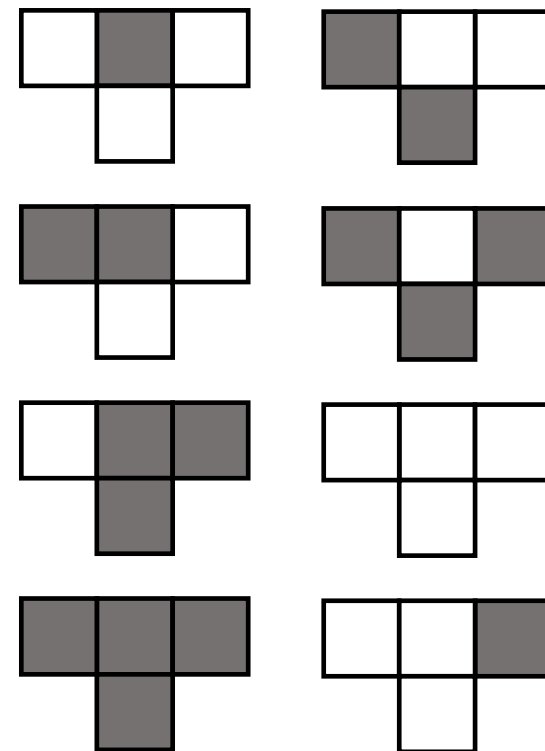
Space time diagram



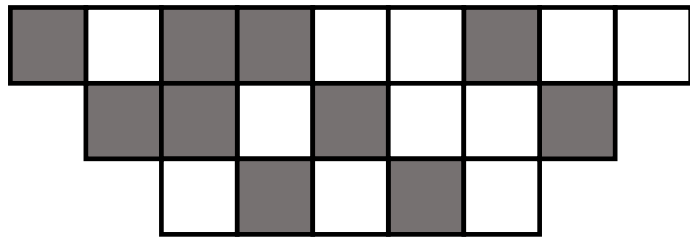
← State

- Evolution for **sub-configurations**

Evolution Rules



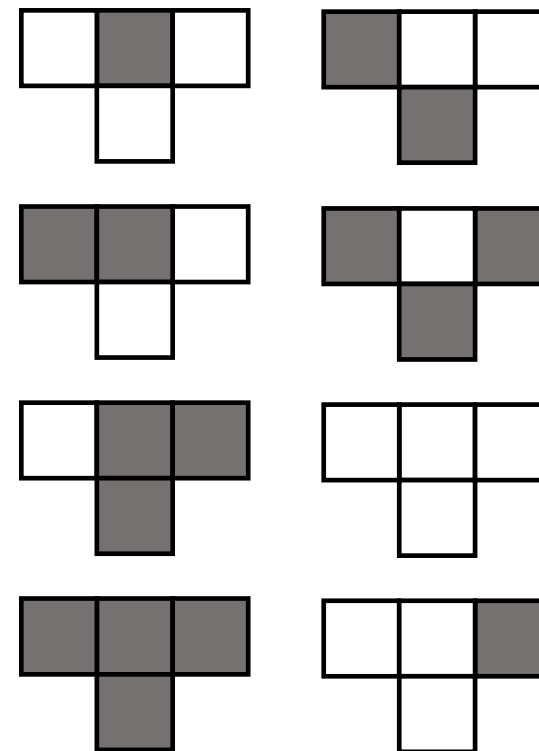
Space time diagram



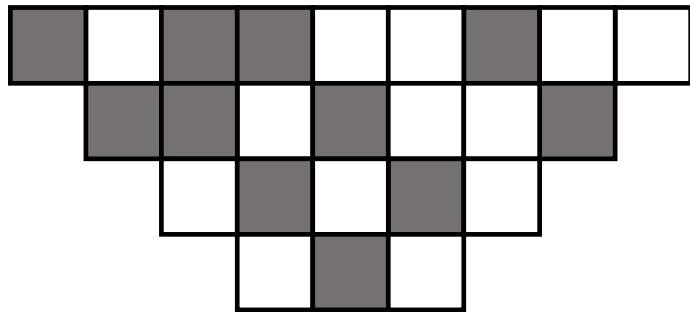
← State

- Evolution for **sub-configurations**

Evolution Rules



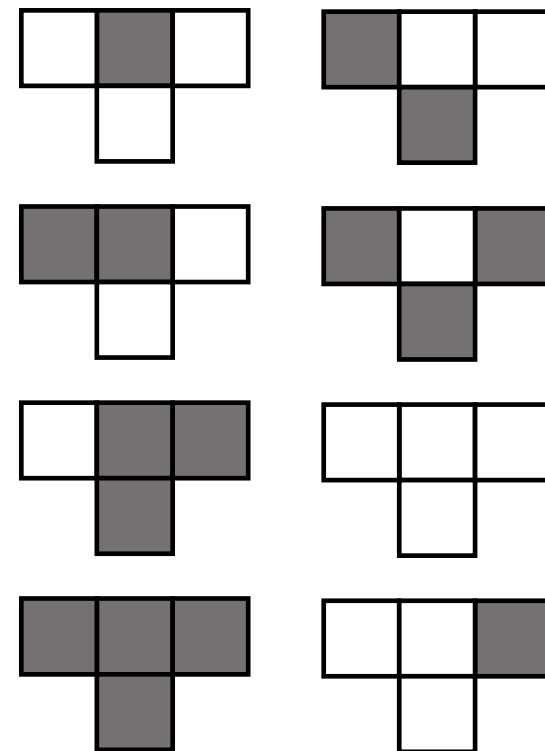
Space time diagram



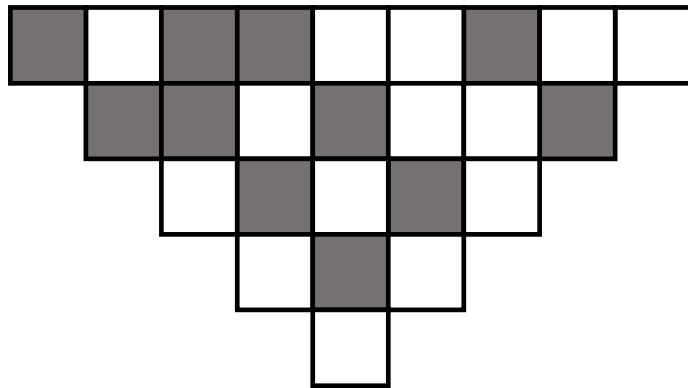
← State

- Evolution for **sub-configurations**

Evolution Rules



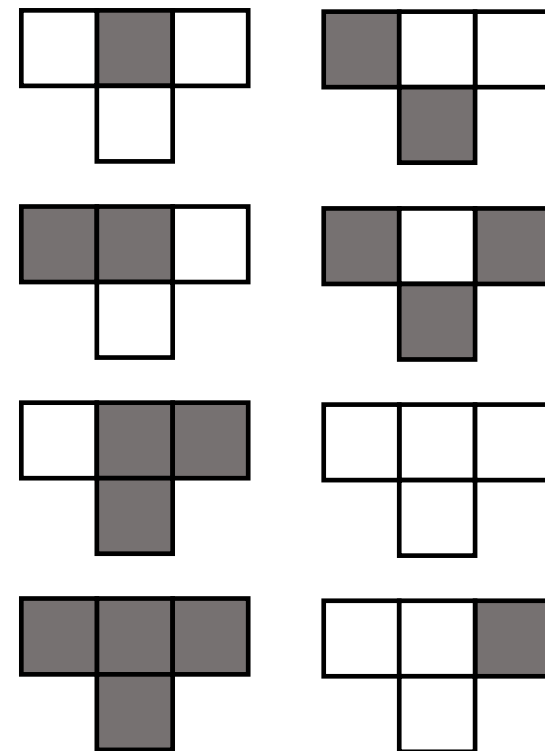
Space time diagram



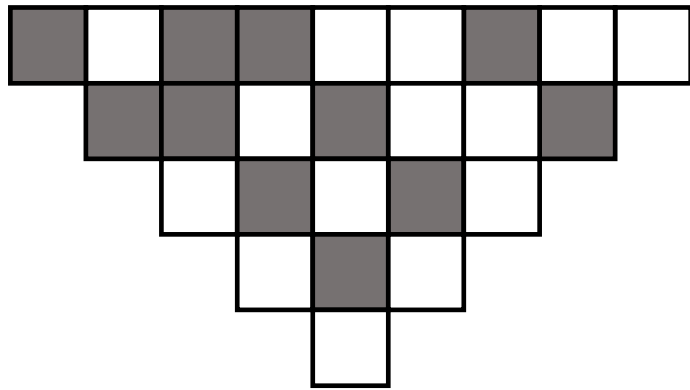
←State

- Evolution for **sub-configurations**
- Rules **extended** to sub-configurations !

Evolution Rules

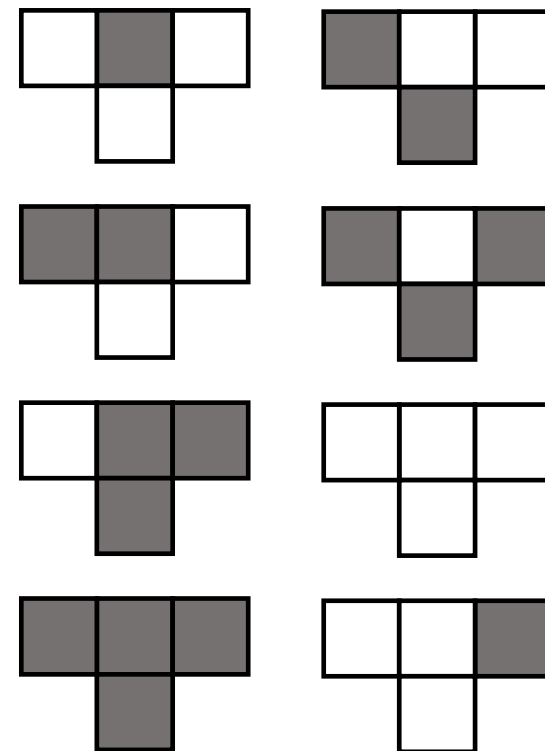


Space time diagram

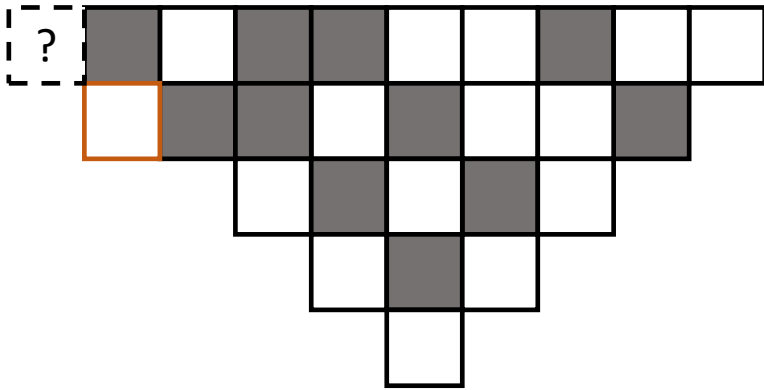


- We can deduce more !

Evolution Rules

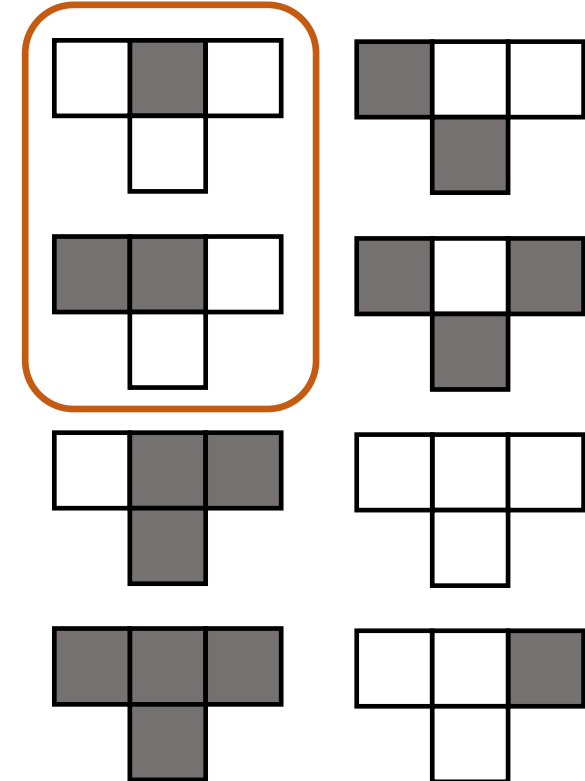


Space time diagram

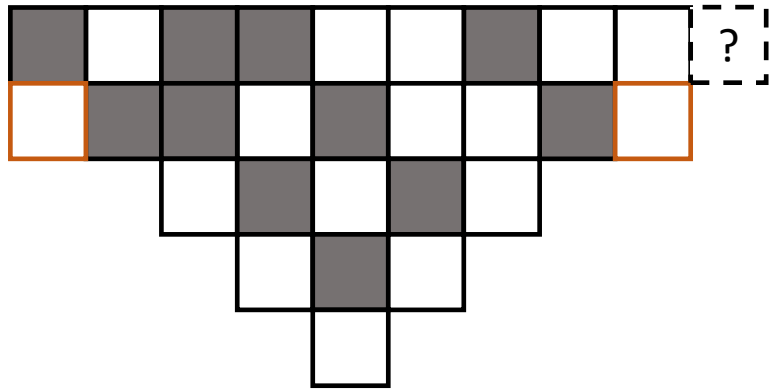


- We can deduce more !

Evolution Rules

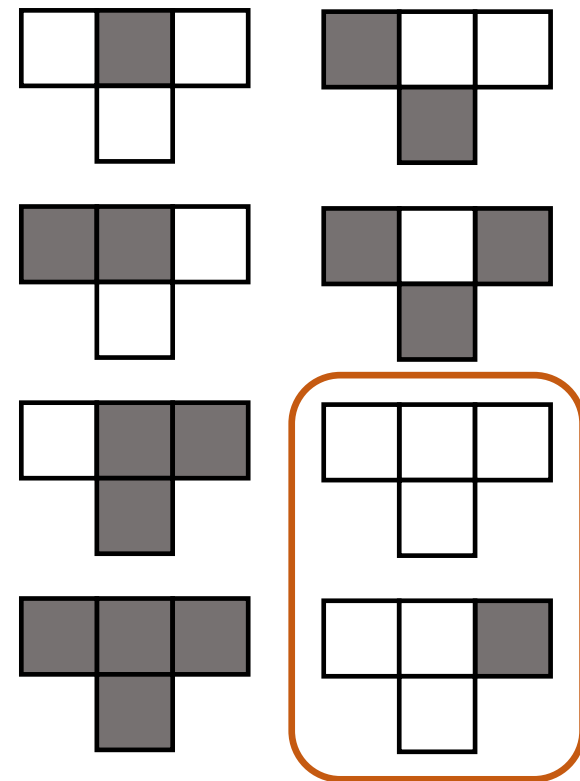


Space time diagram

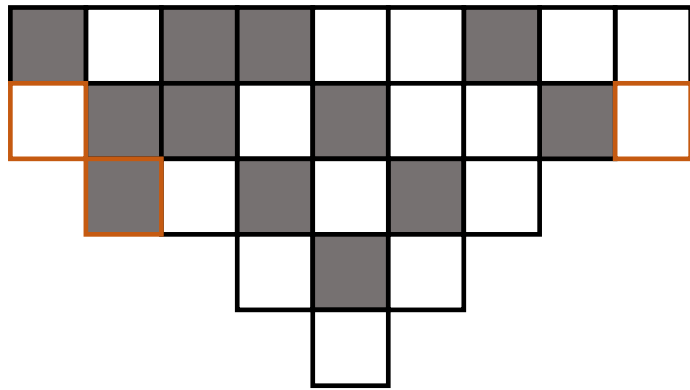


- We can deduce more !

Evolution Rules

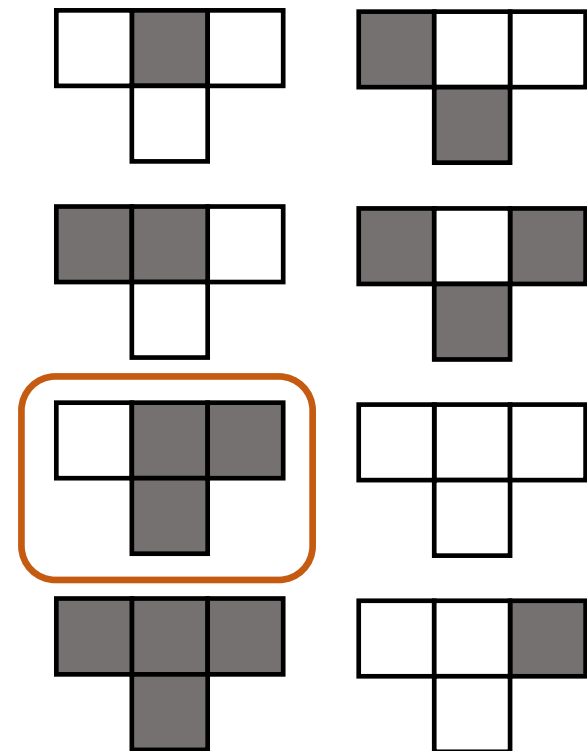


Space time diagram

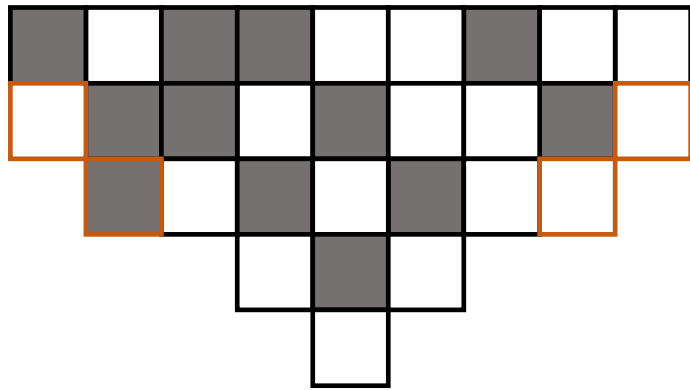


- We can deduce more !

Evolution Rules

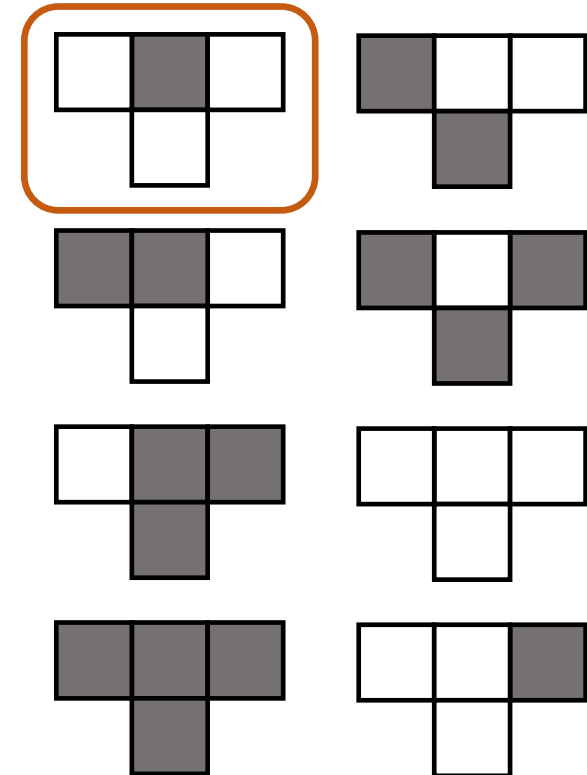


Space time diagram

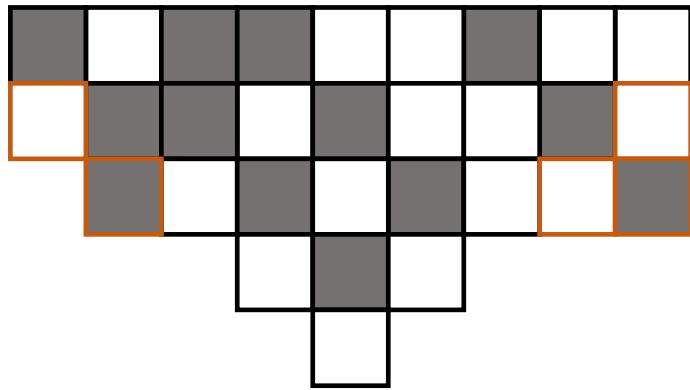


- We can deduce more !

Evolution Rules

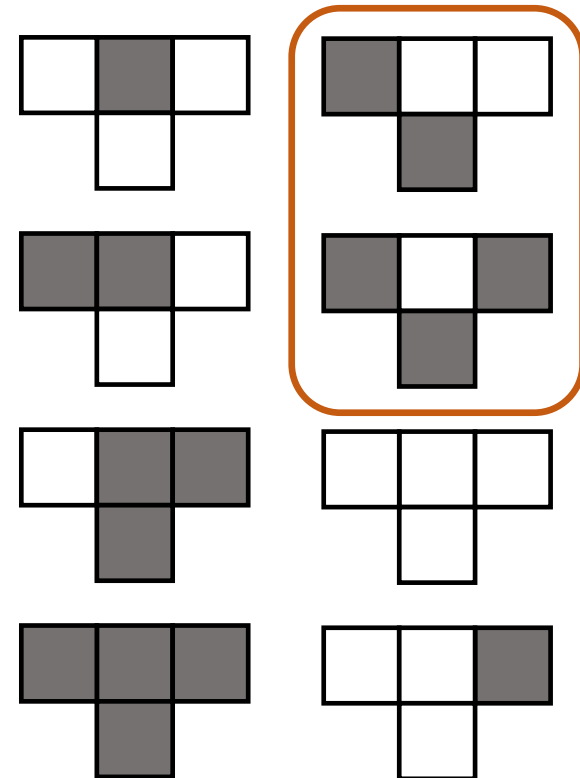


Space time diagram

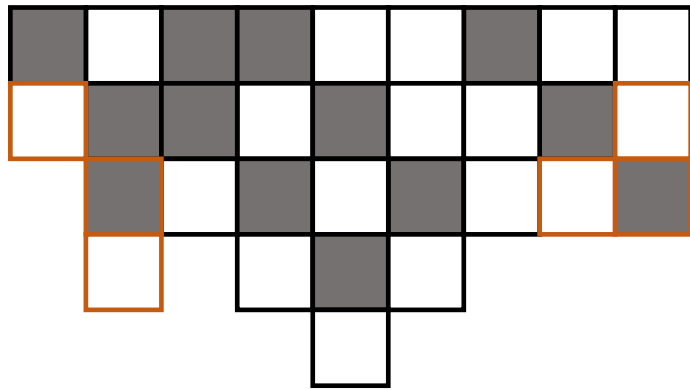


- We can deduce more !

Evolution Rules

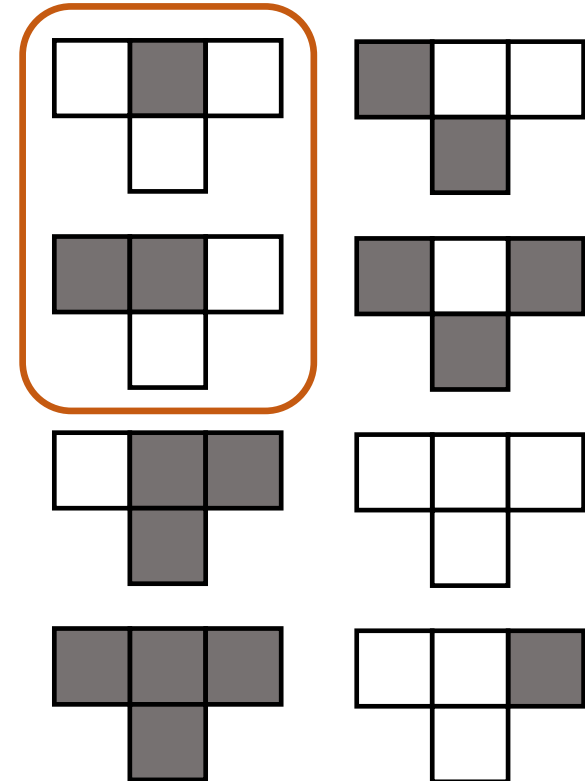


Space time diagram

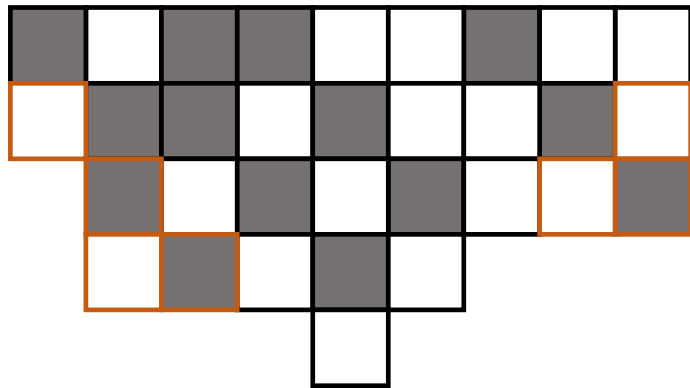


- We can deduce more !

Evolution Rules

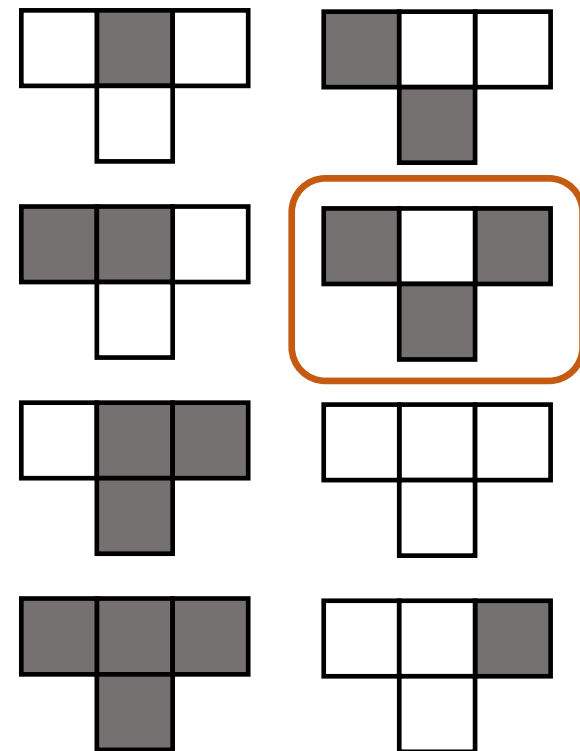


Space time diagram

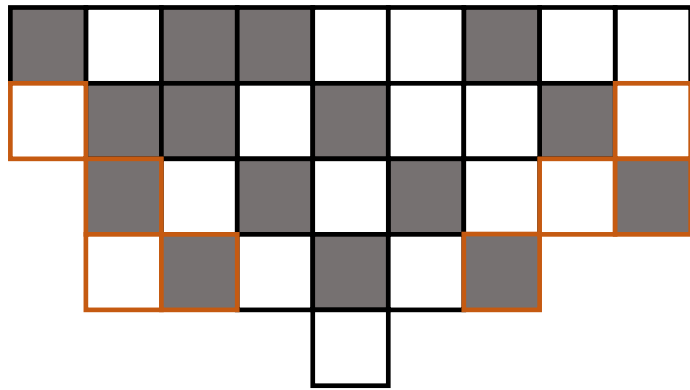


- We can deduce more !

Evolution Rules

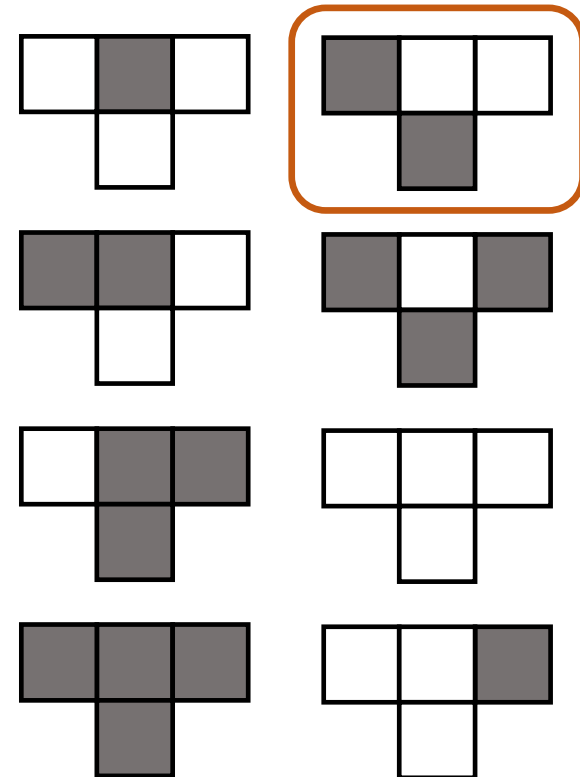


Space time diagram

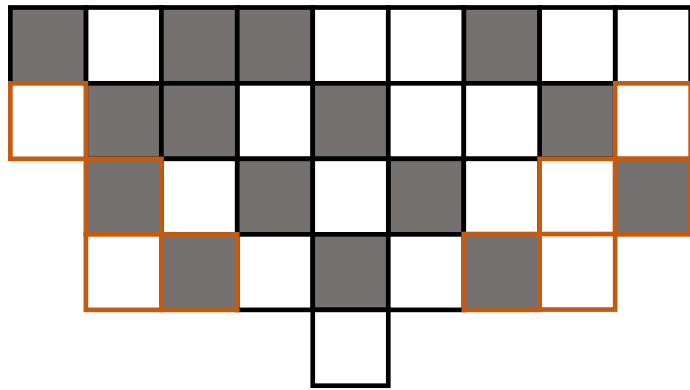


- We can deduce more !

Evolution Rules

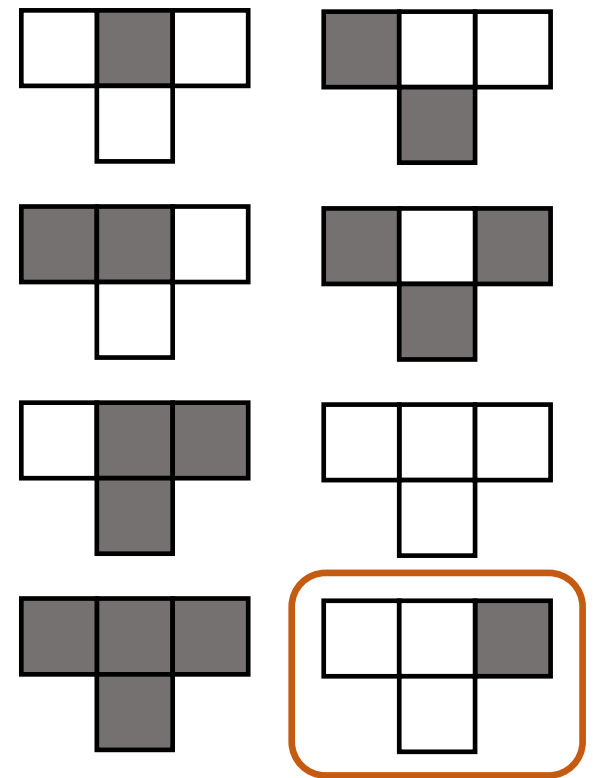


Space time diagram

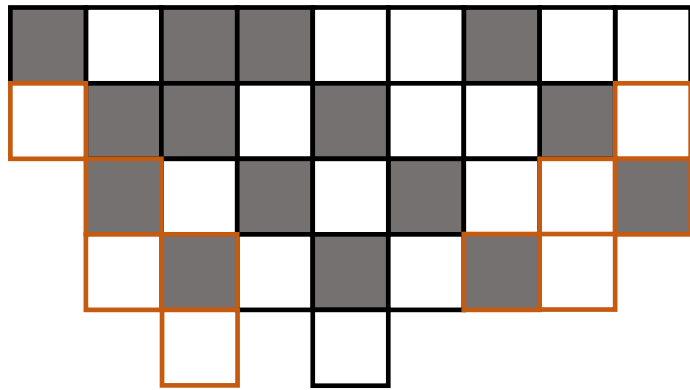


- We can deduce more !

Evolution Rules

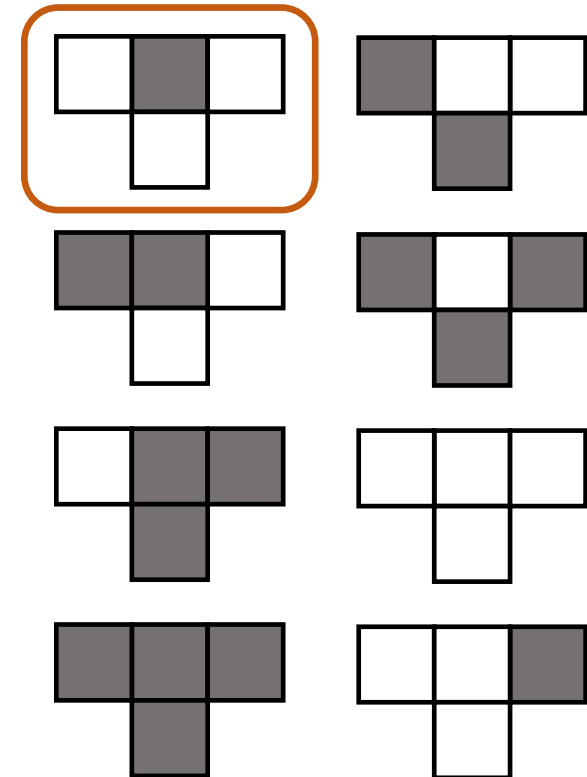


Space time diagram

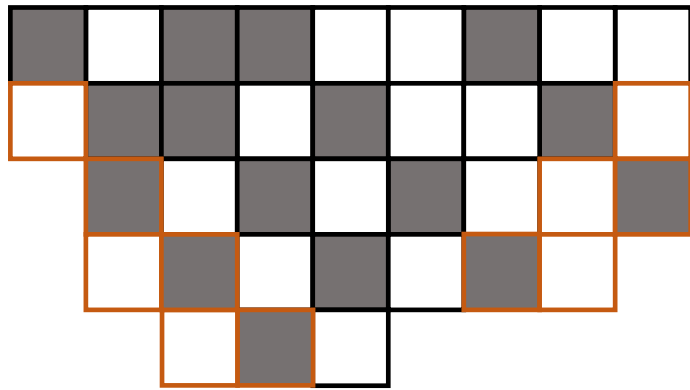


- We can deduce more !

Evolution Rules

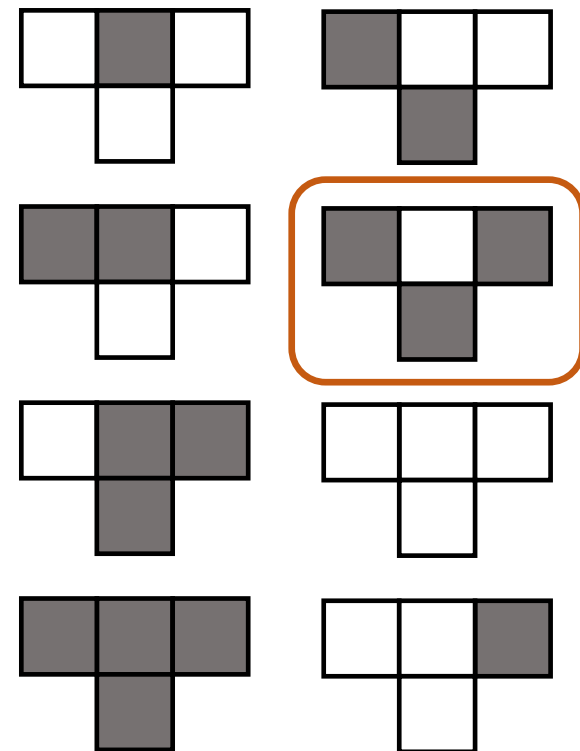


Space time diagram

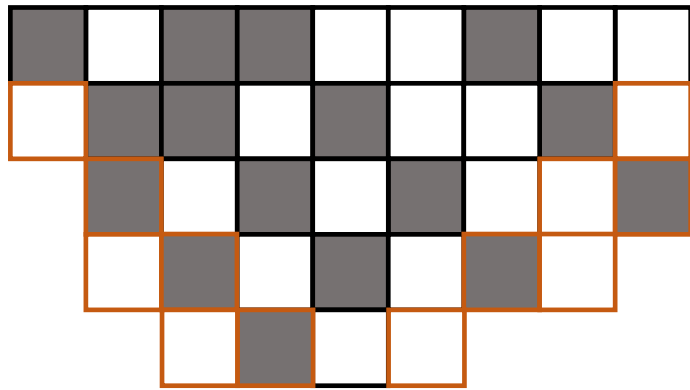


- We can deduce more !

Evolution Rules

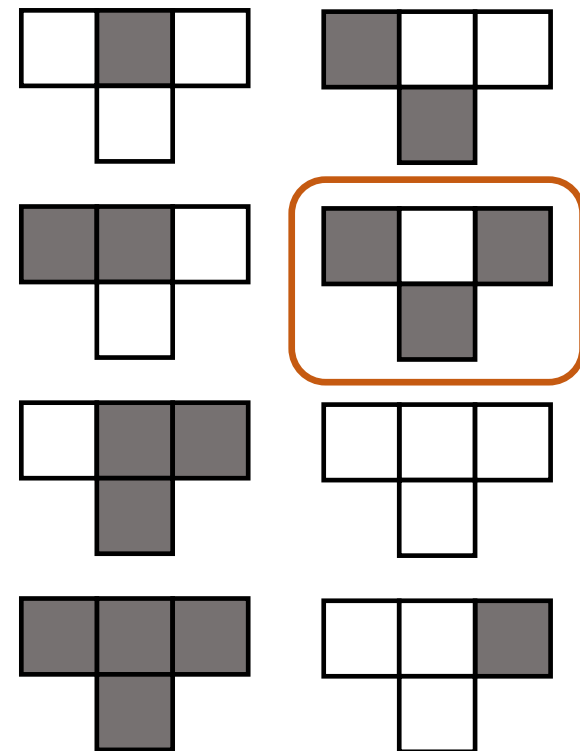


Space time diagram

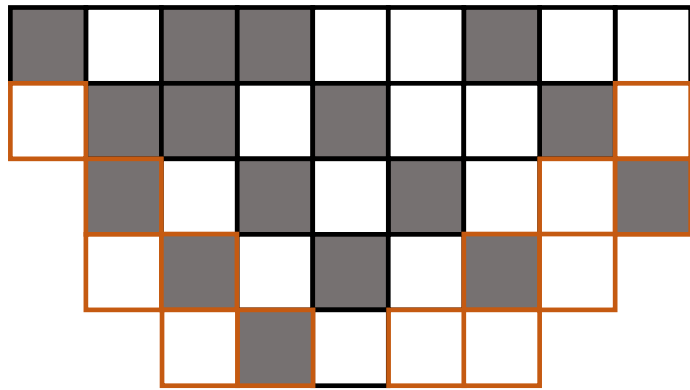


- We can deduce more !

Evolution Rules

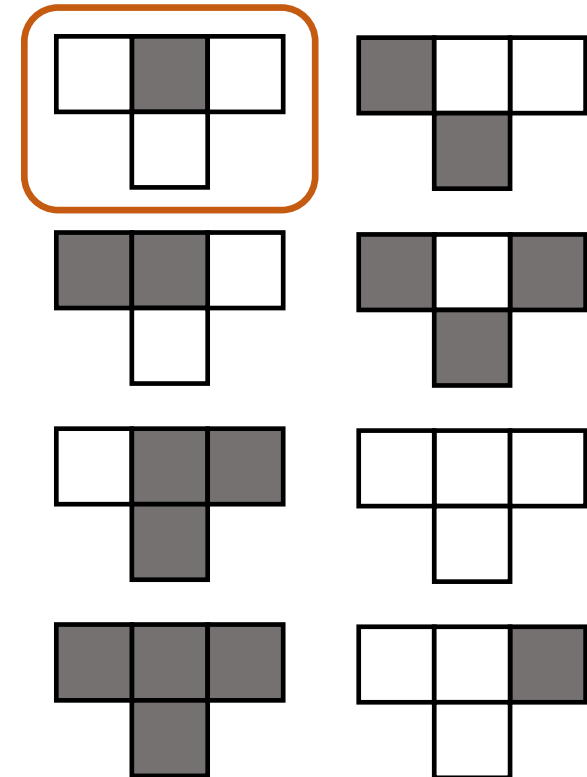


Space time diagram

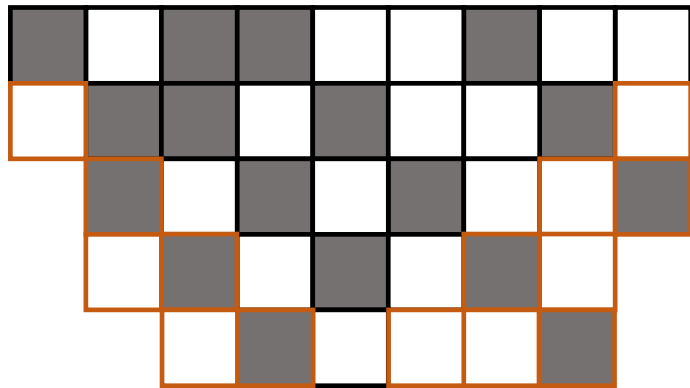


- We can deduce more !

Evolution Rules

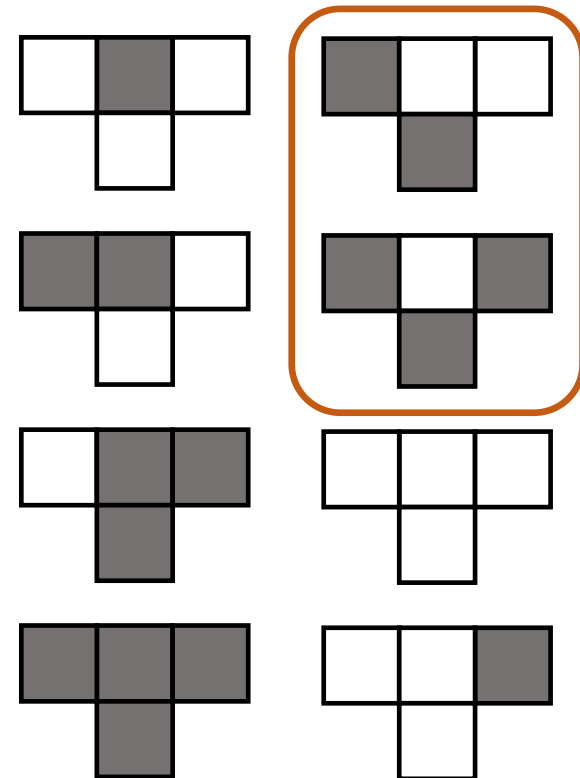


Space time diagram

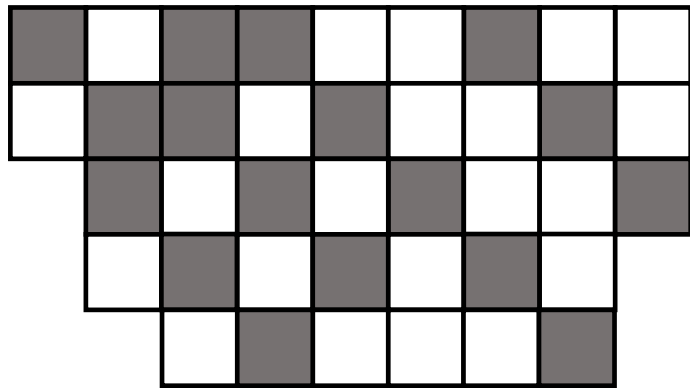


- We can deduce more !

Evolution Rules

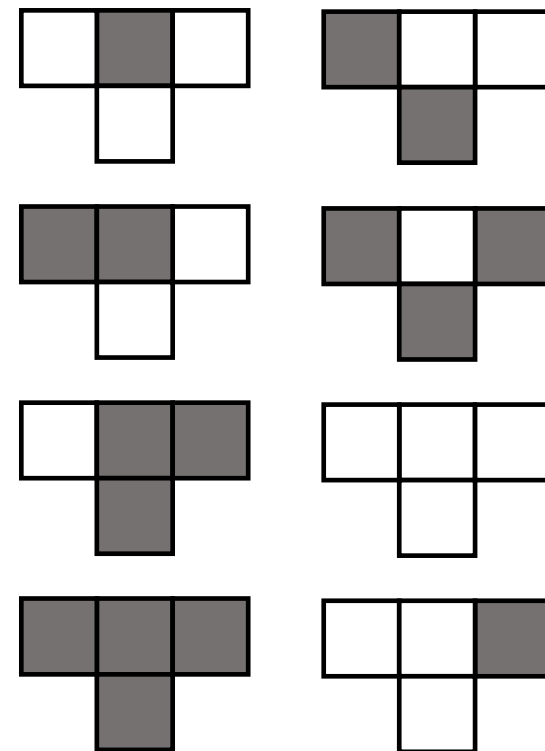


Space time diagram



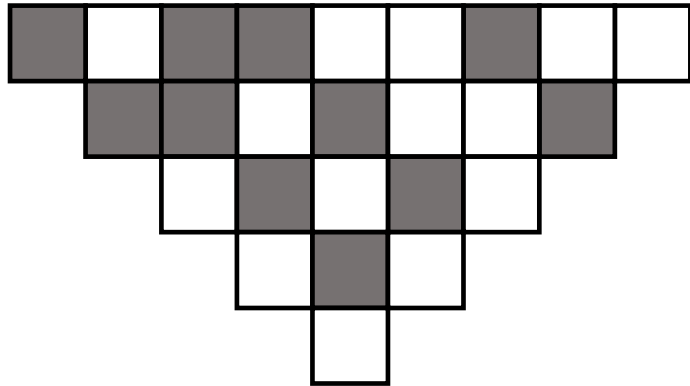
- An other extension to sub-configurations

Evolution Rules

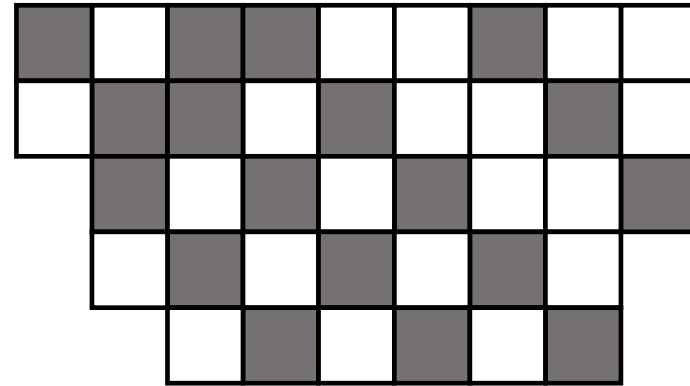


Two ways of extending

- Coarse transition function $\underline{\Delta}$

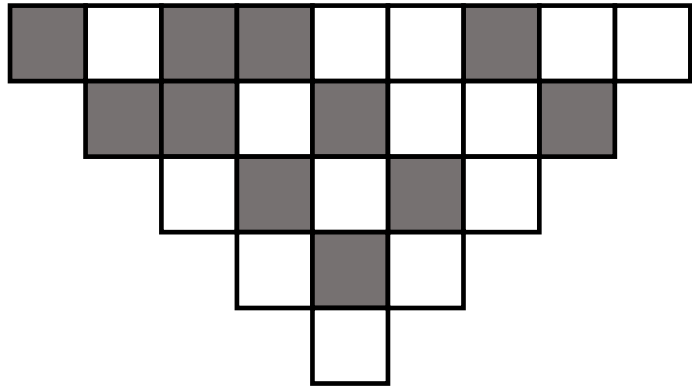


- Fine transition function $\overline{\Delta}$

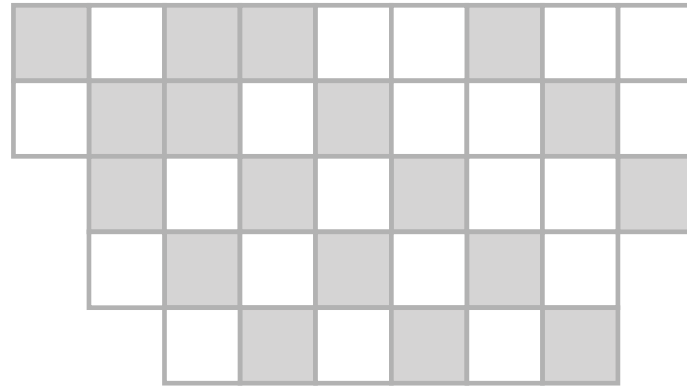


Two ways of extending

- Coarse transition function $\underline{\Delta}$

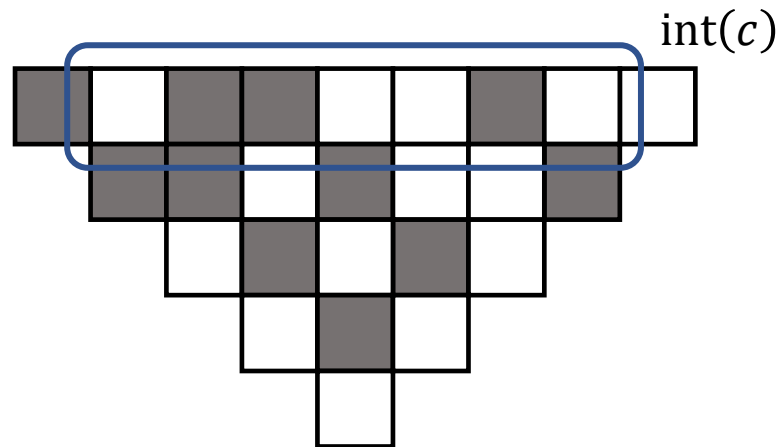


- Fine transition function $\overline{\Delta}$



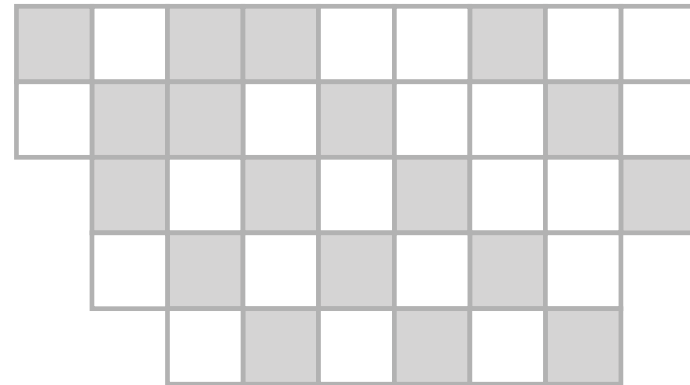
Two ways of extending

- Coarse transition function $\underline{\Delta}$
 - Deduce with full neighborhood



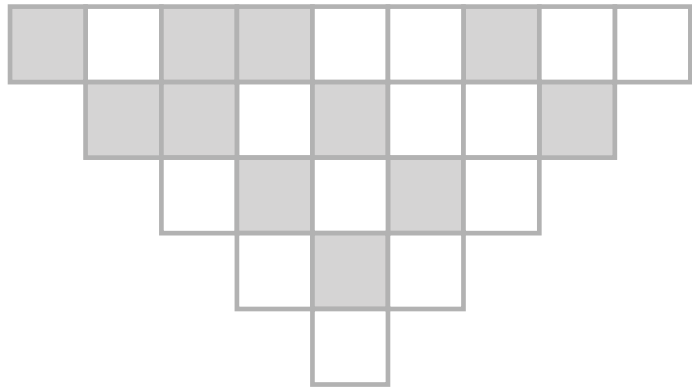
- Minimal extension

- Fine transition function $\overline{\Delta}$



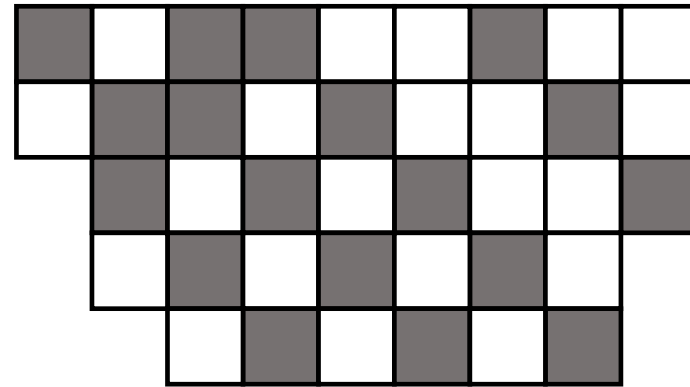
Two ways of extending

- Coarse transition function $\underline{\Delta}$
 - Deduce with full neighborhood



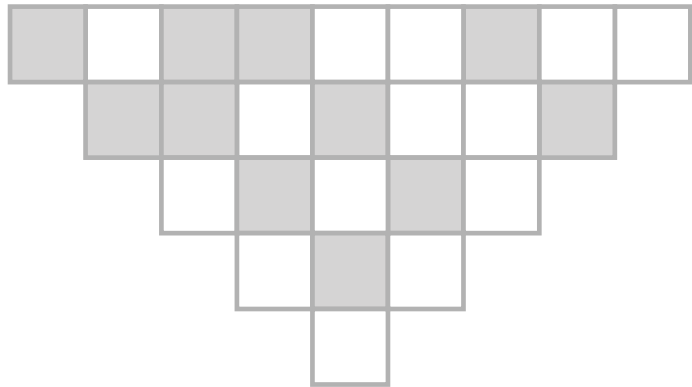
- Minimal extension

- Fine transition function $\overline{\Delta}$



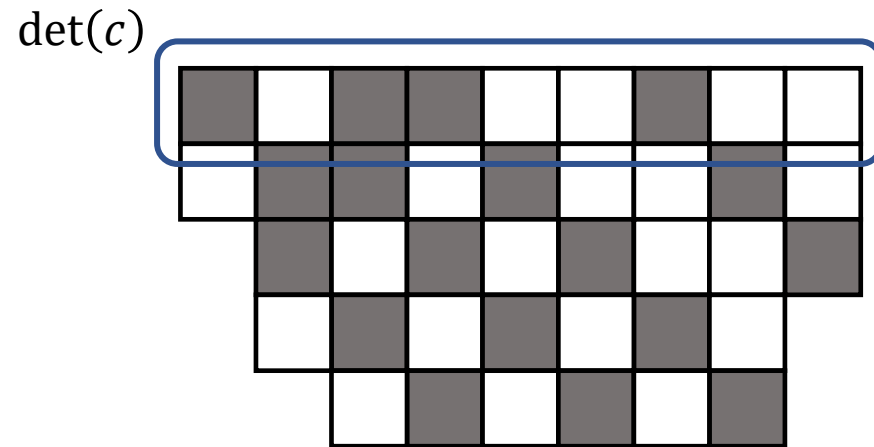
Two ways of extending

- Coarse transition function $\underline{\Delta}$
 - Deduce with full neighborhood



- Minimal extension

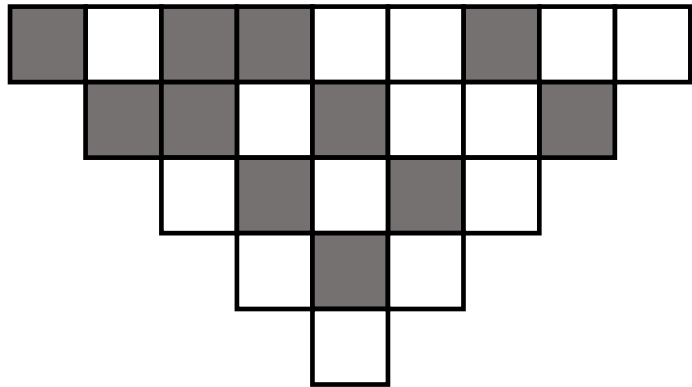
- Fine transition function $\overline{\Delta}$
 - Deduce without neighborhood



- Maximal extension

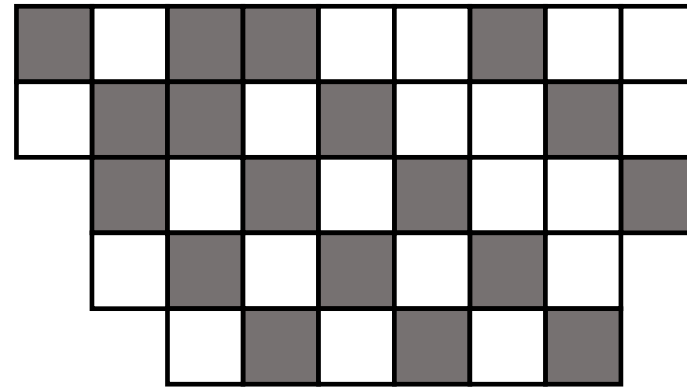
Two ways of extending

- Coarse transition function $\underline{\Delta}$
 - Deduce with full neighborhood



- Is a left Kan extension !

- Fine transition function $\overline{\Delta}$
 - Deduce without neighborhood



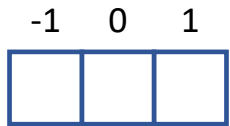
- Is a right Kan extension !

Outline

- Two ways to extend with an example
- The poset of sub-configurations
- The two extensions are kan extensions

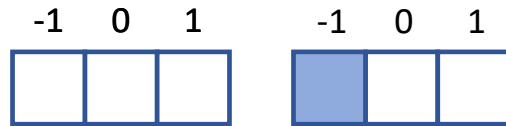
Local configurations

- Local configuration maps $l: N \rightarrow Q$



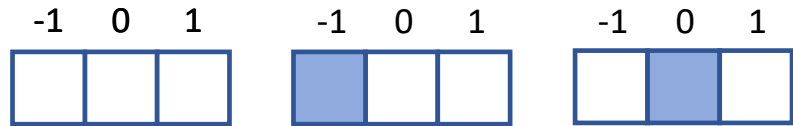
Local configurations

- Local configuration maps $l: N \rightarrow Q$



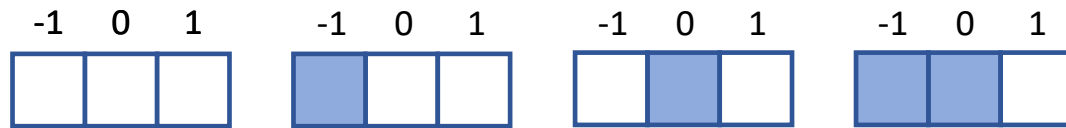
Local configurations

- Local configuration maps $l: N \rightarrow Q$



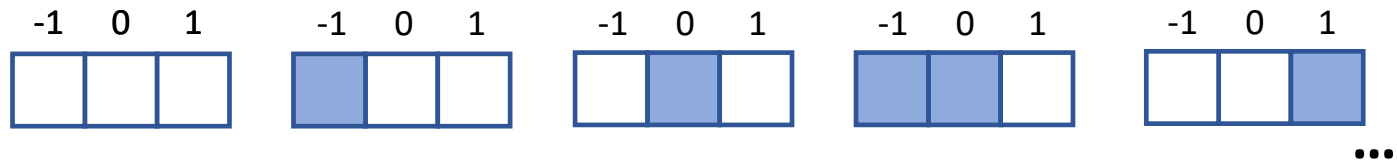
Local configurations

- Local configuration maps $l: N \rightarrow Q$



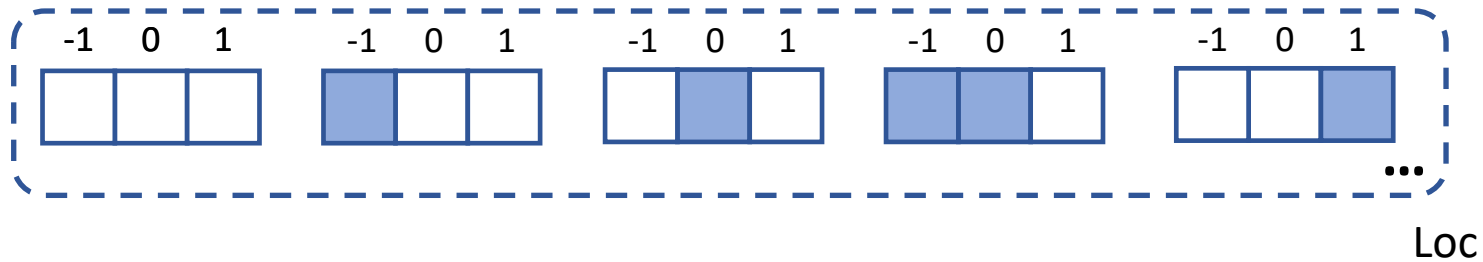
Local configurations

- Local configuration maps $l: N \rightarrow Q$



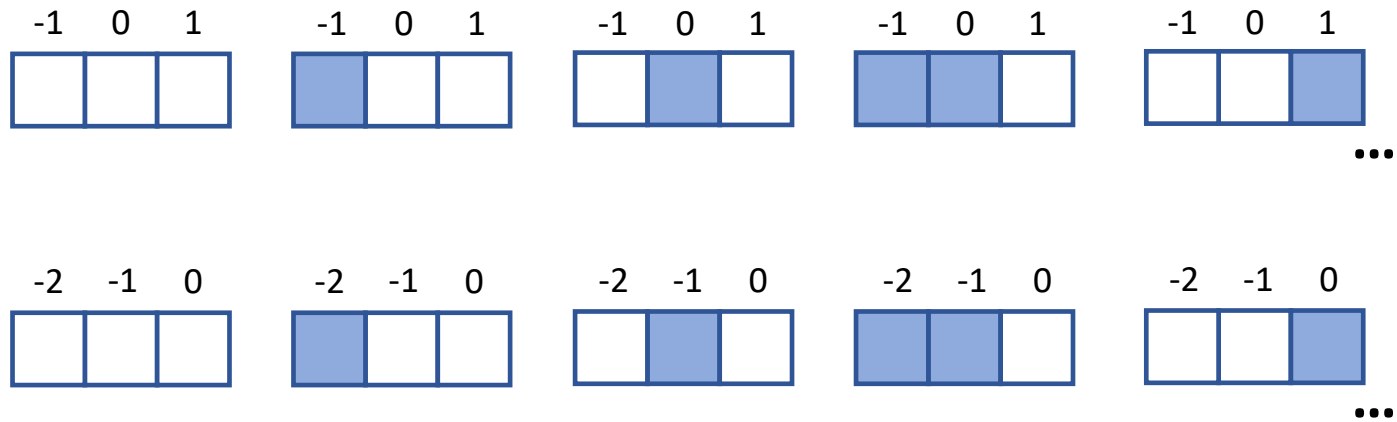
Set of local configurations

- Set of local configuration: $\text{Loc} := Q^N$



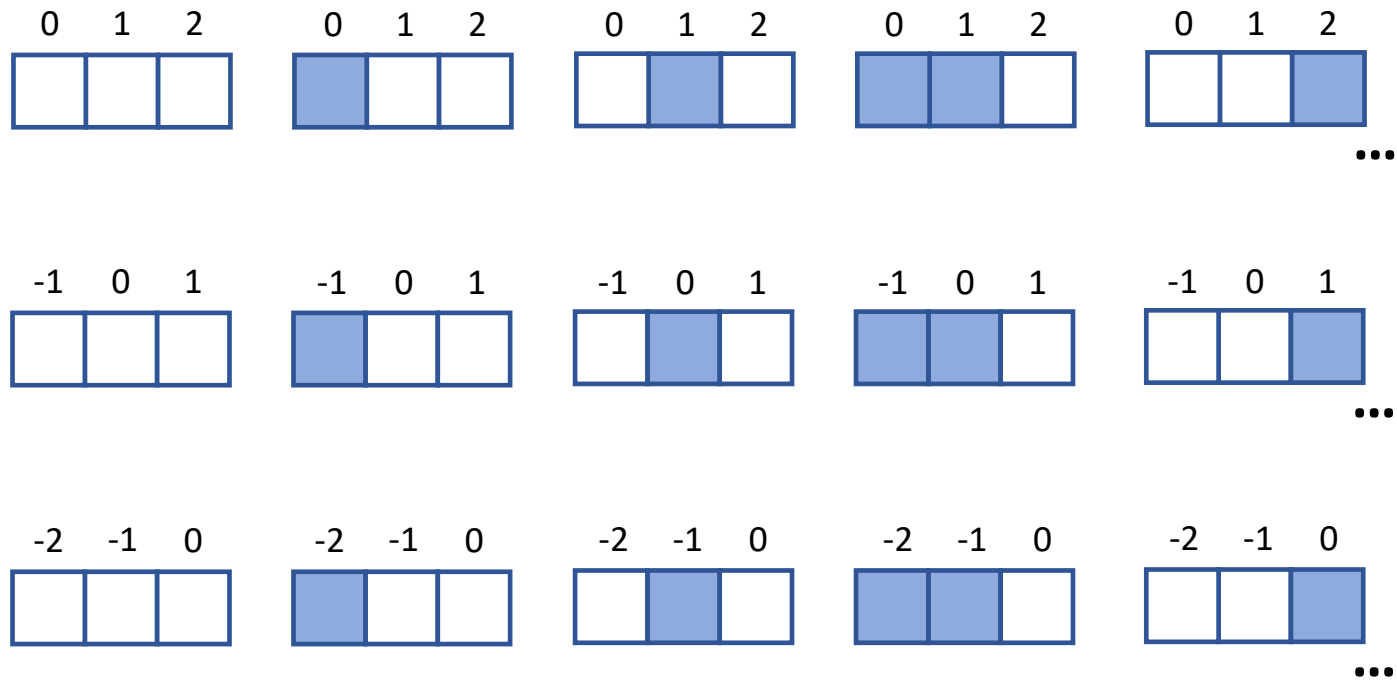
Shifted local configurations

- Shifted local configuration, maps $l: p + N \rightarrow Q$



Shifted local configurations

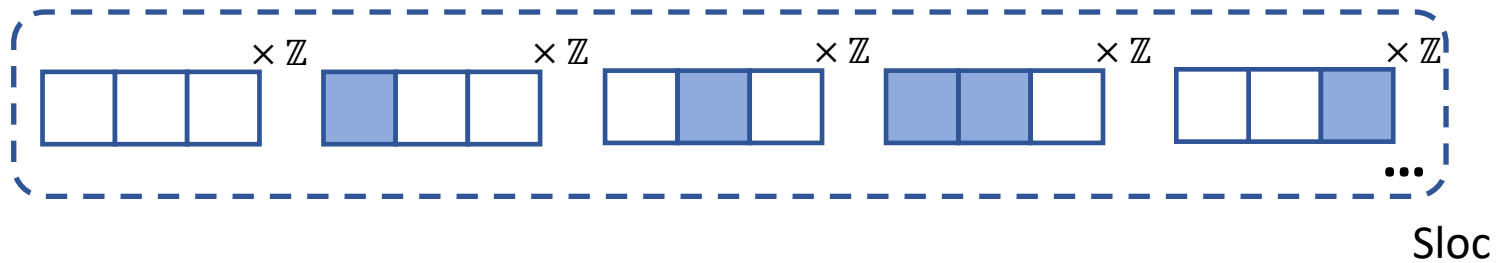
- Shifted local configuration, maps $l: p + N \rightarrow Q$



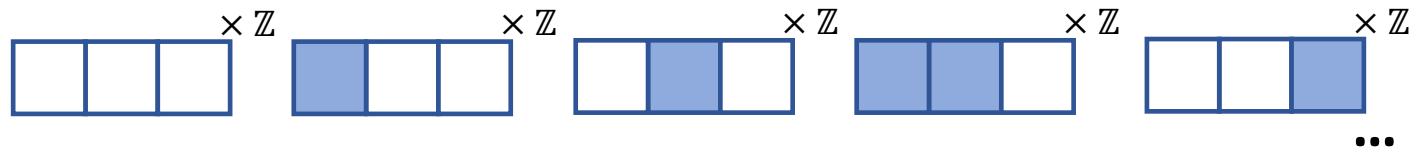
Set of shifted local configurations

- Shifted local configurations :

$$Sloc := \bigcup_{p \in \mathbb{Z}} p + N \rightarrow Q$$

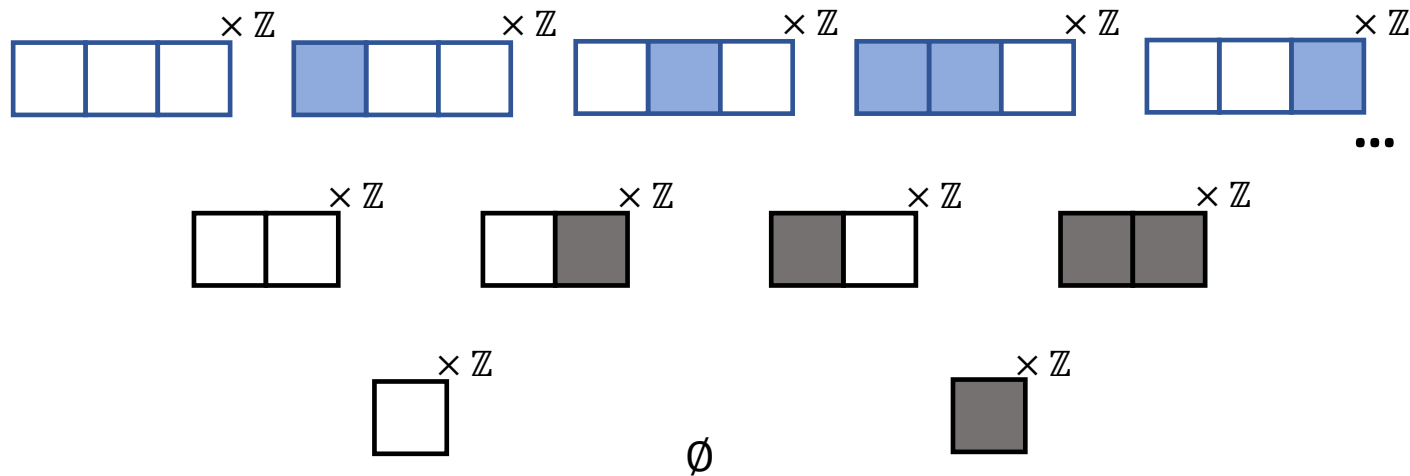


Set of sub-configurations



- Shifted local configurations

Set of sub-configurations



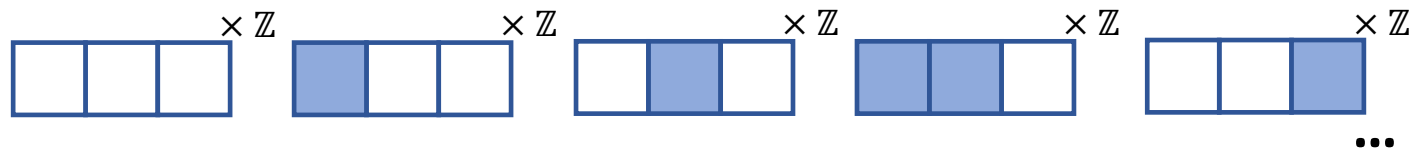
- Shifted local configurations

- Shifted sub-local configurations

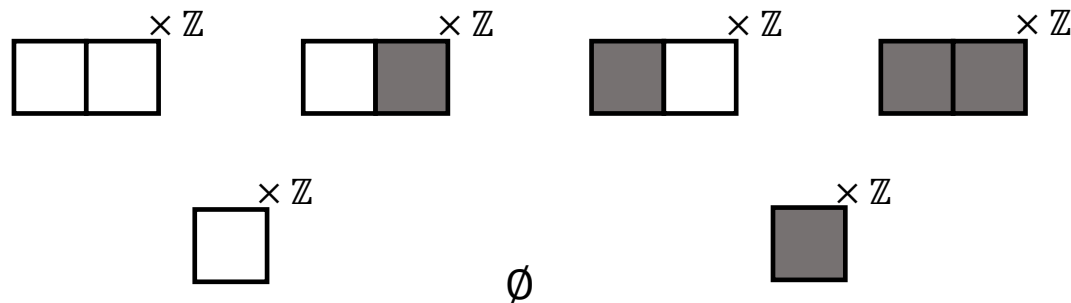
Set of sub-configurations



- Configurations

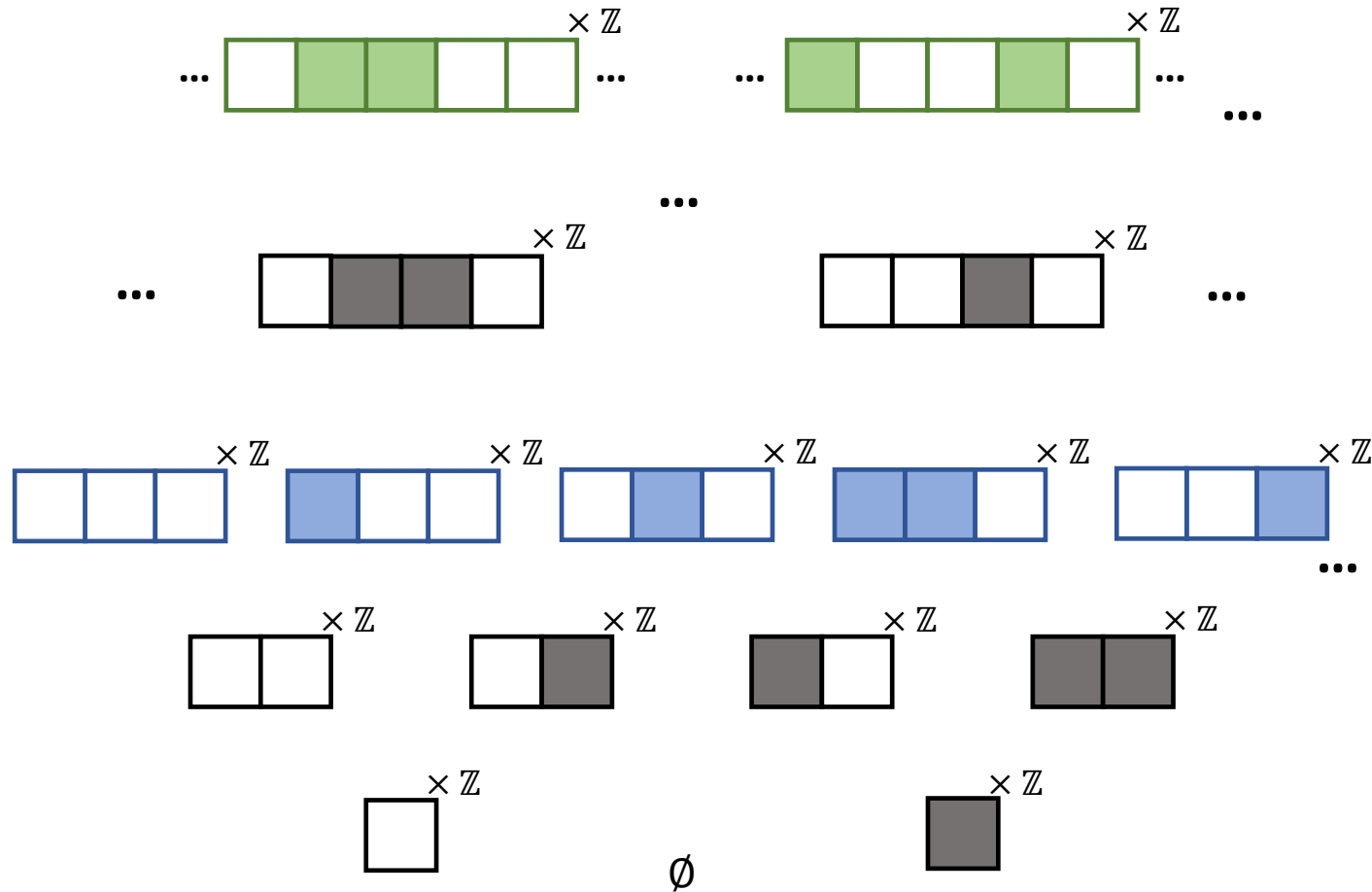


- Shifted local configurations



- Shifted sub-local configurations

Set of sub-configurations



- Configurations

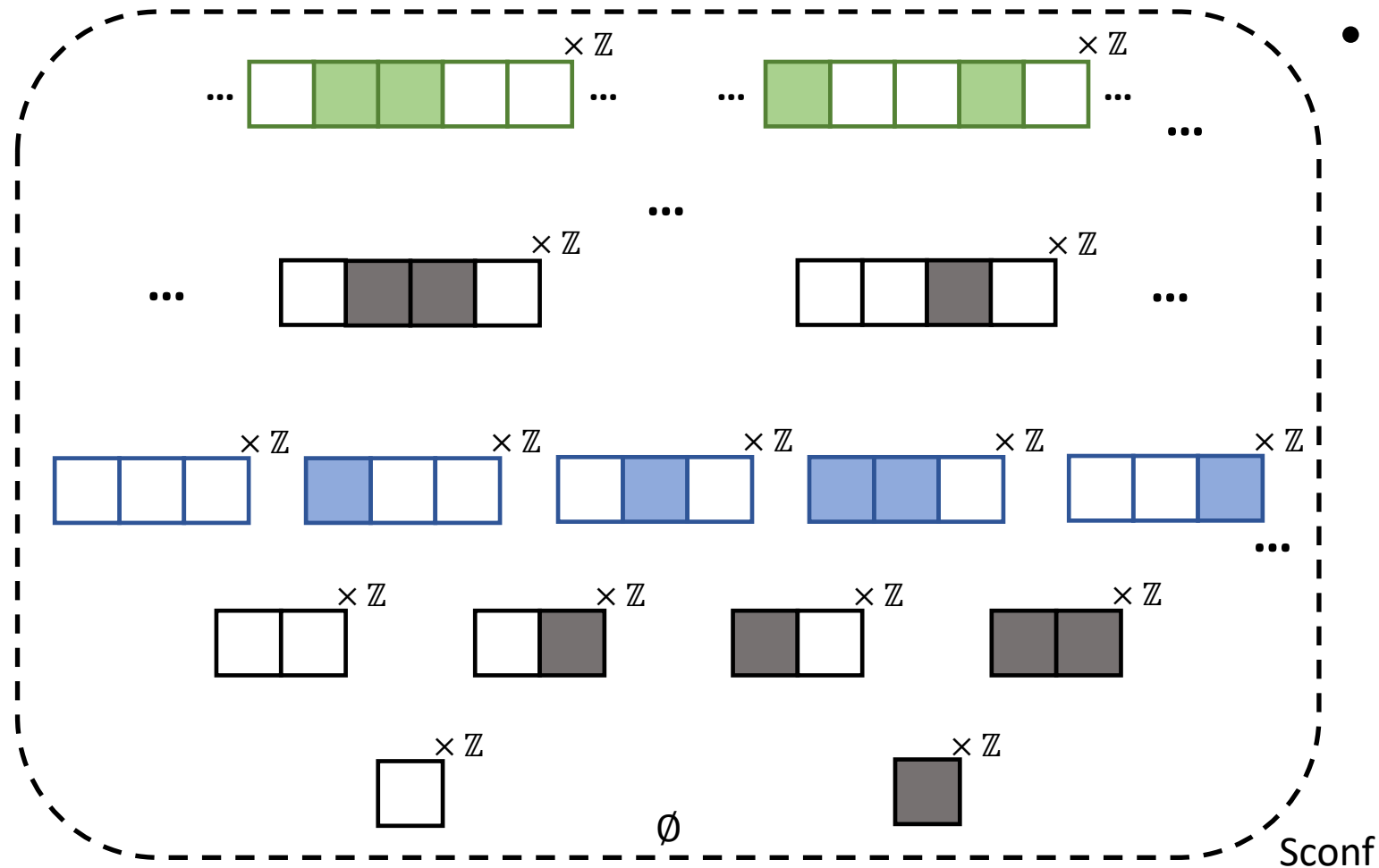
- Shifted local configurations

- Shifted sub-local configurations

Set of sub-configurations

- Sub configurations :

$$Pconf := \bigcup_{S \subseteq \mathbb{Z}} Q^S$$

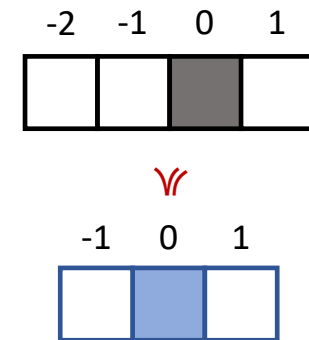


Poset of sub-configurations

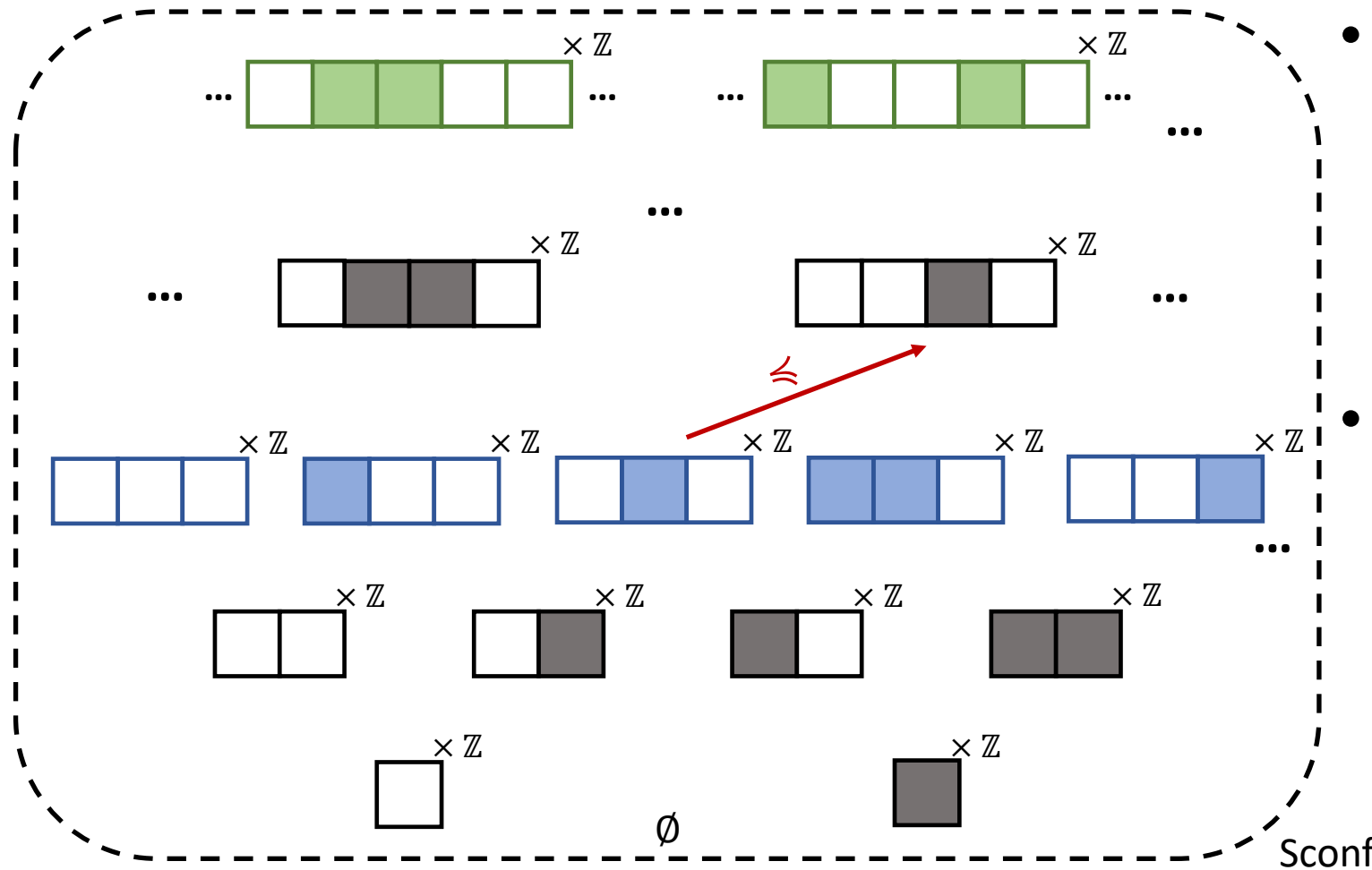
- Partial configurations :

$$Pconf := \bigcup_{S \subseteq \mathbb{Z}} Q^S$$

- Partial order relation :



Sconf



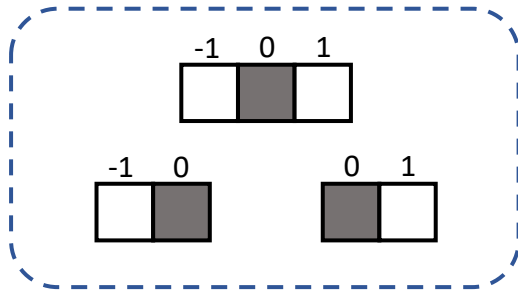
Simpler category theory

- Simple frame of work...

- 2-category of posets

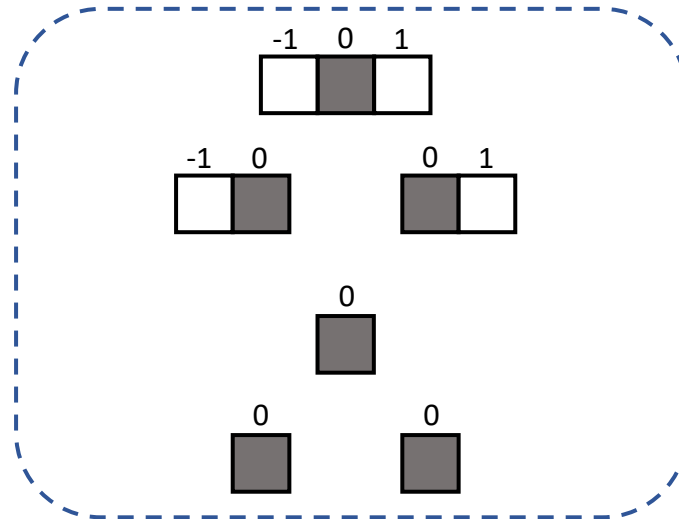
Simpler category theory

- Simple frame of work...



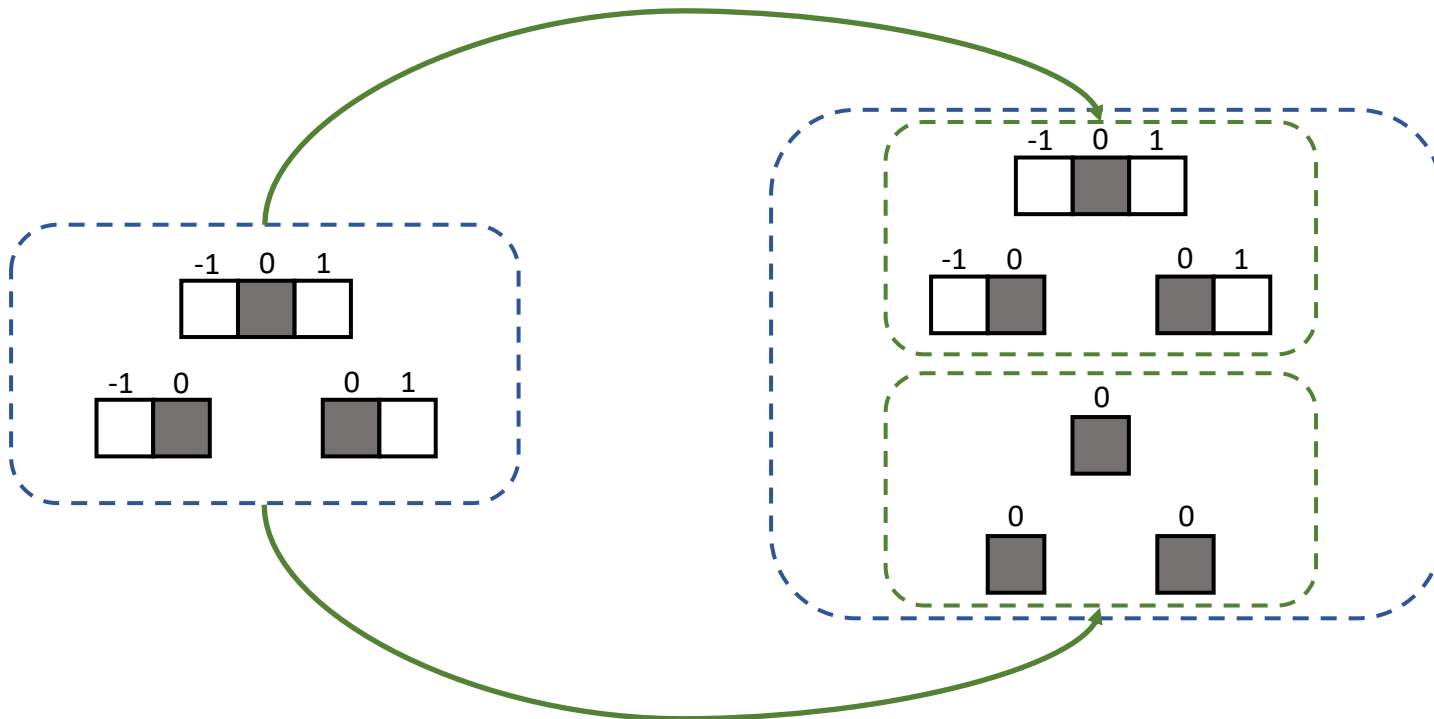
- 2-category of posets :

- Categories: Posets



Simpler category theory

- Simple frame of work...

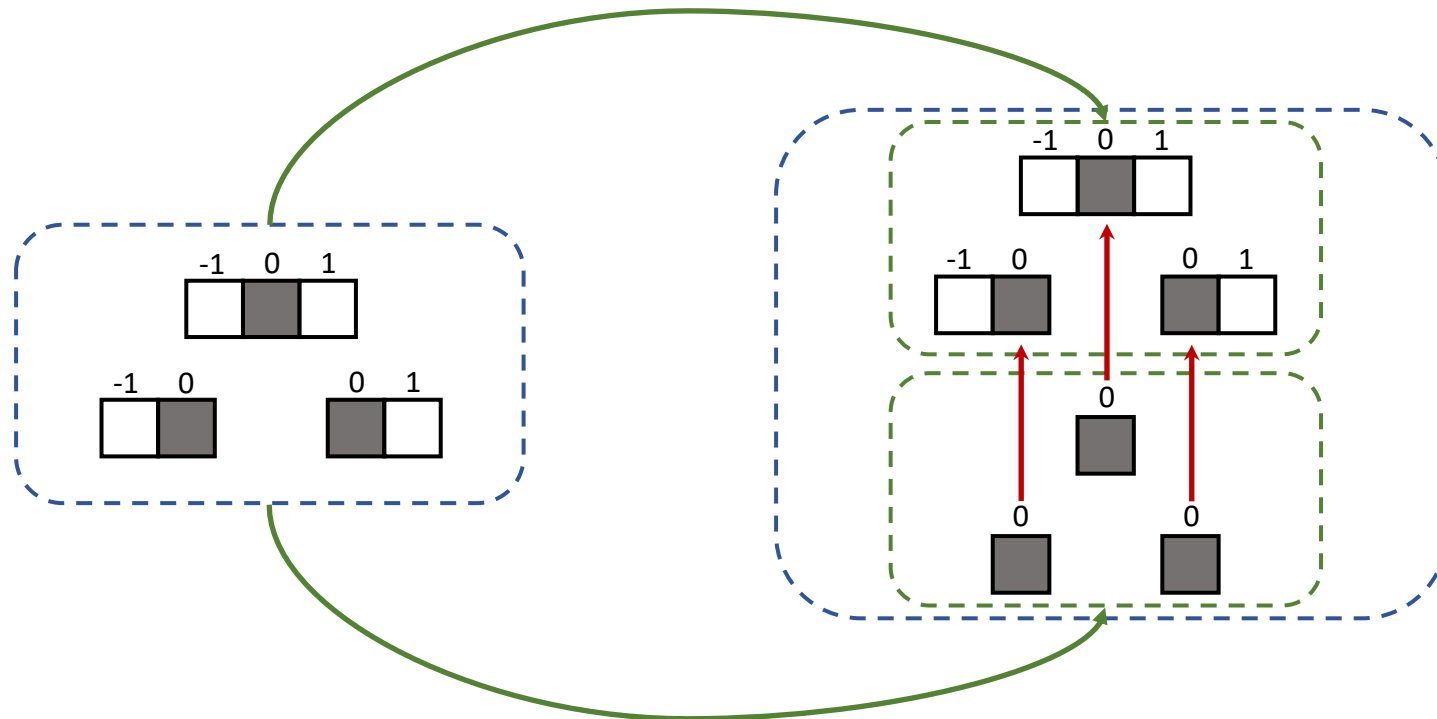


- 2-category of posets :

- Categories: Posets
- Functors: monotonous functions

Simpler category theory

- Simple frame of work...

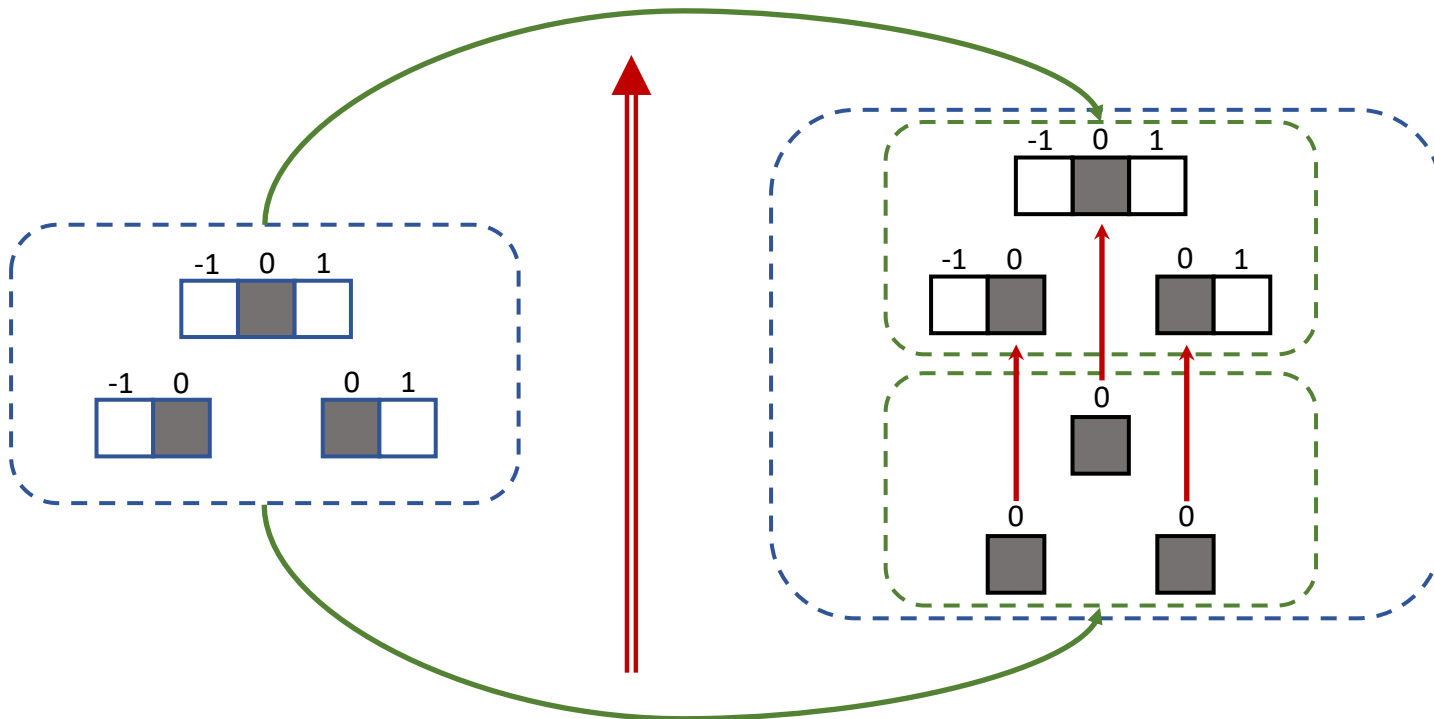


- 2-category of posets :

- Categories: Posets
- Functors: monotonous functions
- Natural transformations: partial order over functors

Simpler category theory

- Simple frame of work...



- 2-category of posets :

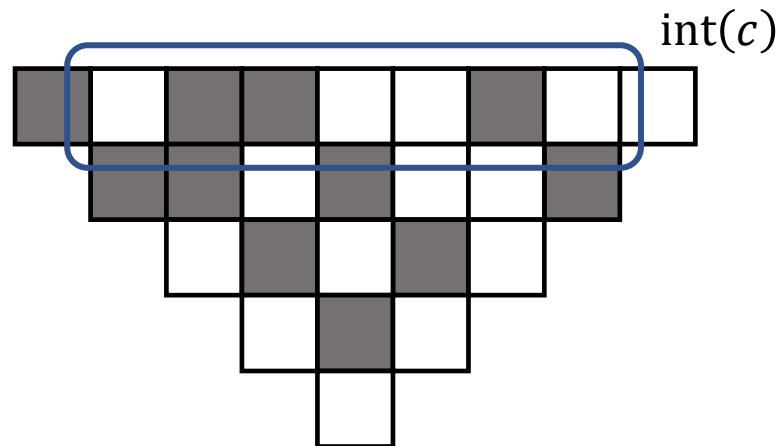
- Categories: Posets
- Functors: monotonous functions
- Natural transformations: partial order over functors

Outline

- Two ways to extend with an example
- The poset of sub-configurations
- The two extensions are kan extensions

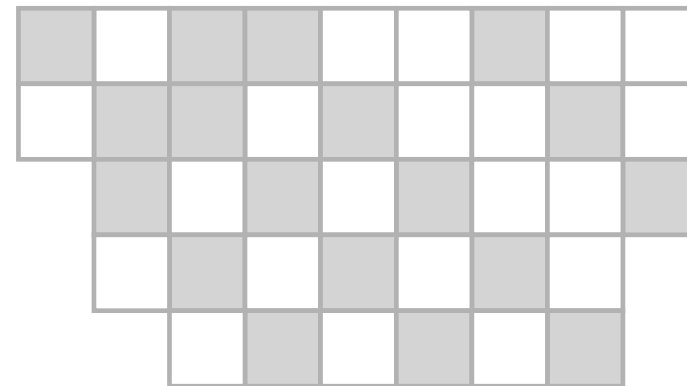
Two way of extending

- Coarse transition function $\underline{\Delta}$
 - Deduce with full neighborhood



- Is a left Kan extension !

- Fine transition function $\overline{\Delta}$
 - Deduce without neighborhood

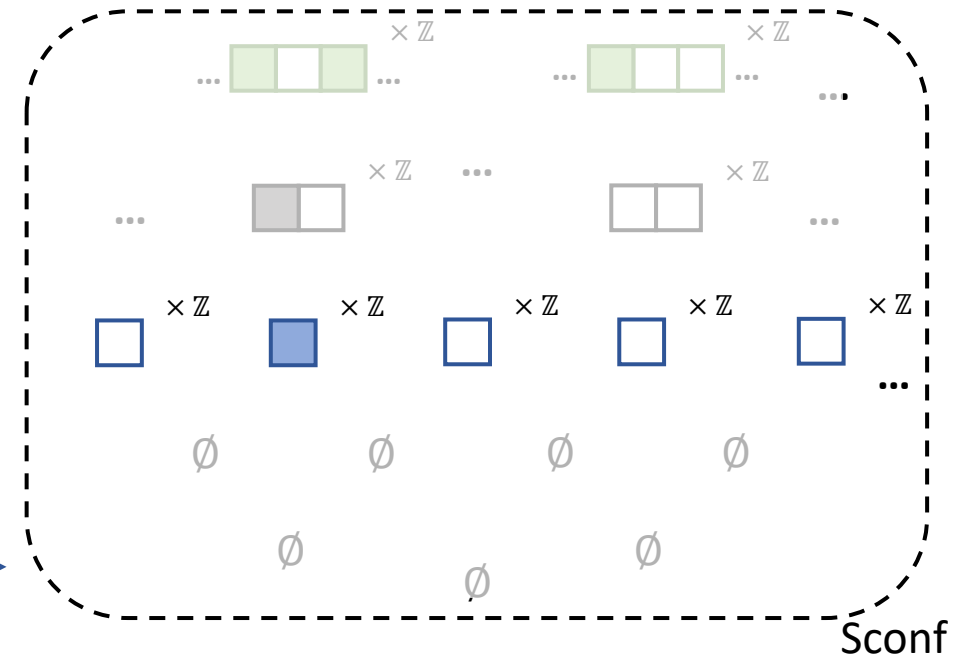
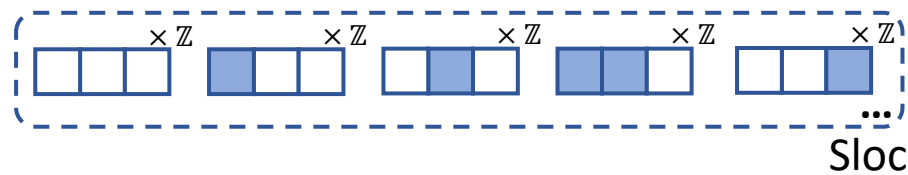


- Is a right Kan extension !

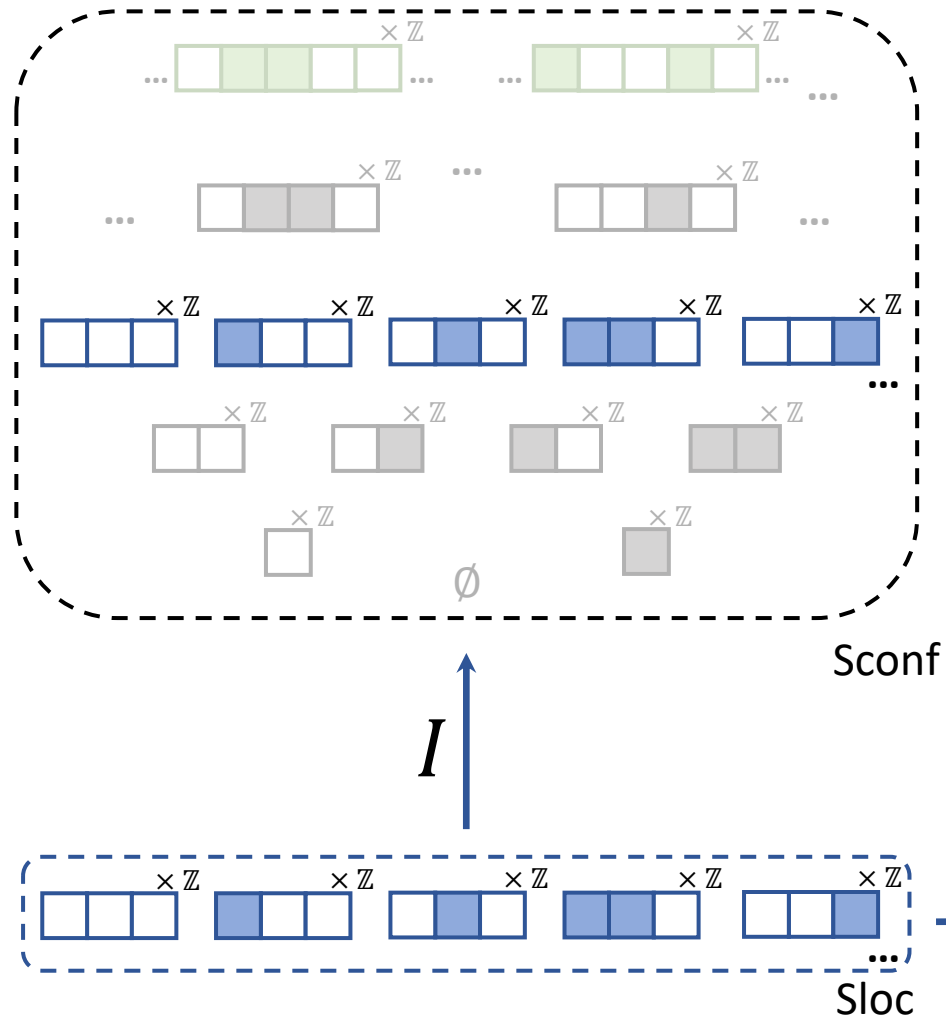
Coarse as left Kan extension

- Shifted local transition $\overleftrightarrow{\delta}$:
 - Applies **local rules** over Sloc

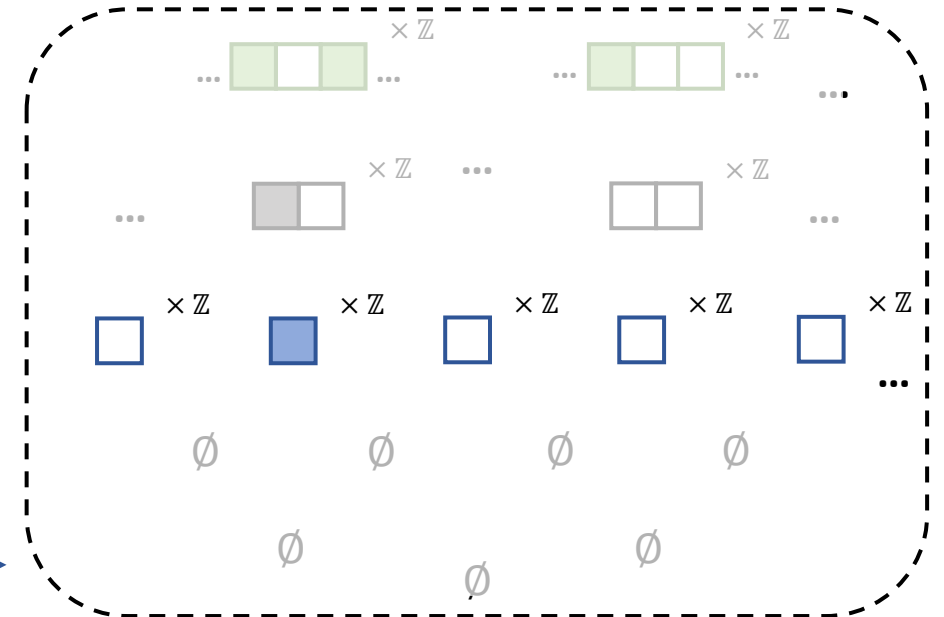
$$\overleftrightarrow{\delta} \left(\begin{array}{ccc} 4 & 5 & 6 \\ \blacksquare & \square & \square \end{array} \right) = \blacksquare_5$$



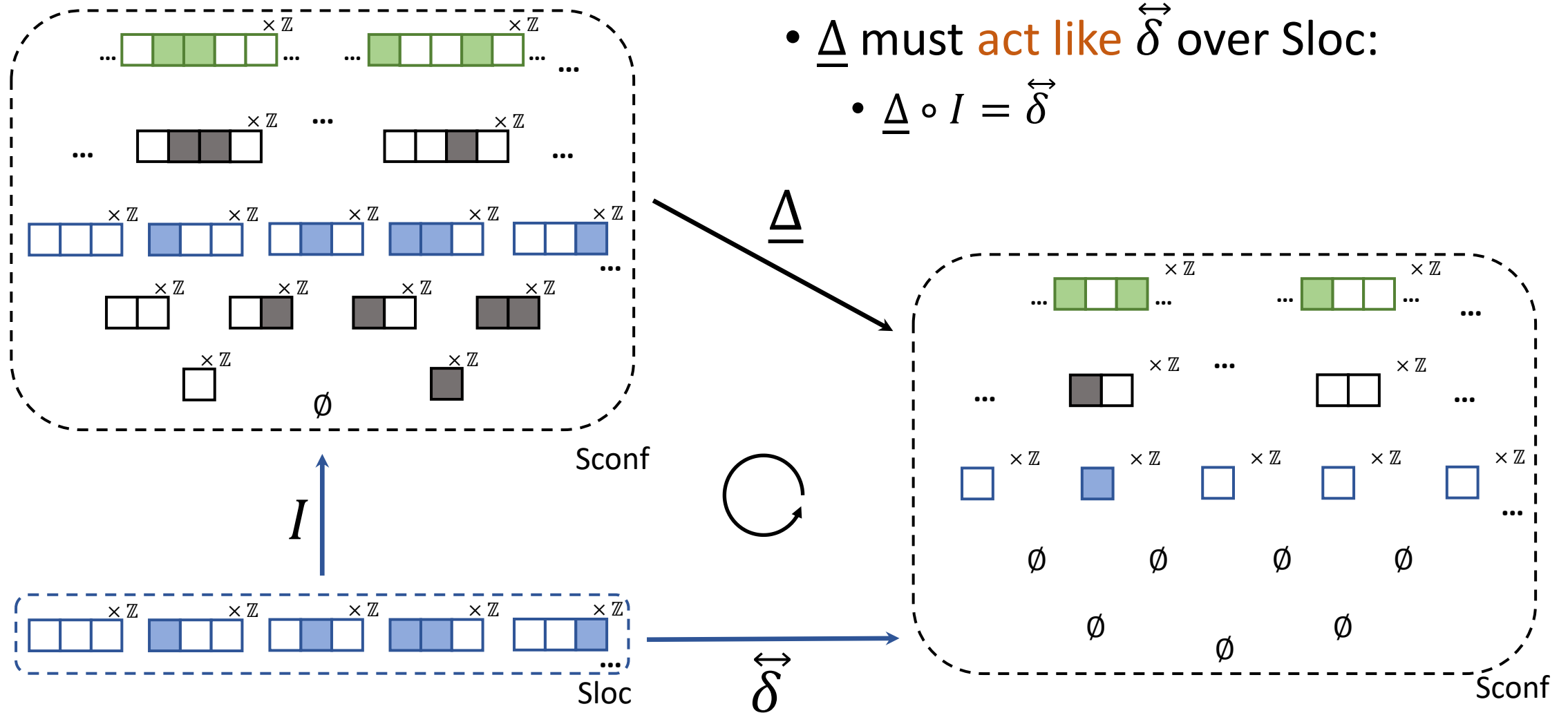
Coarse as left Kan extension



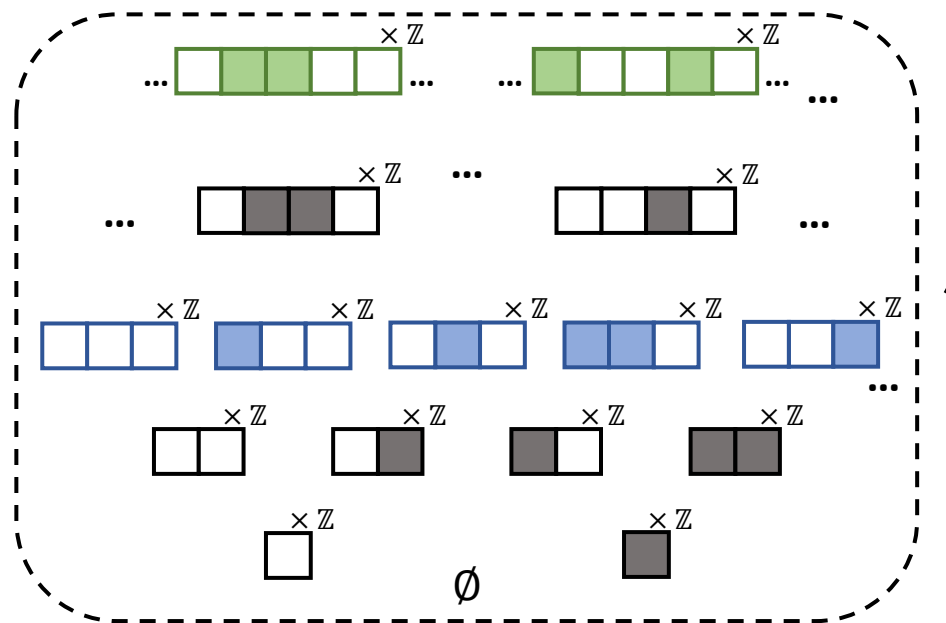
- Shifted local transition δ
- Sloc is included in Pconf by (monotonous) I



Coarse as left Kan extension

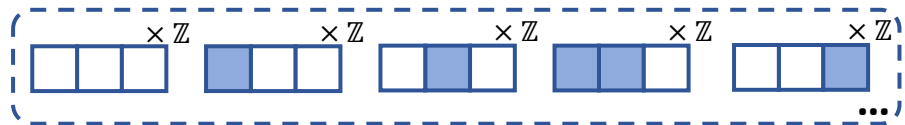


Coarse as left Kan extension

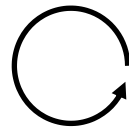


Sconf

I



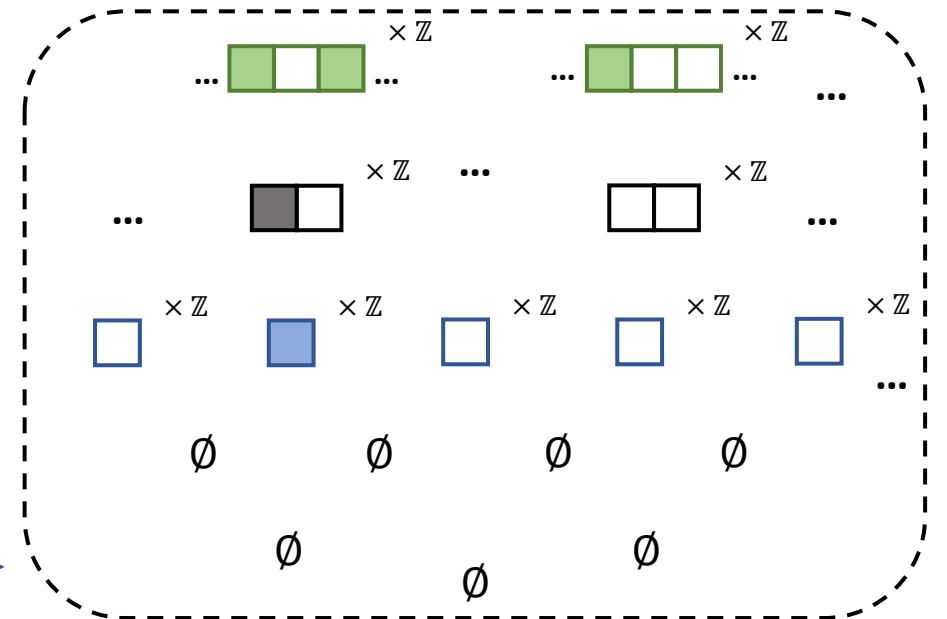
Sloc



δ

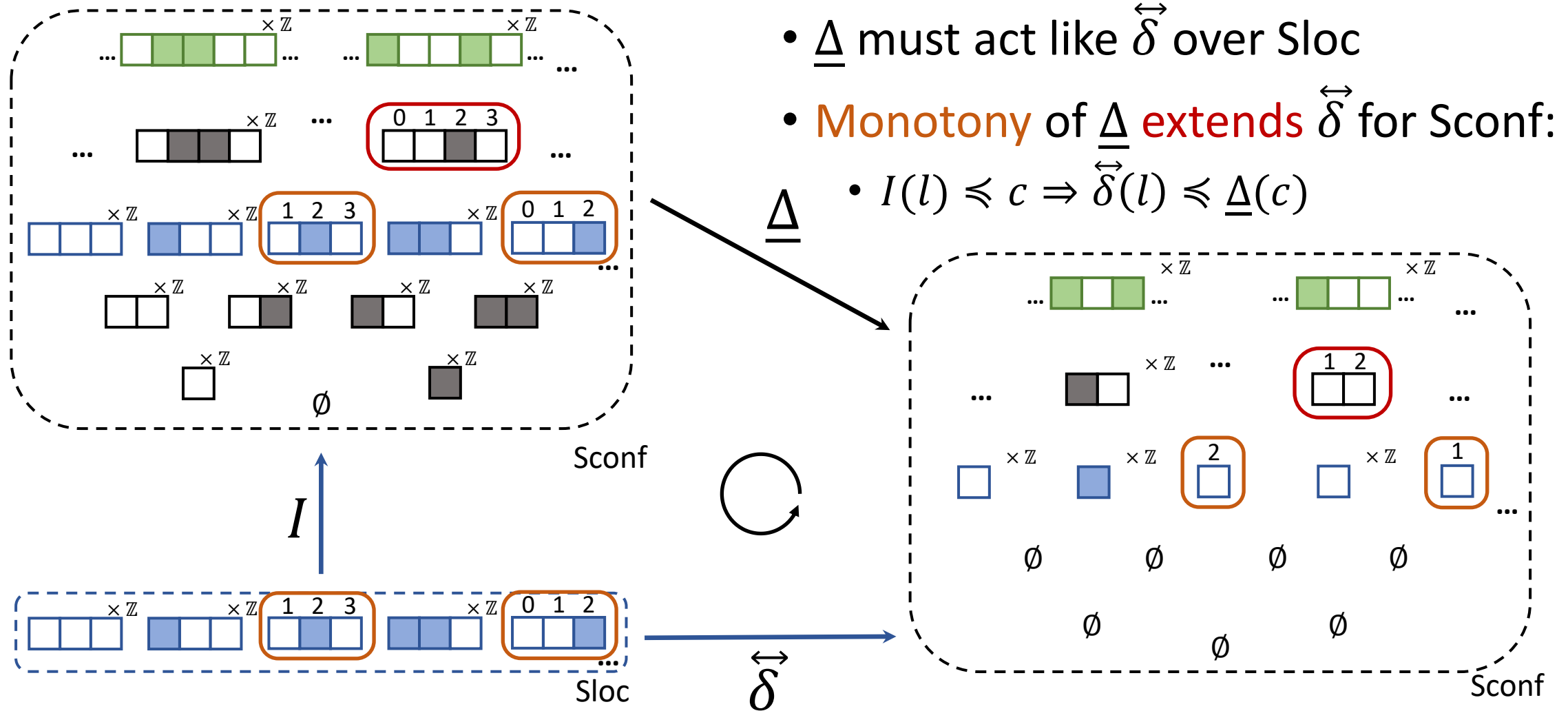
- $\underline{\Delta}$ must act like δ over Sloc
- **Monotony** of $\underline{\Delta}$ extends δ for Sconf:
 - $I(l) \preceq c \Rightarrow \delta(l) \preceq \underline{\Delta}(c)$

$\underline{\Delta}$

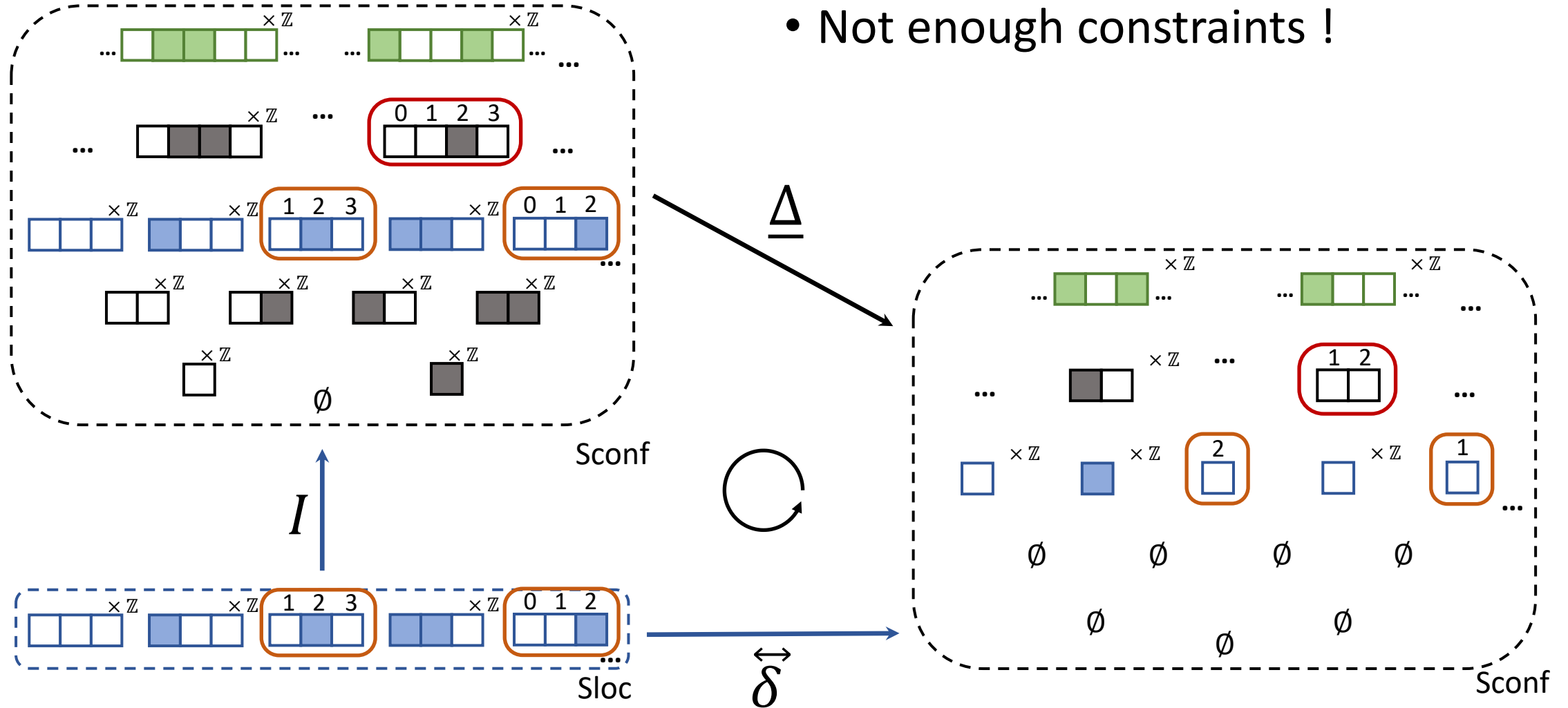


Sconf

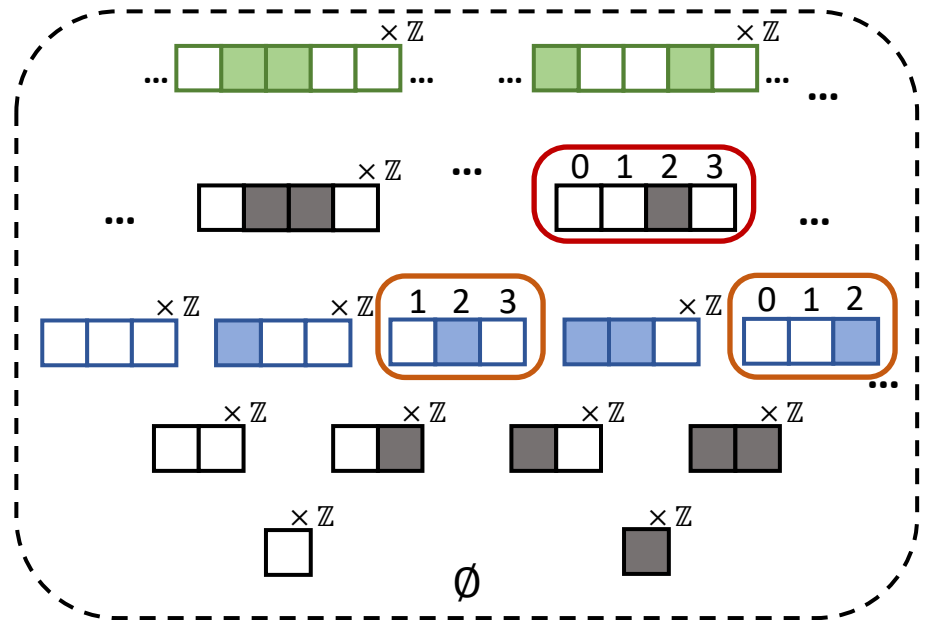
Coarse as left Kan extension



Coarse as left Kan extension

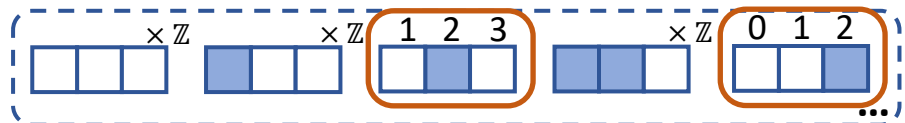


Coarse as left Kan extension



S_{conf}

I



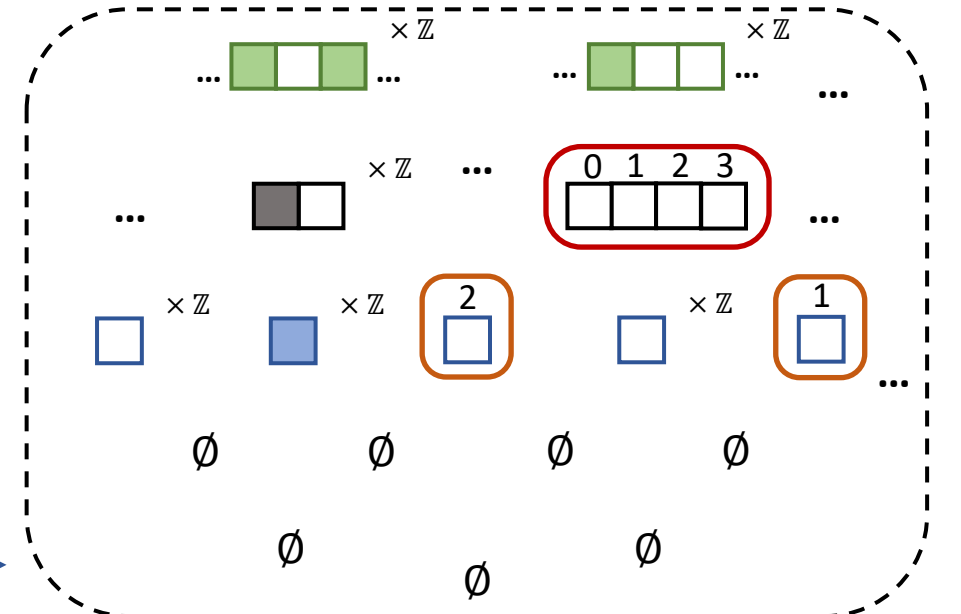
S_{loc}



δ

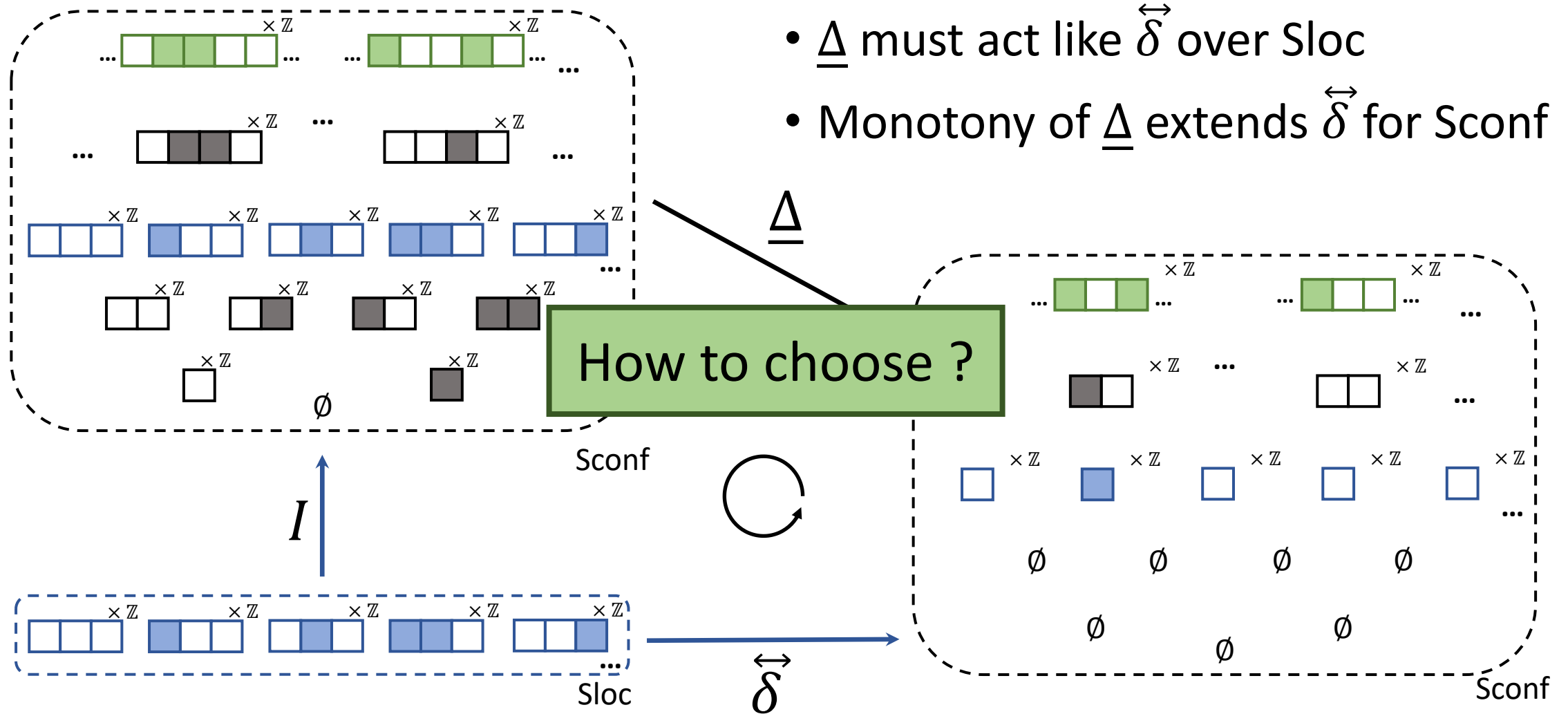
- Not enough constraints !
- Function could add some cells

Δ'

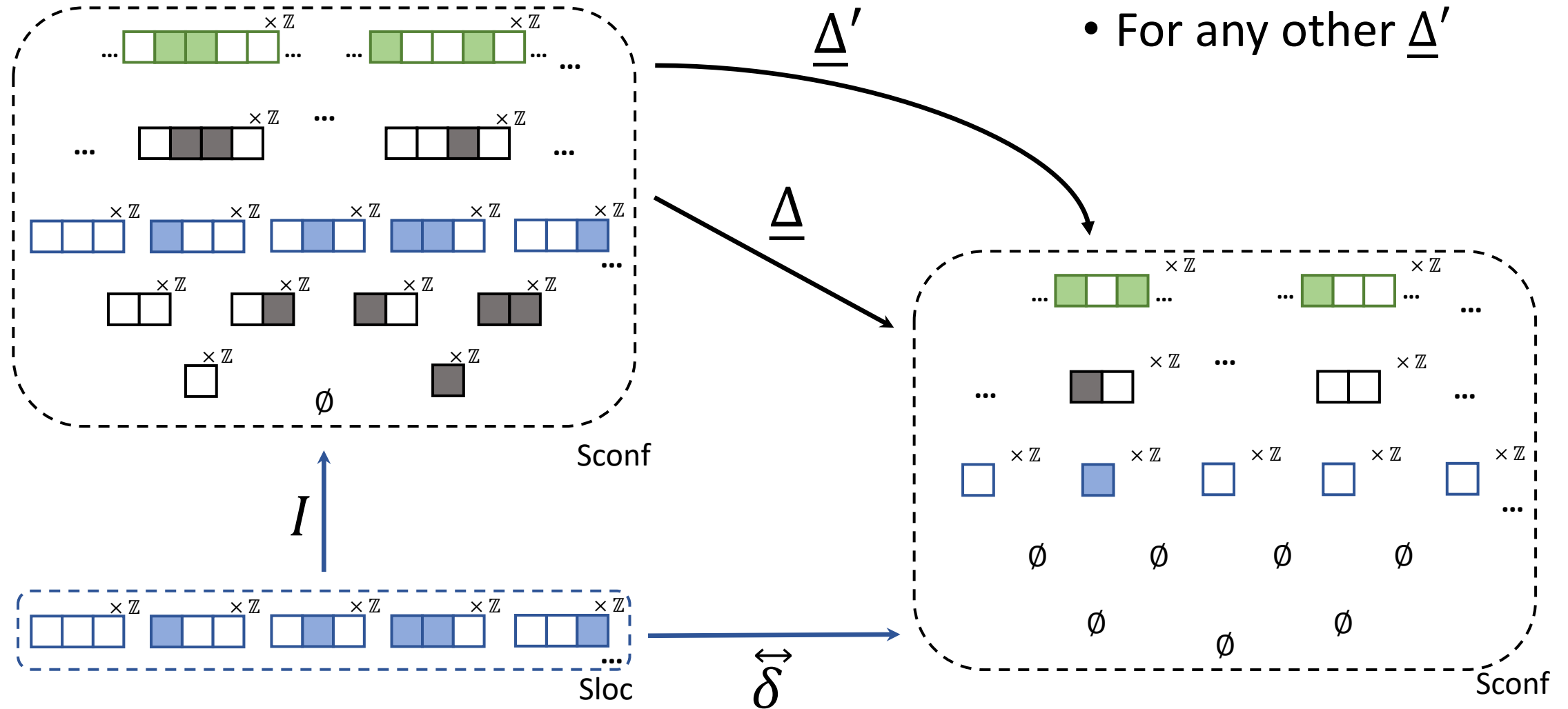


S_{conf}

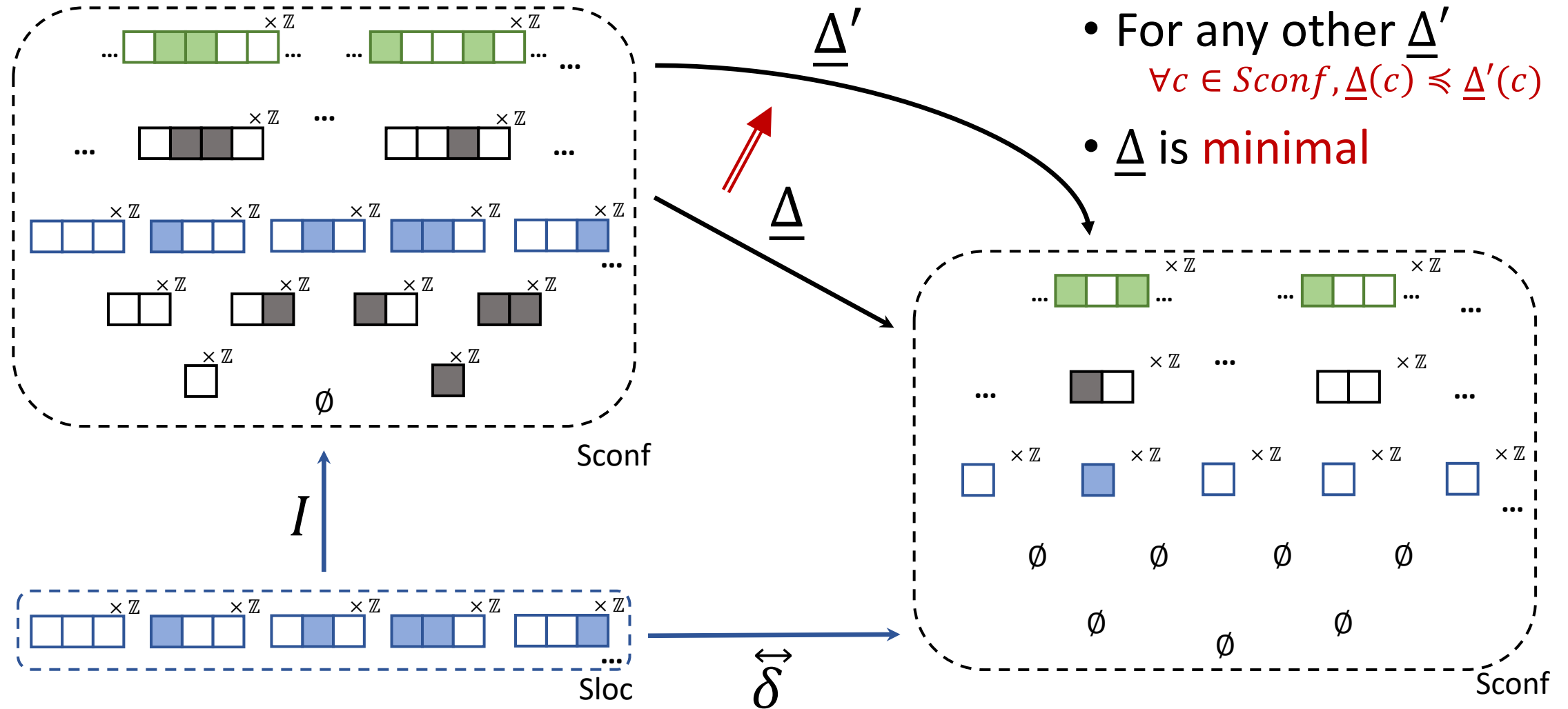
Coarse as left Kan extension



Coarse as left Kan extension

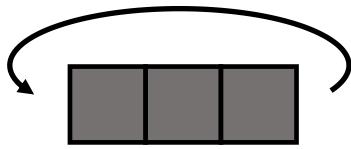


Coarse as left Kan extension

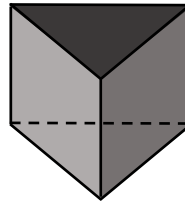


Coarse as left Kan extension

- If **torsion of space**, more complicated...



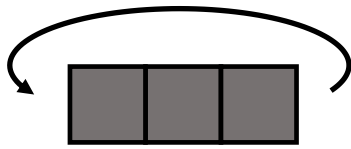
Space : closed ribbon



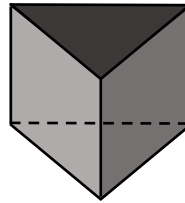
Sub-configuration

Coarse as left Kan extension

- If torsion of space, more complicated...

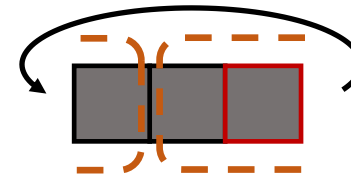
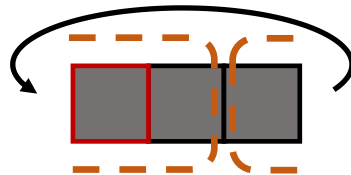
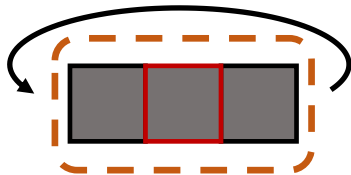


Space : closed ribbon



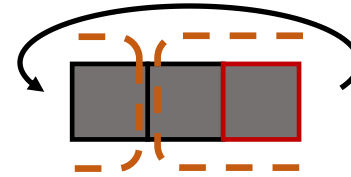
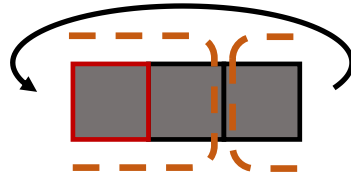
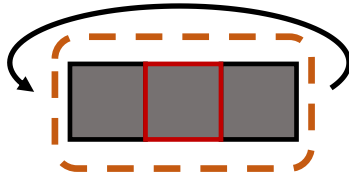
Sub-configuration

- Sub-configuration = **multiple neighborhoods** !



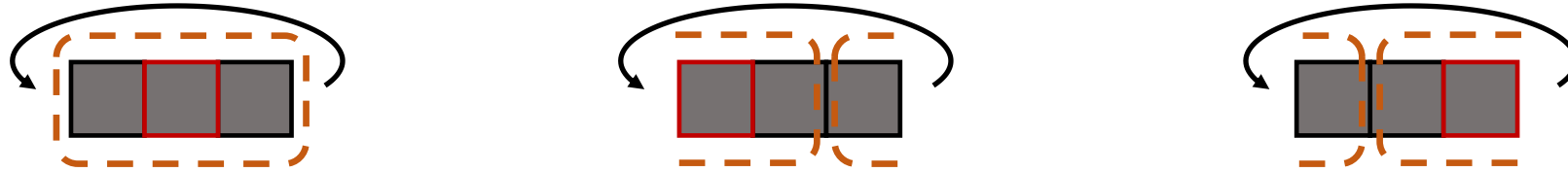
Coarse as left Kan extension

- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !



Coarse as left Kan extension

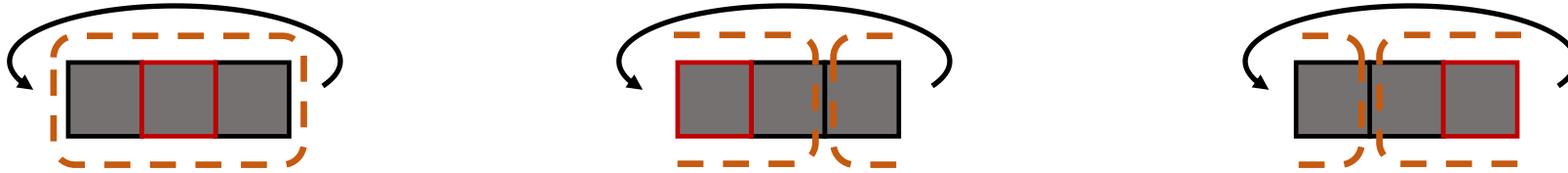
- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !



- Rules must know the center, extension does not

Coarse as left Kan extension

- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !



- Rules must know the center, extension does not
 - Extension = ?

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline -1 \\ \hline \end{array}$$

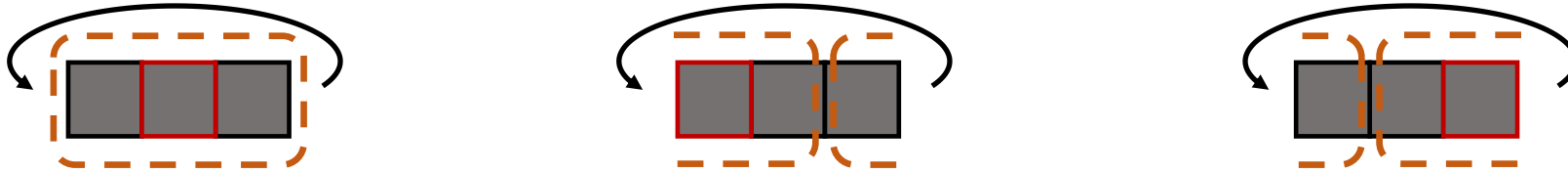
$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 0 \\ \hline \end{array}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 1 \\ \hline \end{array}$$

$$\underline{\Delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = ?$$

Coarse as left Kan extension

- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !



- Rules must know the center, extension does not
 - Extension = **multiple rules at one time** !

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline -1 \\ \hline \end{array}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 0 \\ \hline \end{array}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 1 \\ \hline \end{array}$$

$$\underline{\Delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}$$

Coarse as left Kan extension

- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !
- Rules must know the center, extension does not
 - Extension = multiple rules at one time !

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline -1 \\ \hline \end{array}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 0 \\ \hline \end{array}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 1 \\ \hline \end{array}$$

$$\underline{\Delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}$$

Coarse as left Kan extension

- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !
- Rules must know the center, extension does not
 - Extension = multiple rules at one time !

$$\overset{\leftarrow}{\delta}(\begin{array}{c} -1 \quad 0 \quad 1 \\ \boxed{} \boxed{} \boxed{} \end{array}) = \boxed{}^{-1}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{c} -1 \quad 0 \quad 1 \\ \boxed{} \boxed{} \boxed{} \end{array}) = \boxed{}^0$$

$$\overset{\leftarrow}{\delta}(\begin{array}{c} -1 \quad 0 \quad 1 \\ \boxed{} \boxed{} \boxed{} \end{array}) = \boxed{}^1$$

$$\underline{\Delta}(\begin{array}{c} -1 \quad 0 \quad 1 \\ \boxed{} \boxed{} \boxed{} \end{array}) = \begin{array}{c} -1 \quad 0 \quad 1 \\ \boxed{} \boxed{} \boxed{} \end{array}$$

- **R**edefine $Sloc := \bigcup_{p \in G} \{p\} \times Q^{(p+N)}$

Coarse as left Kan extension

- If torsion of space, more complicated...
- Sub-configuration = multiple neighborhoods !
- Rules must know the center, extension does not
 - Extension = multiple rules at one time !

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline -1 \\ \hline \end{array}$$

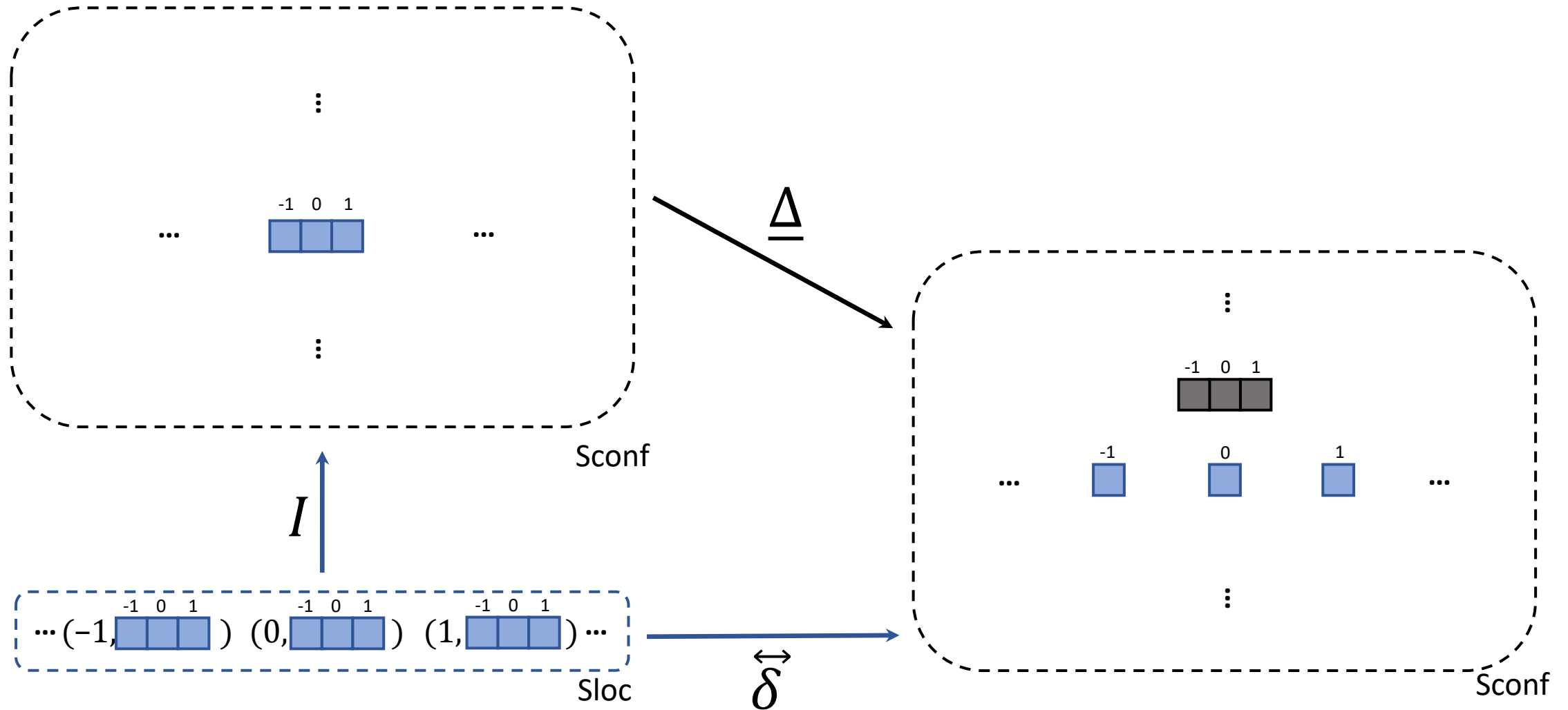
$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 0 \\ \hline \end{array}$$

$$\overset{\leftarrow}{\delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|} \hline 1 \\ \hline \end{array}$$

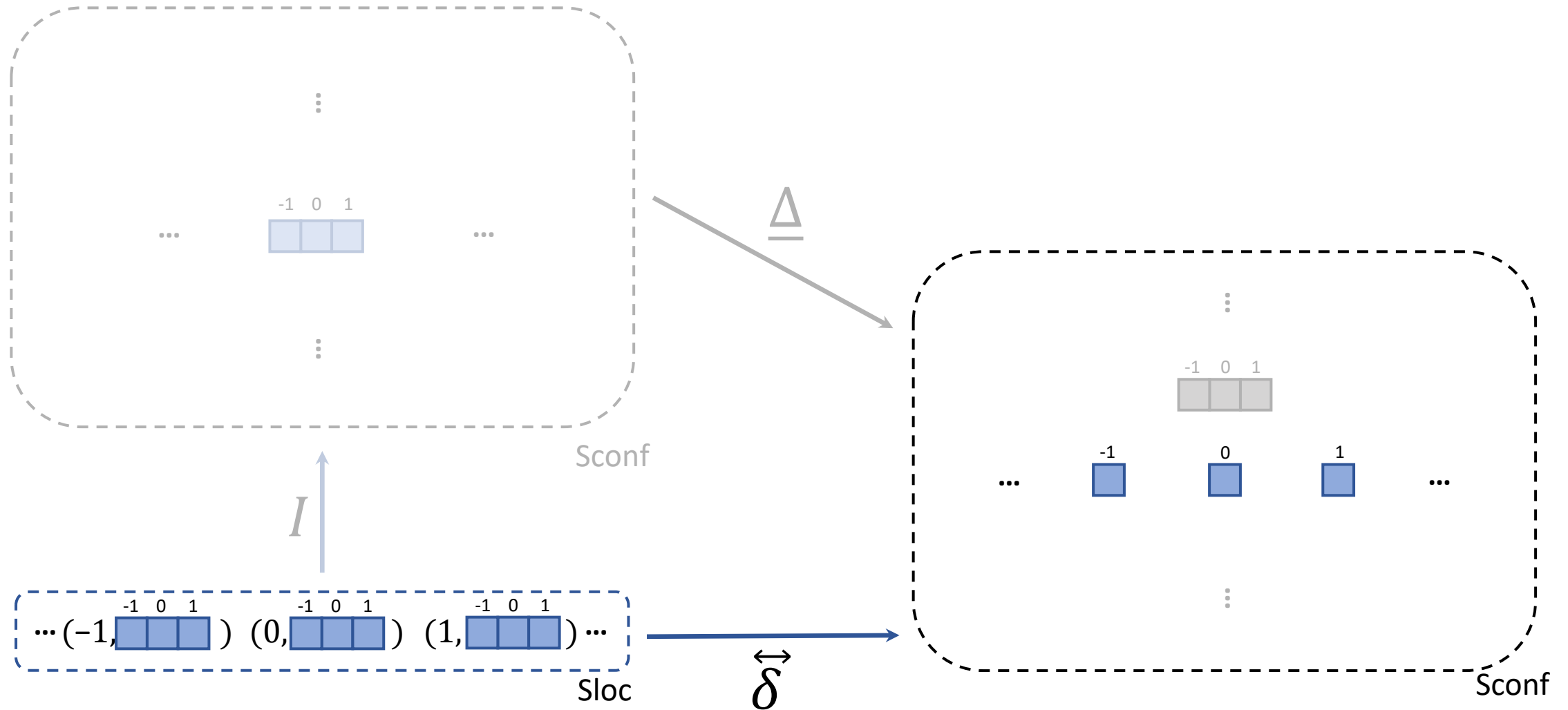
$$\underline{\Delta}(\begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}) = \begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline \end{array}$$

- **R**edefine $Sloc := \bigcup_{p \in G} \{p\} \times Q^{(p+N)}$
- And $I: Sloc \rightarrow SConf := \pi_2$ not injective !

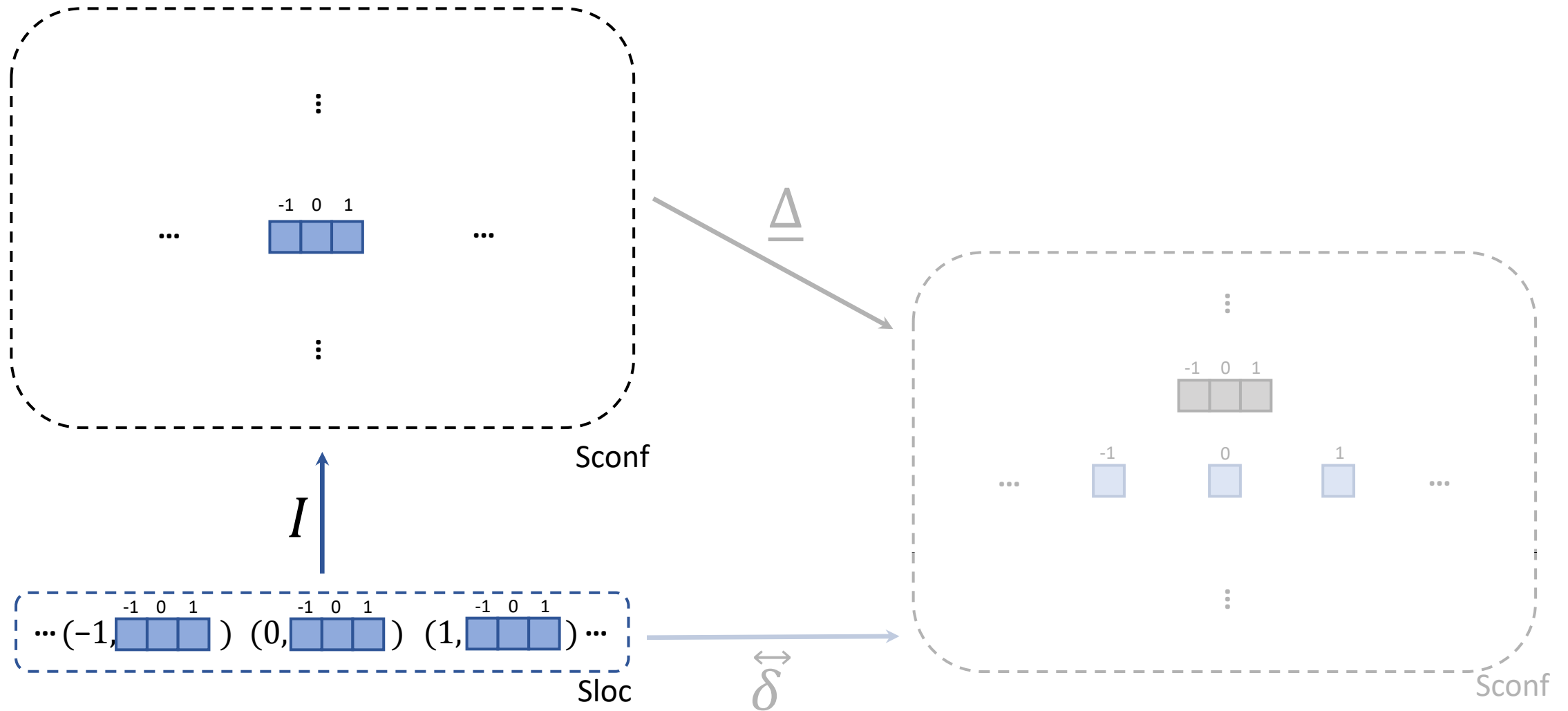
Coarse as left Kan extension



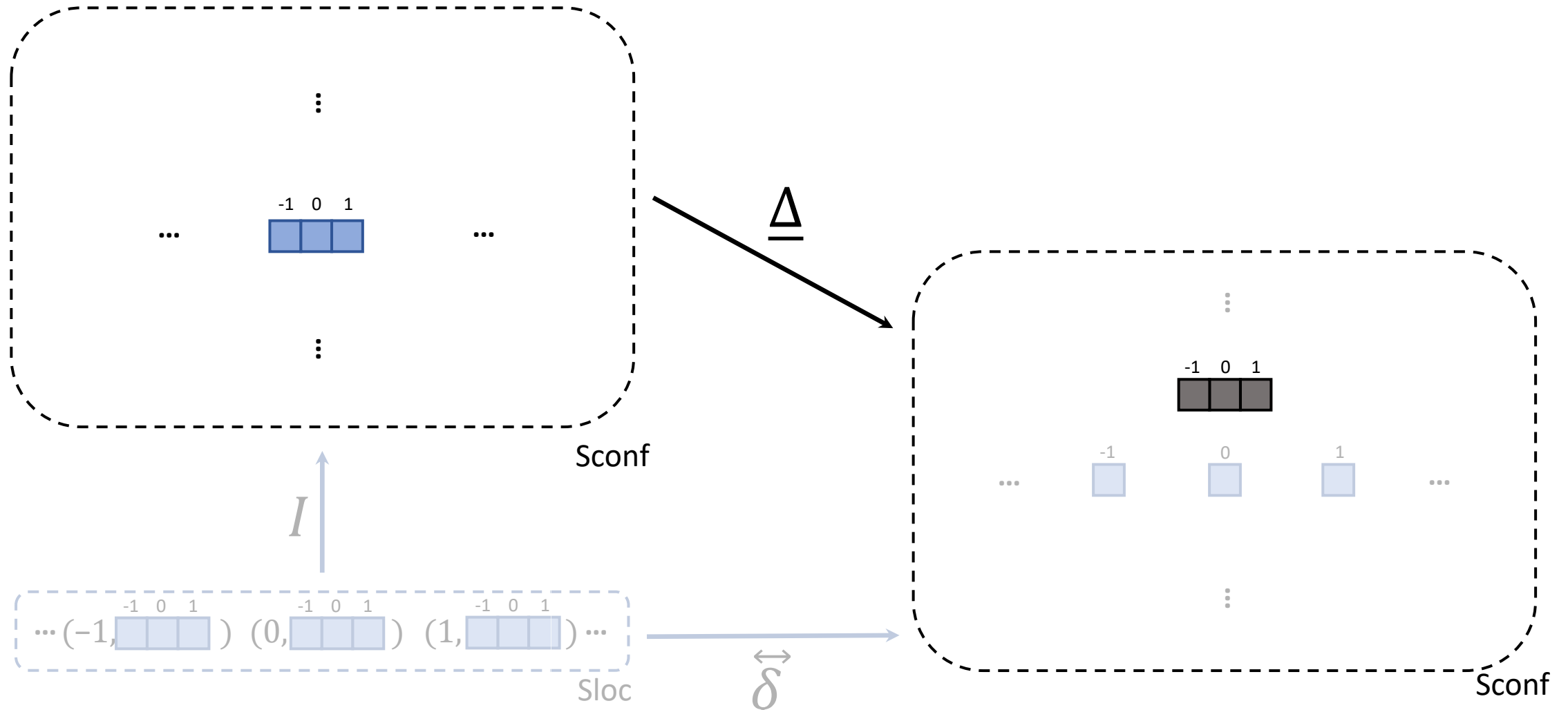
Coarse as left Kan extension



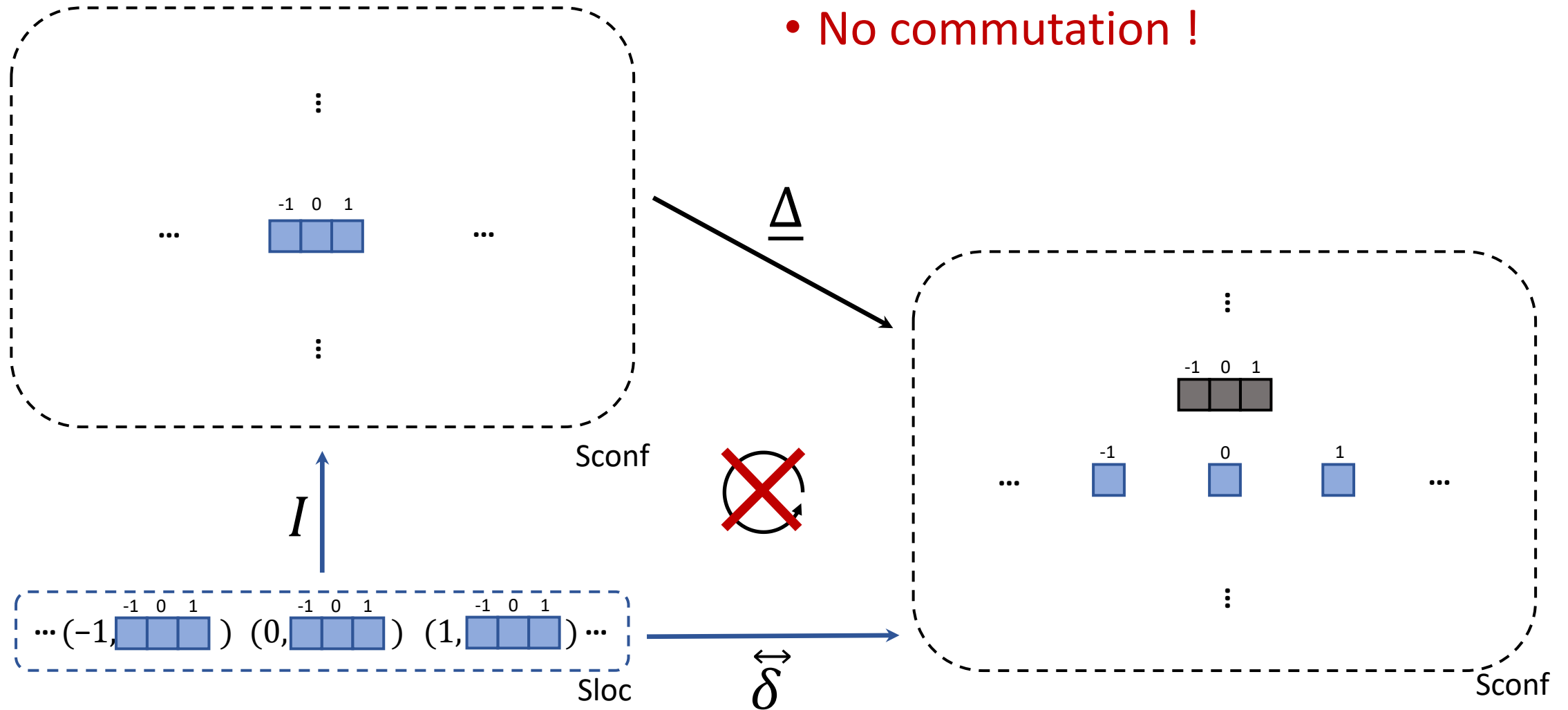
Coarse as left Kan extension



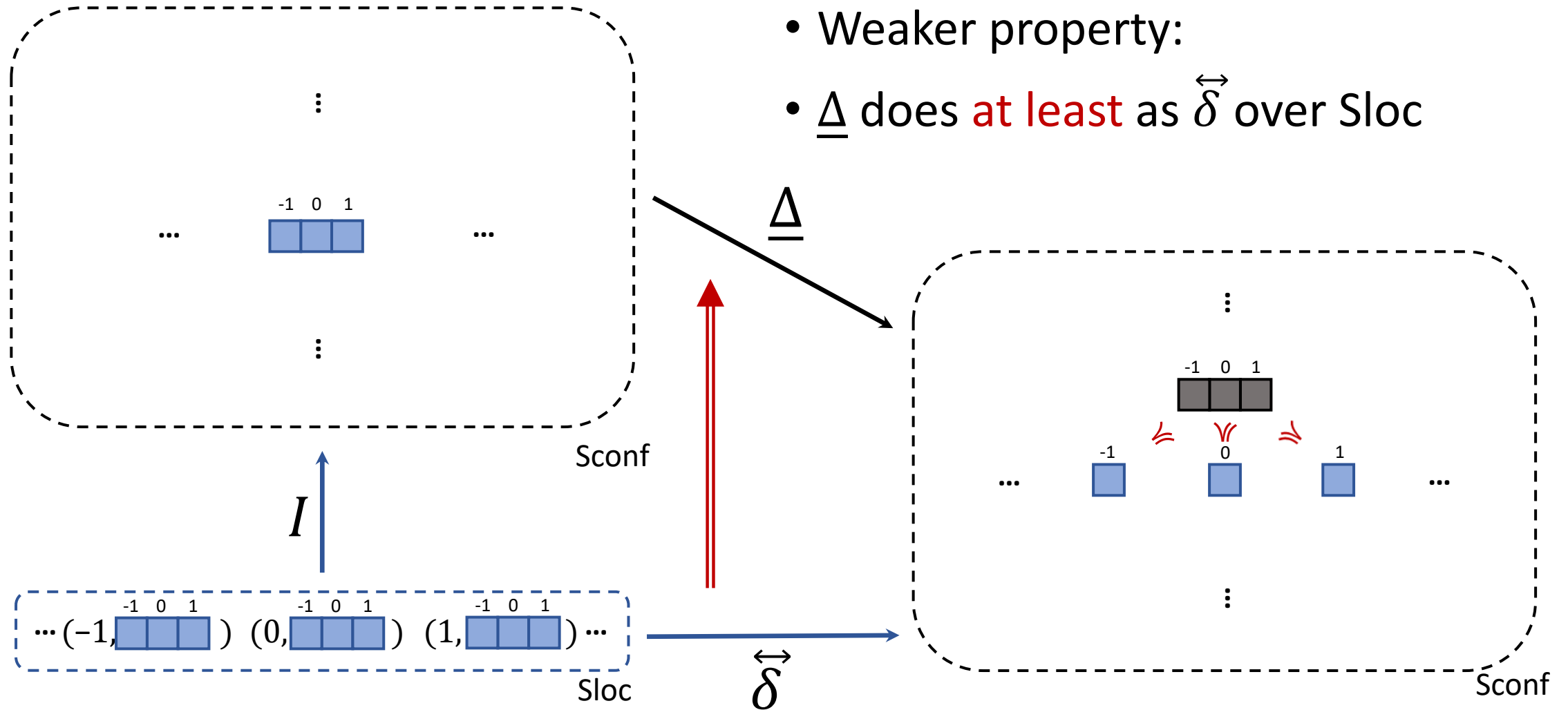
Coarse as left Kan extension



Coarse as left Kan extension



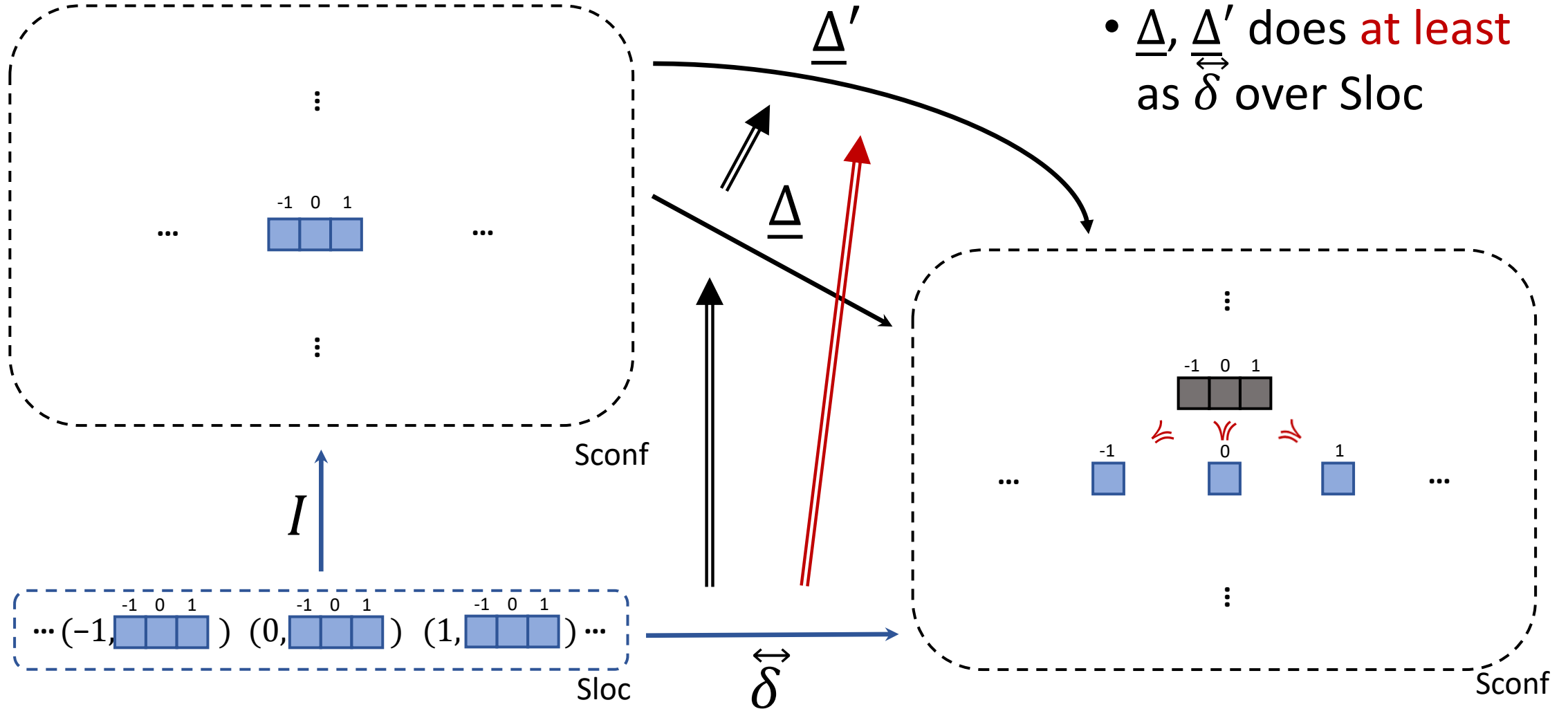
Coarse as left Kan extension



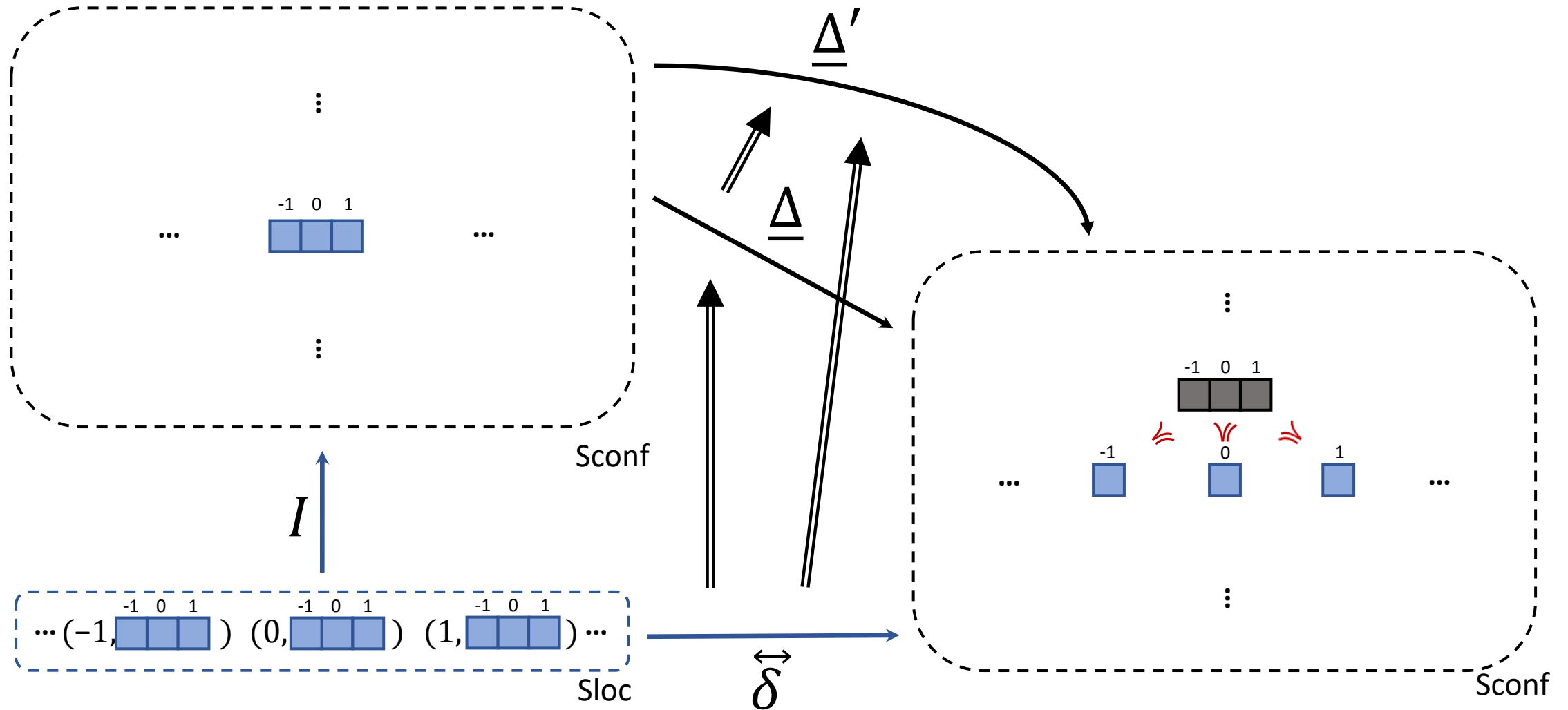
- Weaker property:

- $\underline{\Delta}$ does **at least** as δ over $Sloc$

Coarse as left Kan extension

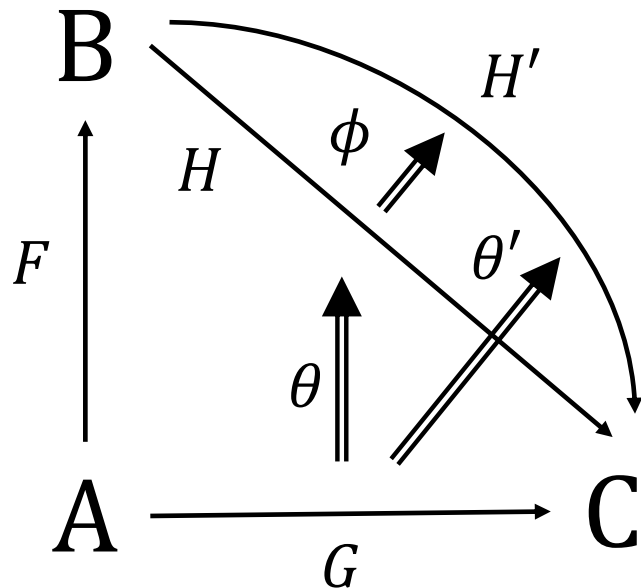


Coarse as left Kan extension



Left Kan Extensions

- Left Kan Extension of G along F is some $\langle H, \theta \rangle$



- $\theta: G \Rightarrow H \circ F$

- Universal :

- Given $\langle H', \theta' \rangle$, exists unique ϕ s.t.

- $\theta' = (\phi \circ F) \cdot \theta$

- H « **minimal** » and unique

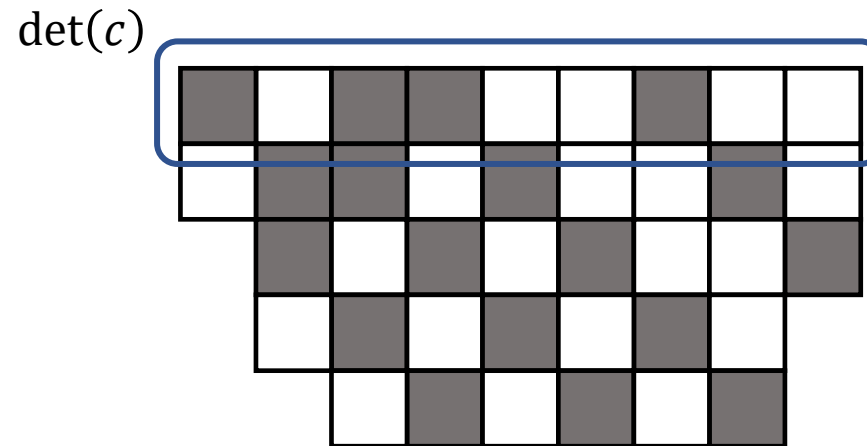
Two way of extending

- Coarse transition function $\underline{\Delta}$
 - Deduce with full neighborhood



- Is a left Kan extension !

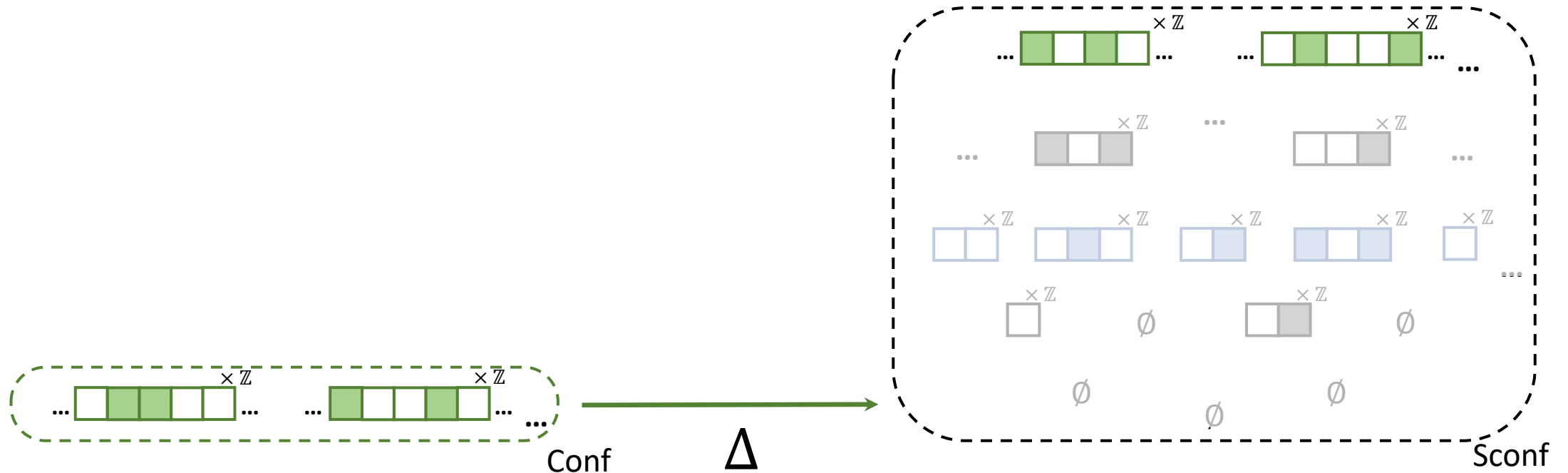
- Fine transition function $\overline{\Delta}$
 - Deduce without neighborhood



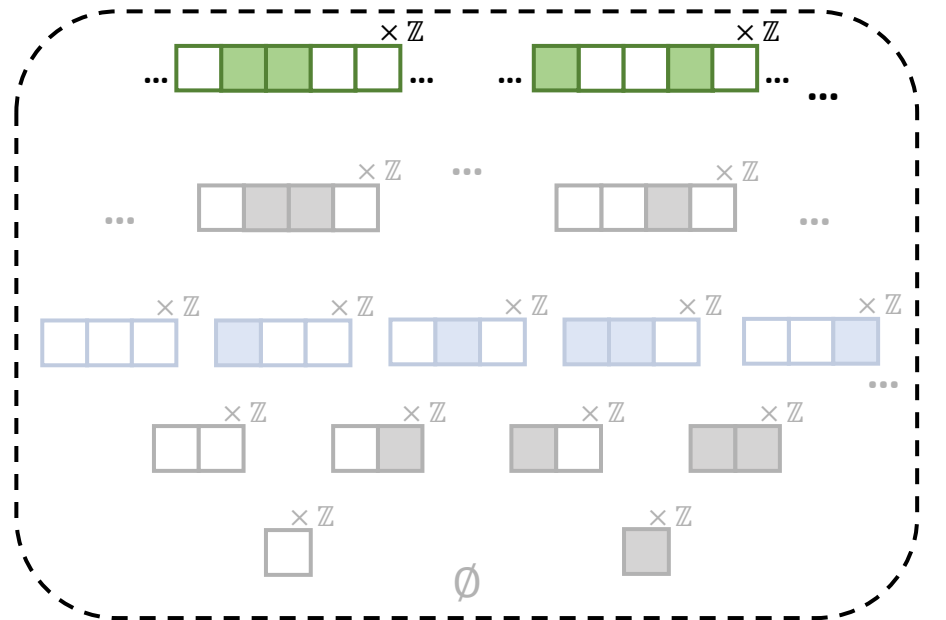
- Is a right Kan extension !

Fine as right Kan extension

- Global transition function Δ

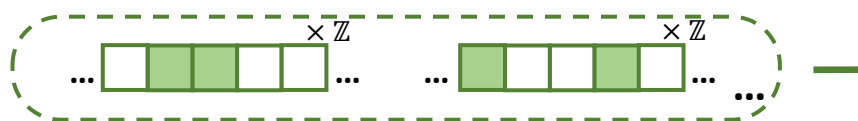


Fine as right Kan extension



Sconf

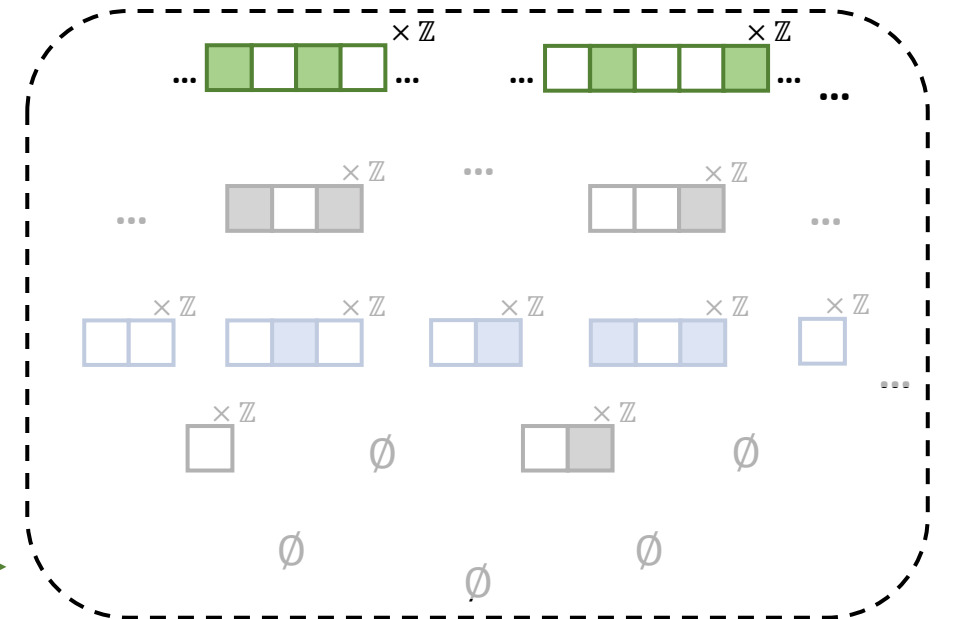
J



Conf

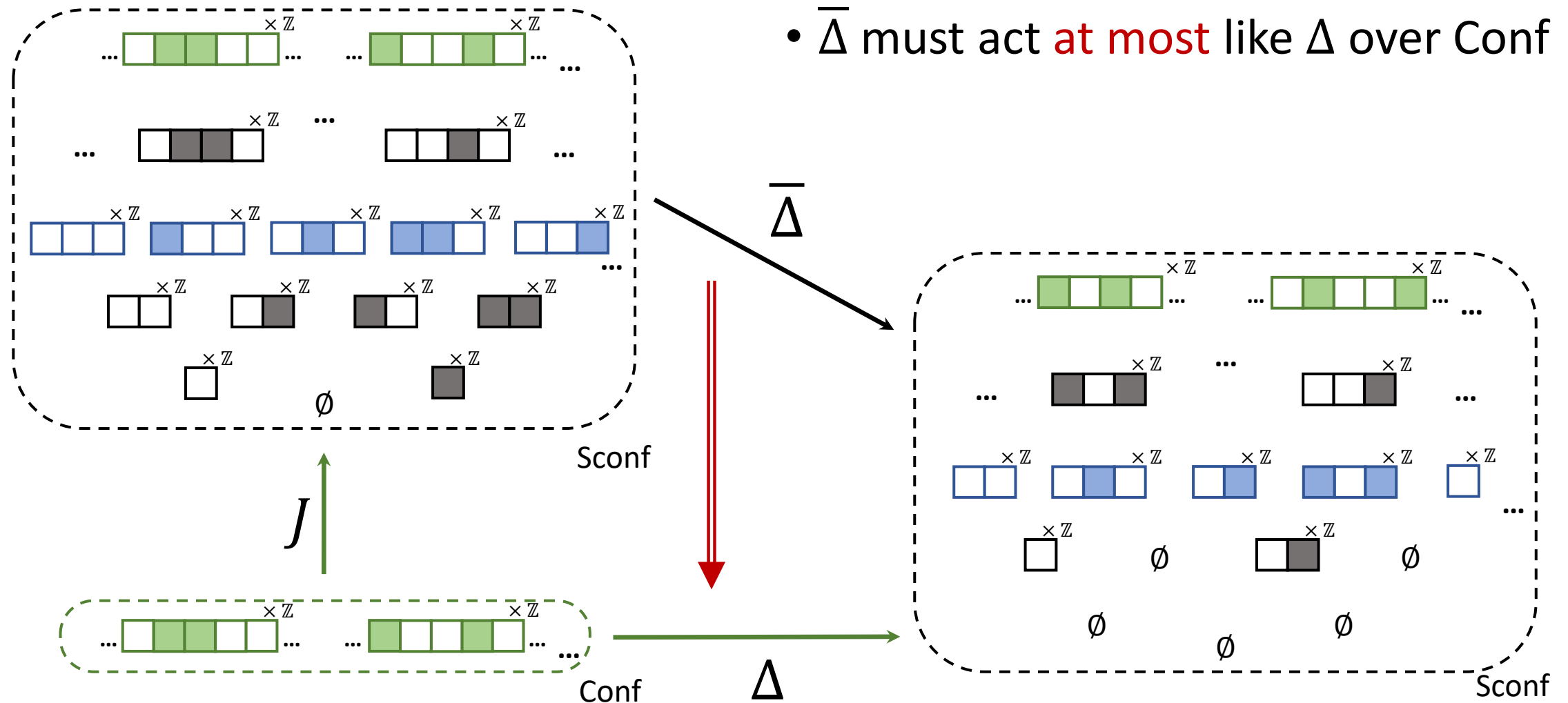
Δ

- Global transition function Δ
- Conf is included in Pconf by (monotonous) J

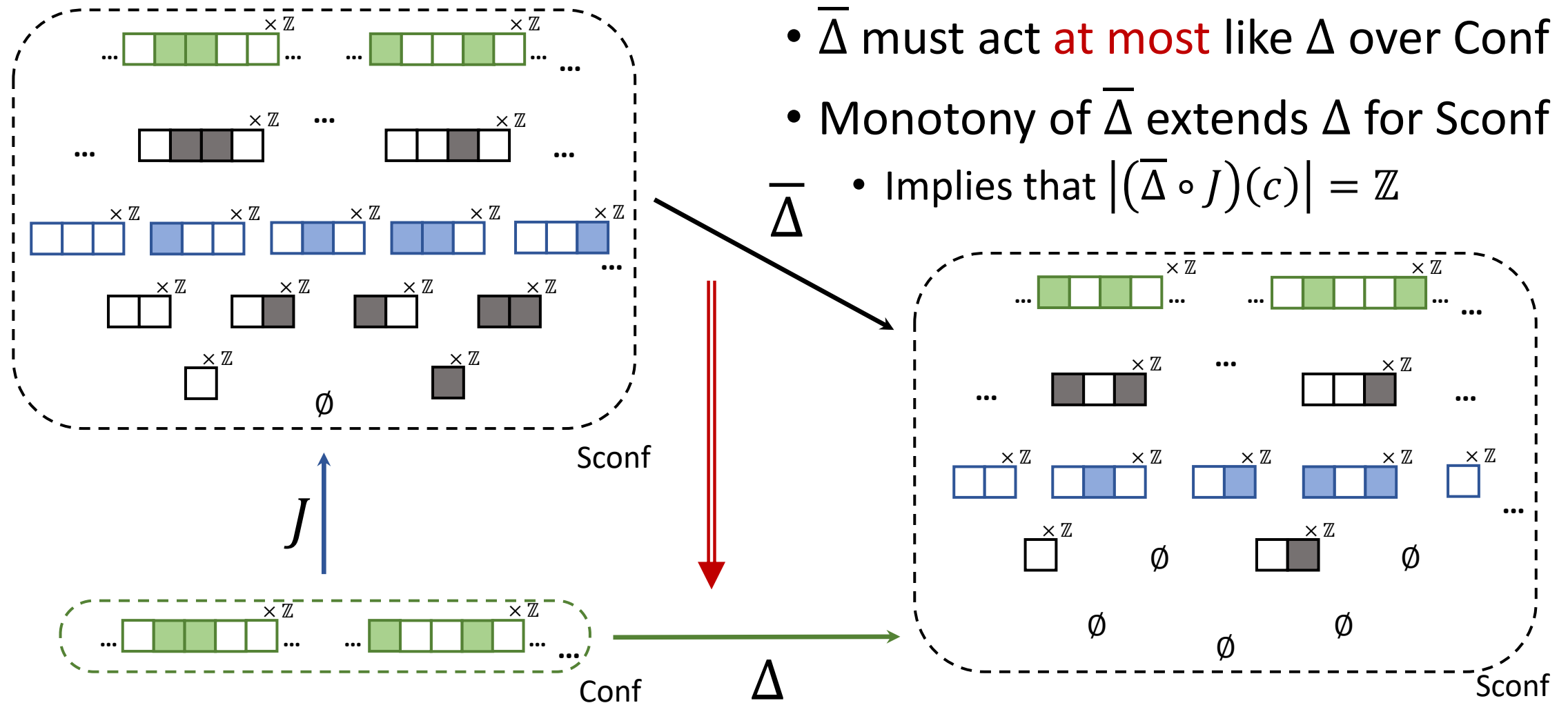


Sconf

Fine as right Kan extension

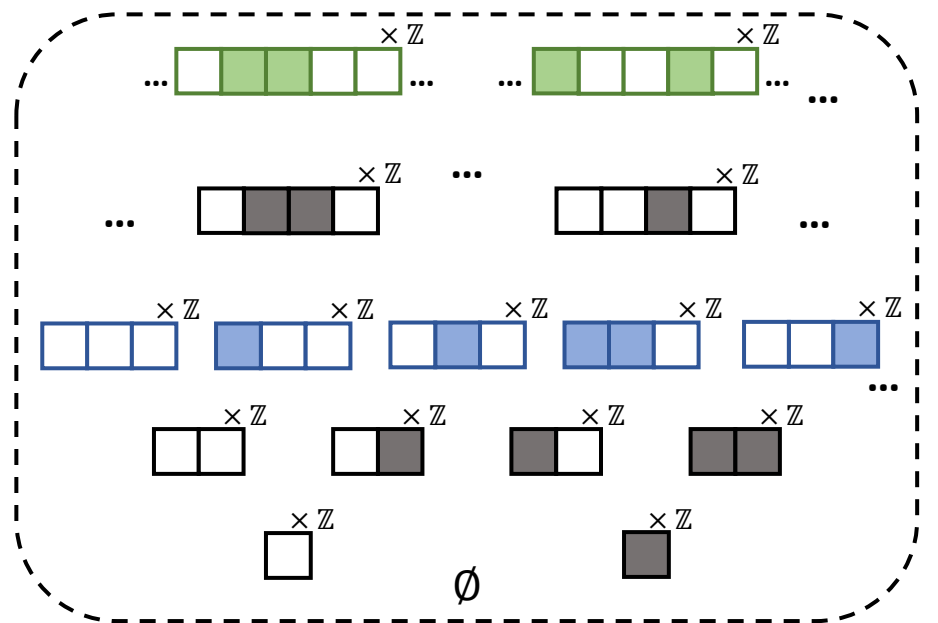


Fine as right Kan extension



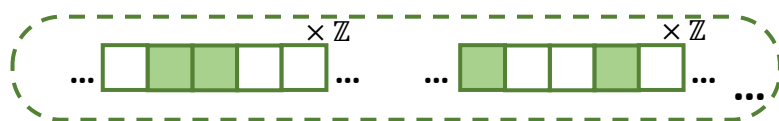
- $\bar{\Delta}$ must act **at most** like Δ over Conf
- Monotony of $\bar{\Delta}$ extends Δ for Sconf
- Implies that $|(\bar{\Delta} \circ J)(c)| = \mathbb{Z}$

Fine as right Kan extension



Sconf

J

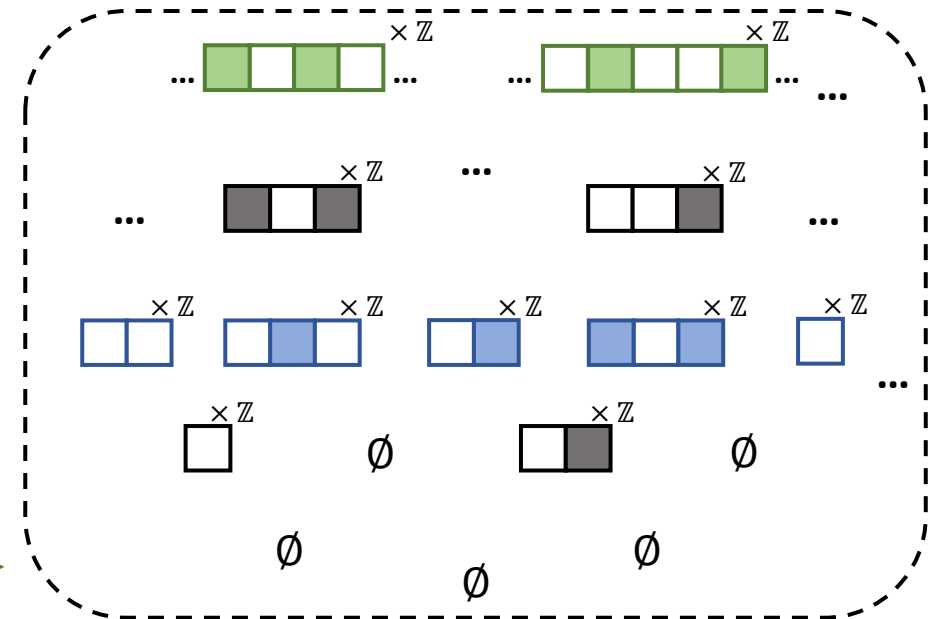


Conf

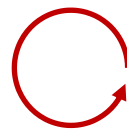
Δ

- $\bar{\Delta}$ must act **like** Δ over Conf
- Monotony of $\bar{\Delta}$ extends Δ for Sconf
- Implies that $|(\bar{\Delta} \circ J)(c)| = \mathbb{Z}$

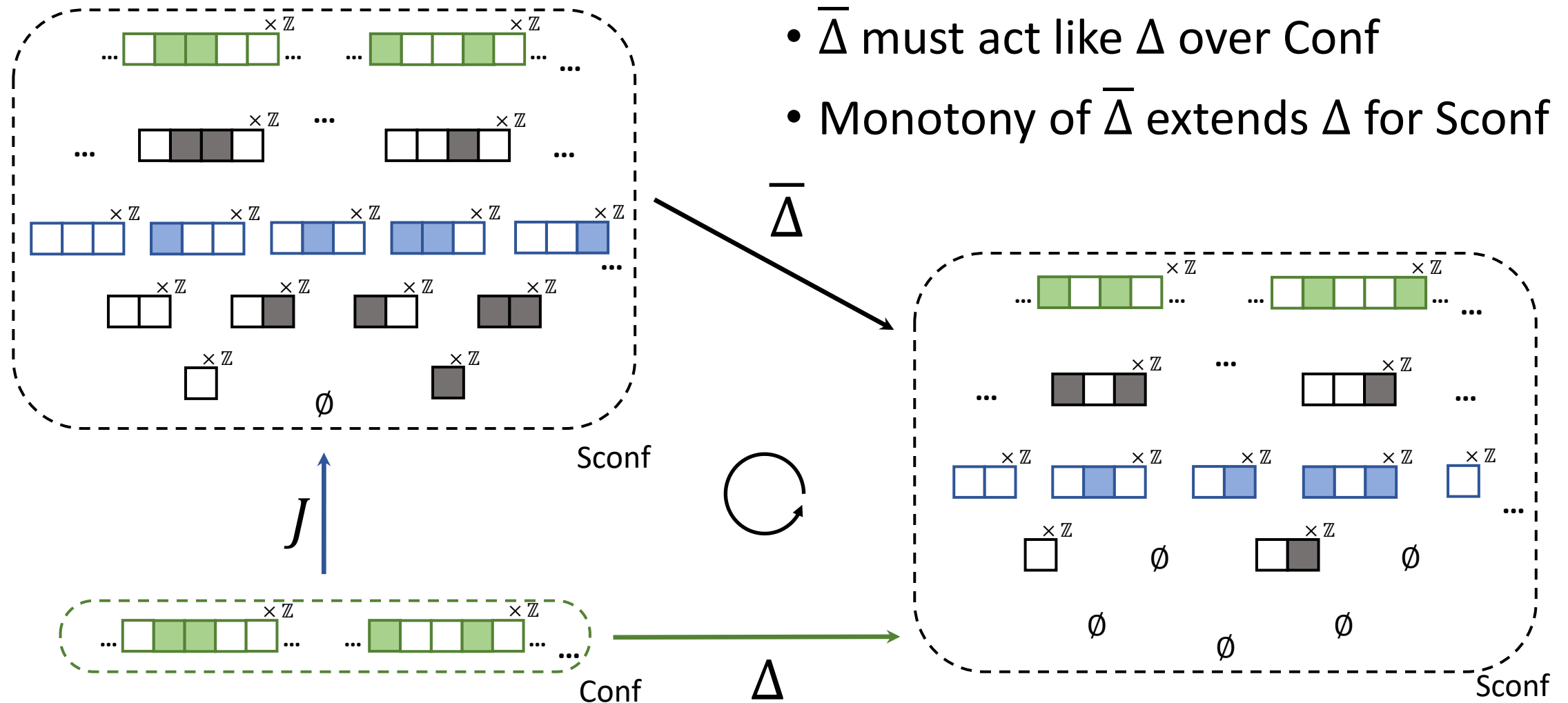
$\bar{\Delta}$



Sconf

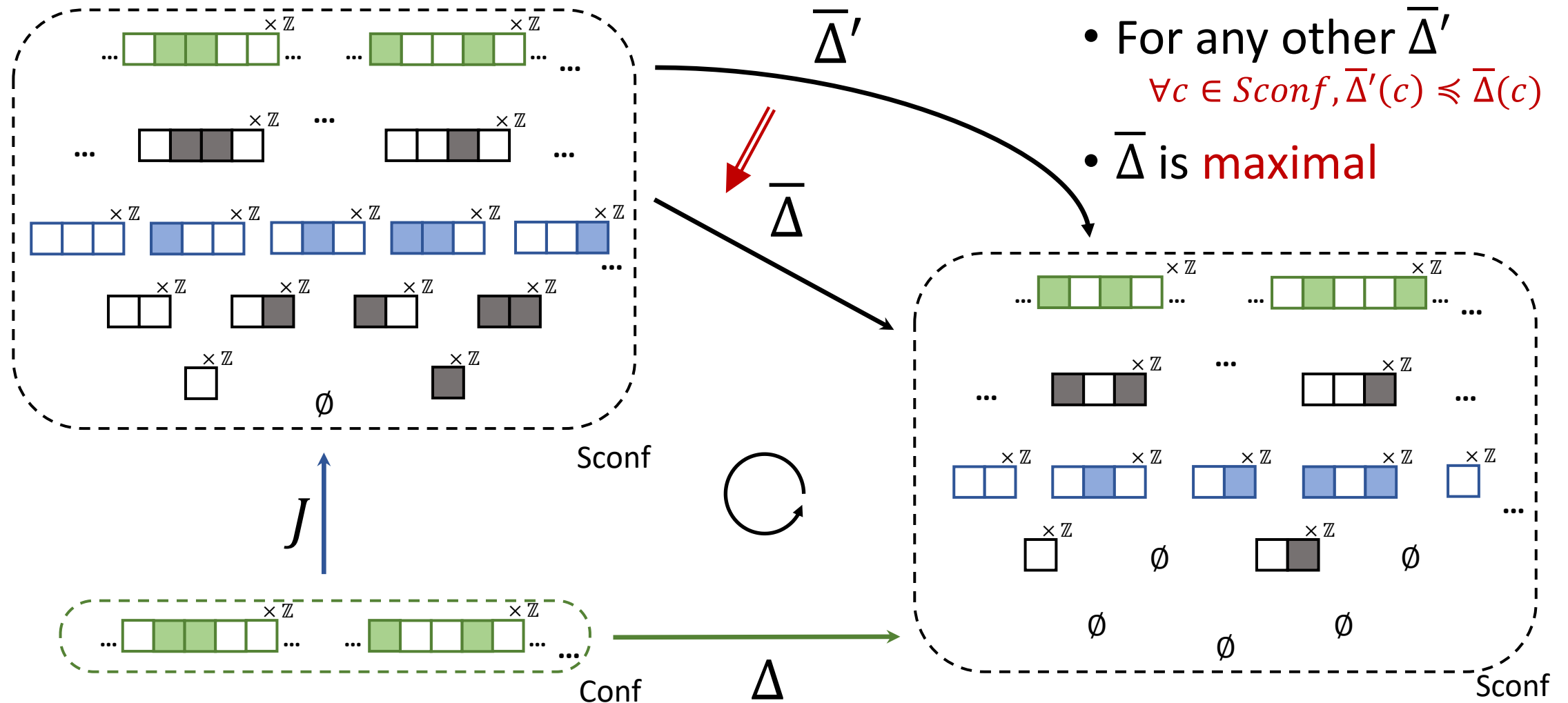


Fine as right Kan extension



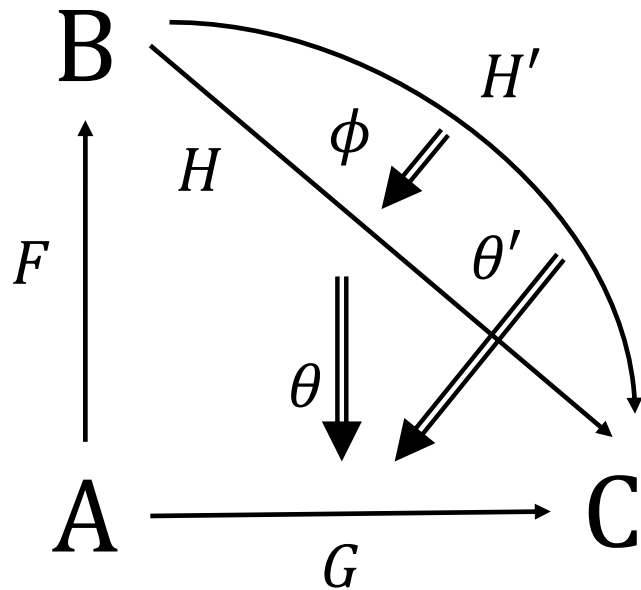
- $\bar{\Delta}$ must act like Δ over Conf
- Monotony of $\bar{\Delta}$ extends Δ for Sconf

Fine as right Kan extension



(Right) Kan Extensions

- (Right) Kan Extension of G along F is : $\langle H, \theta \rangle$



- $\theta: G \Rightarrow H \circ F$

- Universal :

- Given $\langle H', \theta' \rangle$, exists unique ϕ s.t.

- $\theta' = \theta \cdot (\phi \circ F)$

- H « maximal » and unique

Fine as Lan of Ran

- Fine obtained from global transition function
- Global transition is an infinite object
- Get fine extension from local rules ?
 - Computable with « bottom up » procedure

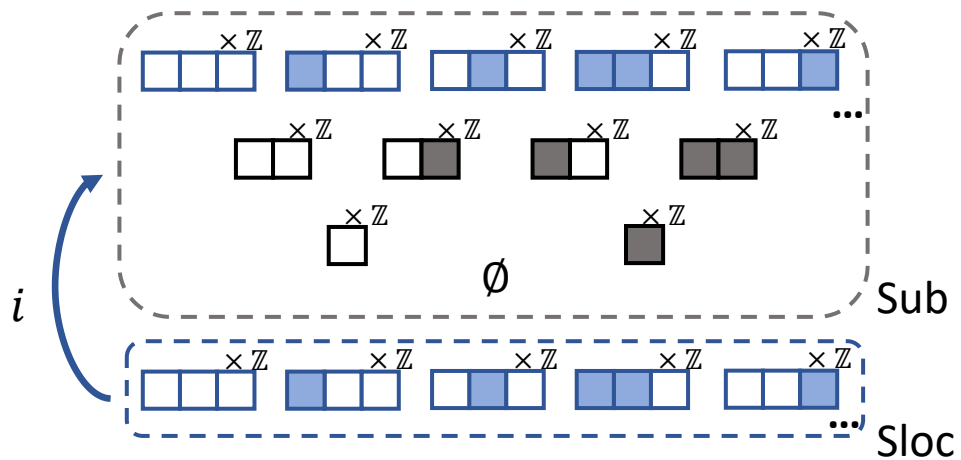
Fine as Lan of Ran

- Fine obtained from global transition function
- Global transition is an infinite object
- Get fine extension from local rules ?
 - Computable with « bottom up » procedure
 - Yes we Kan !

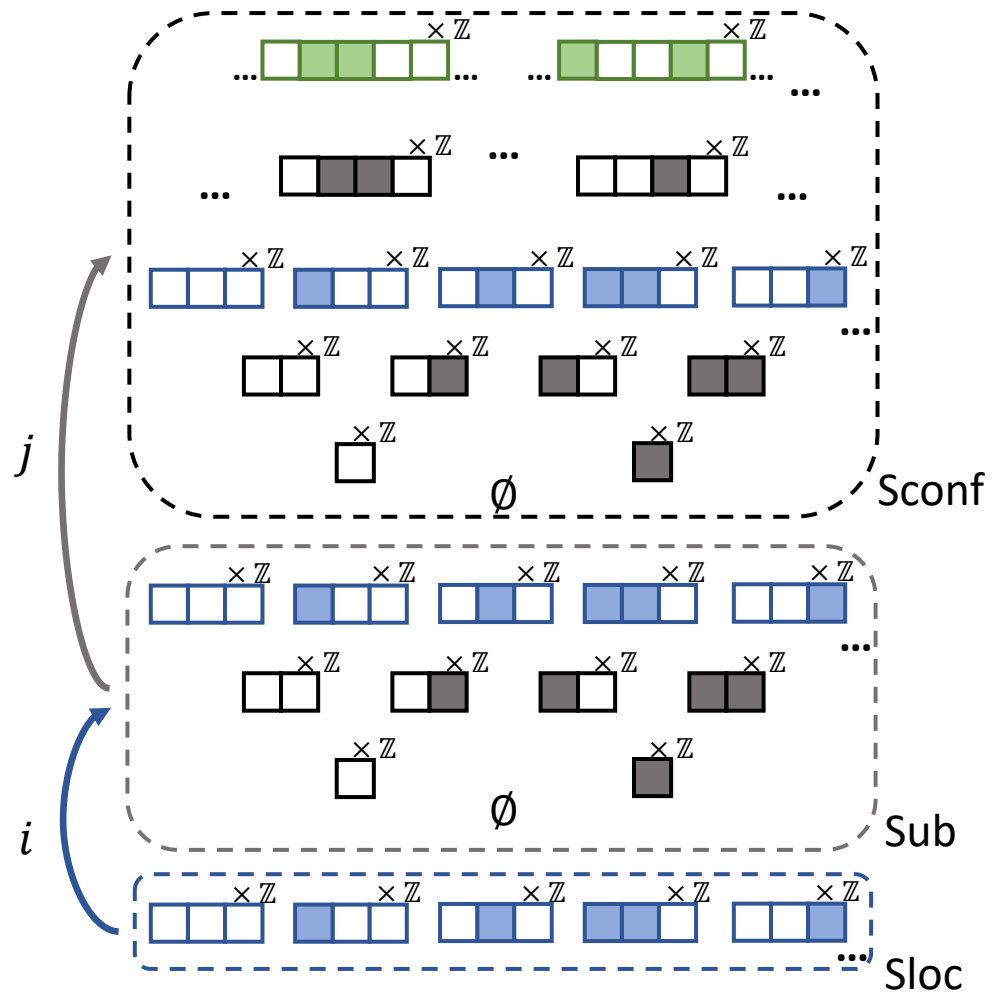
Fine as Lan of Ran

- Sub-local configurations :

$$Sub = \bigcup_{p \in \mathbb{Z}, S \subseteq \mathbb{N}} \{p\} \times Q^{p+S}$$



Fine as Lan of Ran

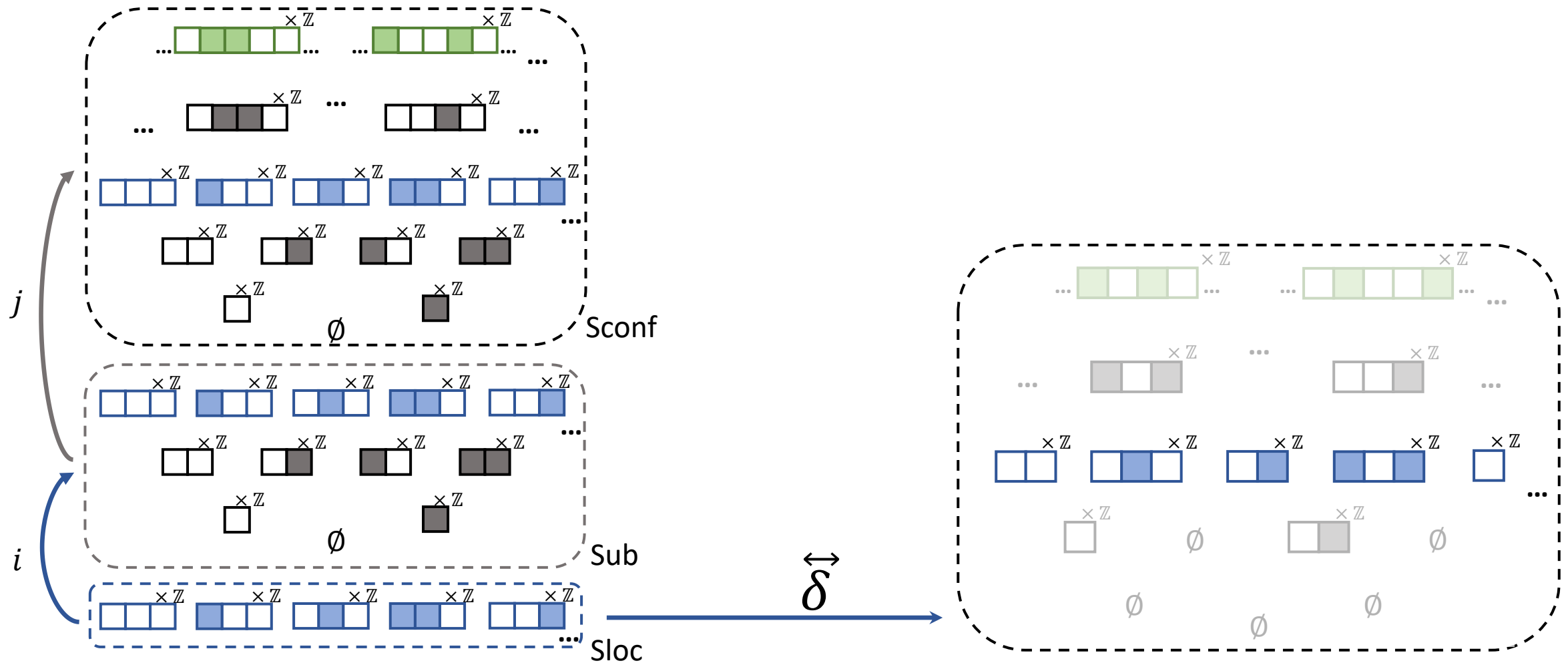


- Sub-local configurations :

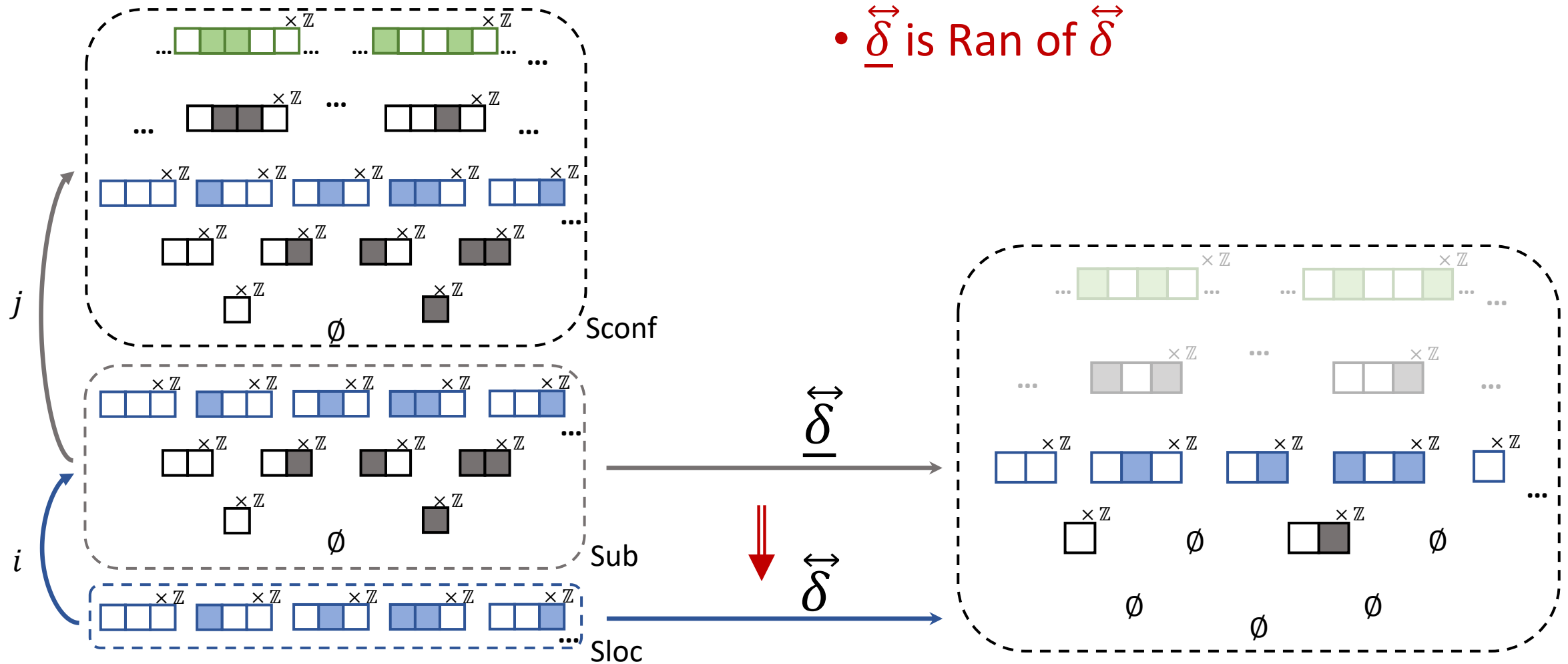
$$Sub = \bigcup_{p \in \mathbb{Z}, S \subseteq N} \{p\} \times Q^{p+S}$$

- $i: Sloc \rightarrow Sub$ inclusion
- $j: Sub \rightarrow Sconf := \pi_2$

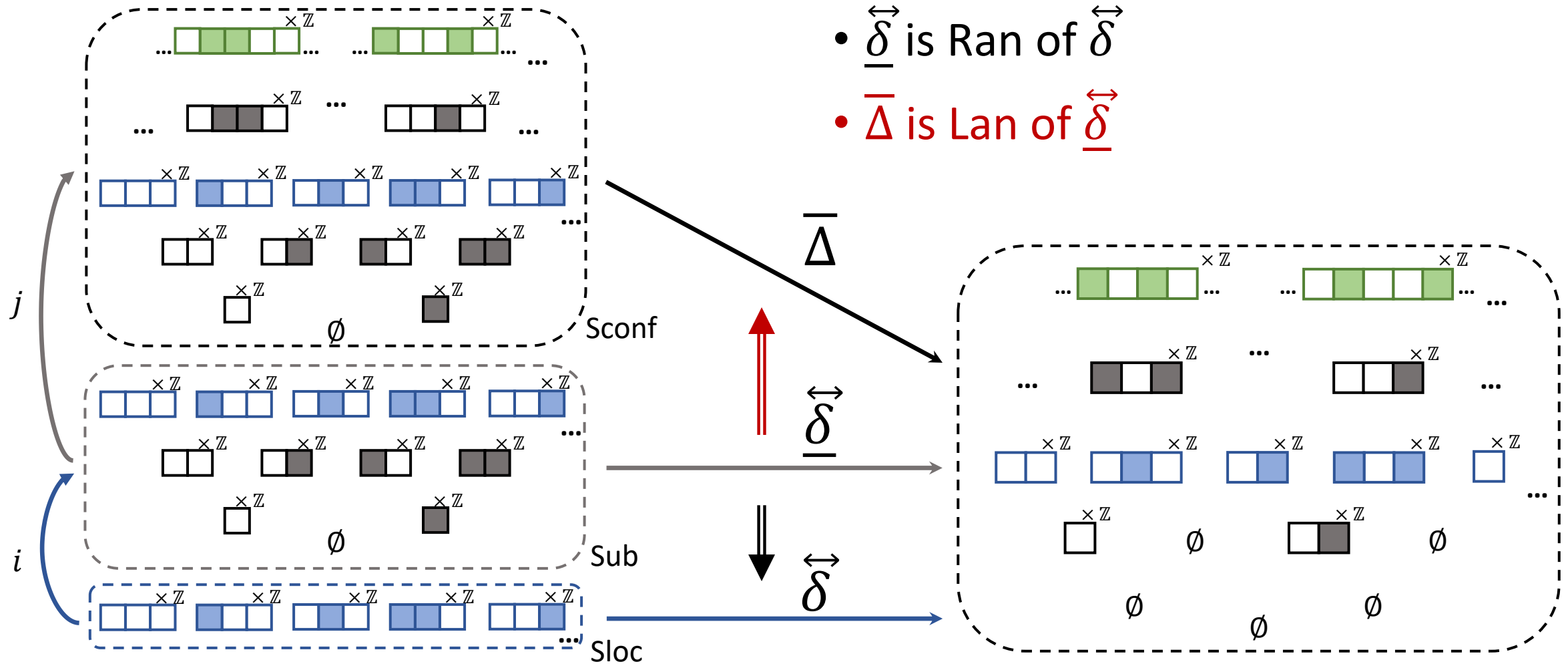
Fine as Lan of Ran



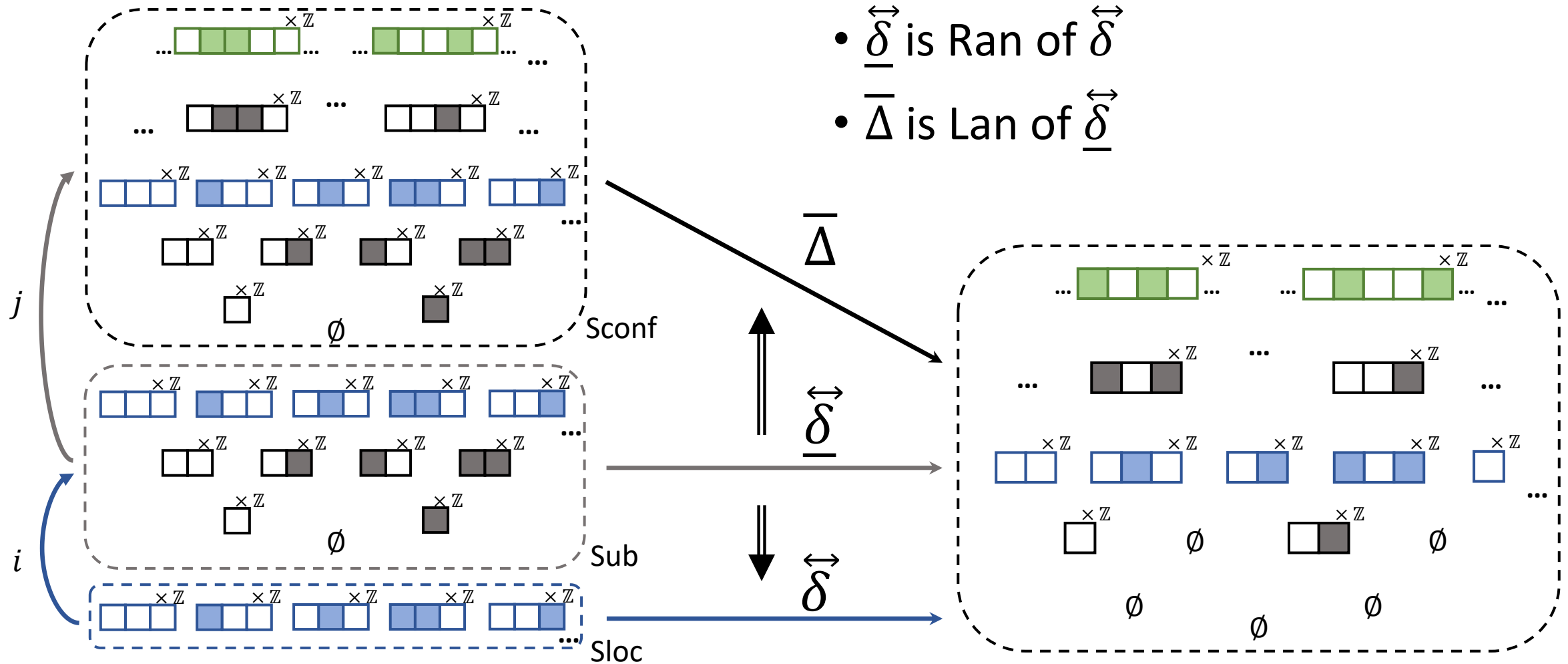
Fine as Lan of Ran



Fine as Lan of Ran



Fine as Lan of Ran



- $\overline{\delta}$ is Ran of $\overleftrightarrow{\delta}$
- $\overline{\Delta}$ is Lan of $\overleftrightarrow{\delta}$

Summary

- Studying local vs global relationship
 - Kan extension good tool
 - Multiple ways to extend
 - Describes extensions using intermediary steps

- Cellular automata to introduce categorical concepts
 - Categories, functors, natural transformations
 - Kan extensions

Perspectives

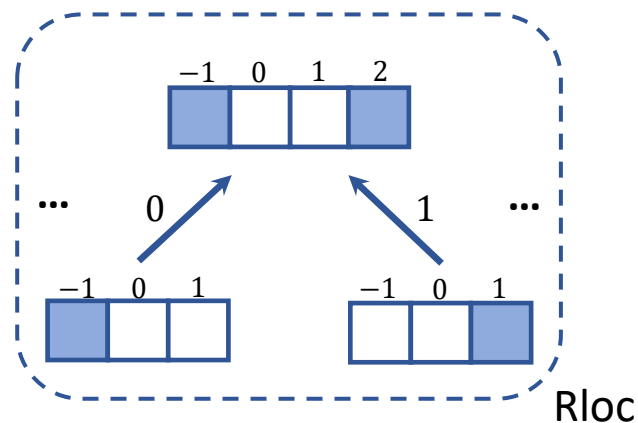
- Non-regular CA :
 - Different behavior at different position
 - Shifted local transition function \rightarrow any function

$$\overset{\leftrightarrow}{\delta} \left(\begin{array}{|c|c|c|} \hline 4 & 5 & 6 \\ \hline \blacksquare & \square & \square \\ \hline \end{array} \right) = \begin{array}{|c|} \hline 5 \\ \hline \blacksquare \\ \hline \end{array}$$

$$\overset{\leftrightarrow}{\delta} \left(\begin{array}{|c|c|c|} \hline 6 & 7 & 8 \\ \hline \blacksquare & \square & \square \\ \hline \end{array} \right) = \begin{array}{|c|} \hline 7 \\ \hline \square \\ \hline \end{array}$$

Perspectives

- Non-regular CA
- Consider only local configuration ?
 - Sconf category, shifts are inclusions
 - Computation up to iso \rightarrow shift-equivalent automata
 - Local configurations : Rloc for relative positioning



Perspectives

- Non-regular CA
- Consider only local configuration ?
 - Shift-equivalent automata



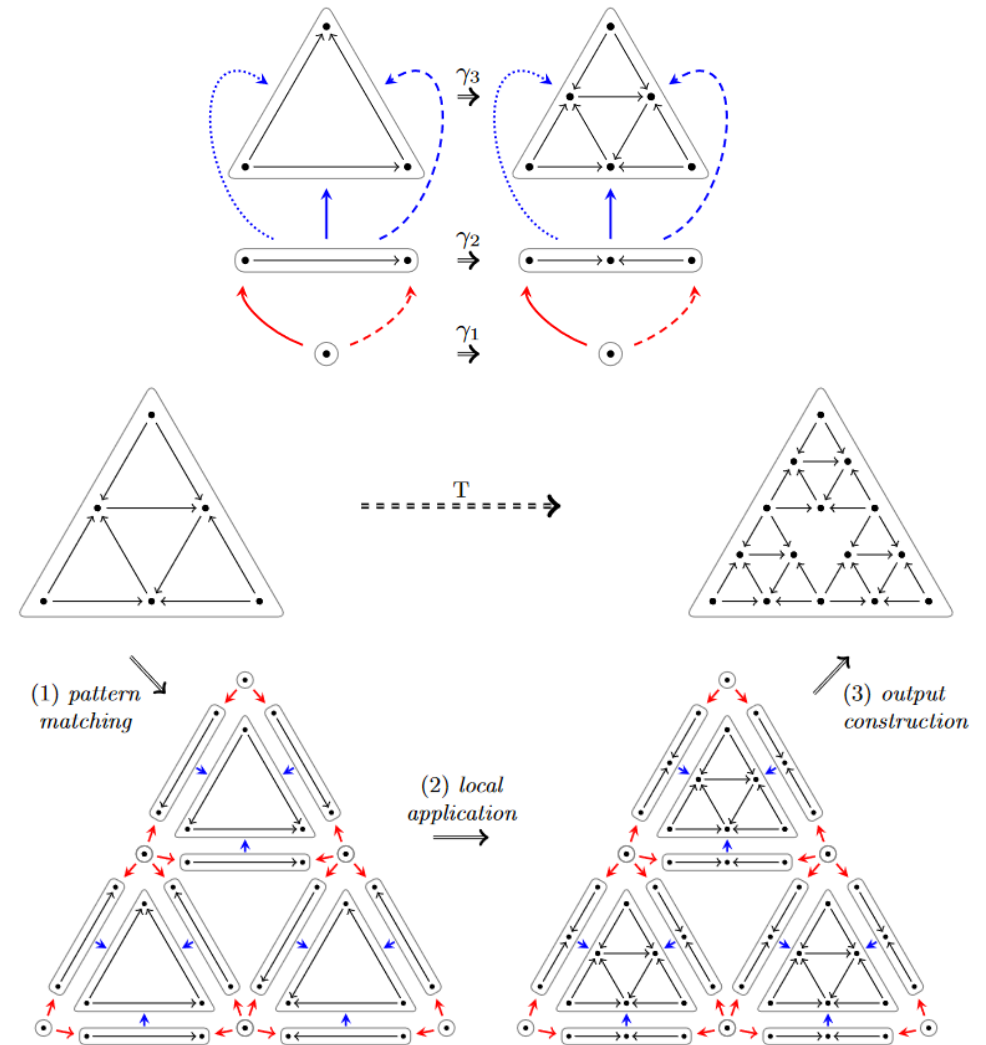
Link with Curtis–Hedlund–Lyndon ?

Perspectives

- Non-regular CA
- Consider only local configuration
 - Shift-equivalent automata
- Other data structures

Perspectives

- Non-regular CA
- Consider only local configuration
 - Shift-equivalent automata
- Other data structures
 - Global Transformations
 - Words, Graphs, Trees ...
 - Possibility to change the space



Perspectives

- Non-regular CA
- Consider only local configuration
 - Shift-equivalent automata
- Other data structures
- Kan extensions here are pointwise !
 - Computable