





FACTORIZATION OF DISCRETE DYNAMICAL SYSTEMS

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DDS and Complex behaviours

Equations over DDS



Abstractions over DDS

- Over the cardinality of the set of states
- Over the asymptotic behaviour
- Over the transient behaviour

The Cyclic Abstraction

- The basic case (EnumSOBFID Problem)
- Contractions Steps
- W-th roots

Conclusions and Perspectives

DISCRETE DYNAMICAL SYSTEMS

• A DDS is a pair < X, f >, where X is the set of states and f is the next state map.

 $f: X \to X$ $x \mapsto f(x)$

• Any DDS can be identified with its dynamics graph $G \equiv (V, E)$ where V = X and $E = \{(\alpha, \beta) \in V \times V, f(\alpha) = \beta\}$.



DISCRETE DYNAMICAL SYSTEMS

- Complex dynamics in Discrete Dynamical Systems
- Simulations or Verification are in general unfeasible







EQUATIONS OVER DDS

- Polynomial equations to translate hypothesis on complex dynamics
- Solutions provide the validation of the hypothesis



A COMMUTATIVE SEMIRING

SUM

< X, f > +< Y, g > = < X \sqcup Y, f \sqcup g >

$$f \sqcup g : X \sqcup Y \to X \sqcup Y$$

$$\forall (\alpha, i) \in X \sqcup Y \quad (f \sqcup g)(\alpha, i) = \begin{cases} (f(\alpha), i) & \text{if } \alpha \in X \land i = 0\\ (g(\alpha), i) & \text{if } \alpha \in Y \land i = 1 \end{cases}$$



PRODUCT

$$<$$
 X, f > \times $<$ Y, g > = $<$ X \times Y, f \times g >

 $(f \times g)(\alpha, \beta) = (f(\alpha), g(\beta))$



HYPOTHESIS VALIDATION

$$a_1 \cdot x_1^{w_1} + a_2 \cdot x_2^{w_2} + \dots + a_s \cdot x_s^{w_s} = C$$

The equation admits a solution \rightarrow the hypothesis is verified

(Dennunzio, Dorigatti, Formenti, Manzoni and Porreca, 2018)

It is proved that:

- the set of DDS equipped with these operations of sum and product is a **commutative semiring**
- the problem of finding a solution for $P(x_1, ..., x_s) = Q(x_1, ..., x_s)$ is **undecidable**
- With a constant term, the complexity is beyond NP

THE MAIN IDEA



ABSTRACTION OVER THE CARDINALITY OF STATES



$$\langle X_{1}, f_{1} \rangle x_{1}^{w_{1}} + \langle X_{2}, f_{2} \rangle x_{2}^{w_{2}} + \dots + \langle X_{s}, f_{s} \rangle x_{s}^{w_{s}} = \langle \Upsilon, g \rangle$$

$$| X_{1} | \bar{x}_{1}^{w_{1}} + | X_{2} | \bar{x}_{2}^{w_{2}} + \dots + | X_{s} | \bar{x}_{s}^{w_{s}} = | \Upsilon |$$

- In the this abstraction, coefficients, variables and known term are natural numbers.
- \bar{x}_i is the cardinality of the set of states in the variable.

ABSTRACTION OVER THE ASYMPTOTIC BEHAVIOUR



In the decidable abstraction, coefficients, variables and known term are cycles.

THE NOTATION

Given $A \equiv \langle X, f \rangle$ and Π its set of periodic points, we denote \dot{A} the DDS induced by Π .



An example...



Figure: $(C_1^1 \oplus C_2^2 \oplus C_3^1)$.

OPERATIONS OVER CYCLES

 $\dot{A} \oplus \dot{B}$

 $\dot{A} \odot \dot{B}$

$$\bigoplus_{i=1}^{K_A} C_{p_{Ai}}^{n_{Ai}} \oplus \bigoplus_{j=1}^{K_B} C_{p_{Bj}}^{n_{Bj}} = C_{p_{A1}}^{n_{A1}} \oplus \dots \oplus C_{p_{AK_A}}^{n_{AK_A}} \oplus C_{p_{B1}}^{n_{B1}} \oplus \dots \oplus C_{p_{BK_B}}^{n_{BK_B}}$$

$$\bigoplus_{i=1}^{K_A} C_{p_{Ai}}^{n_{Ai}} \odot \bigoplus_{j=1}^{K_B} C_{p_{Bj}}^{n_{Bj}} = \bigoplus_{i=1}^{K_A} \bigoplus_{j=1}^{K_B} C_{p_{Ai}}^{n_{Ai}} \odot C_{p_{Bj}}^{n_{Bj}} = \bigoplus_{i=1}^{K_A} \bigoplus_{j=1}^{K_B} C_{\operatorname{lcm}(p_{Ai}, p_{Bj})}^{n_{Ai} \cdot n_{Bj} \cdot \operatorname{gcd}(p_{Ai}, p_{Bj})}$$

Solving Equations on Discrete Dynamical Systems - Dennunzio, Formenti, Margara, Montmirail, Riva. (CIBB 2019)

FROM THE ABSTRACTION TO A BASIC CASE...

THE MDD-BASED PIPELINE

$$\left(\bigoplus_{i=1}^{K_1} C_{p_{1i}}^{n_{1i}} \odot \dot{x}_1^{w_1}\right) \oplus \left(\bigoplus_{i=1}^{K_2} C_{p_{2i}}^{n_{2i}} \odot \dot{x}_2^{w_2}\right) \oplus \cdots \oplus \left(\bigoplus_{i=1}^{K_s} C_{p_{si}}^{n_{si}} \odot \dot{x}_s^{w_s}\right) = \bigoplus_{j=1}^m C_{p_j}^{n_j}$$

Necessary Equations

Identification and resolution of the basic equations.

Identification of the solutions

Intersections and Unions to study the solutions of each contraction step.

Explorations of the feasible solutions space.

Contractions Steps

Algorithmic technique to compute the roots over DDSs. **W-th Roots**

MDDs Boost Equation Solving on Discrete Dynamical Systems - Formenti, Régin, Riva. (CPAIOR 2021)

THE BASIC EQUATION $C_p^1 \odot \dot{X} = C_q^n$



According to the product rule: $C_p^1 \odot C_z^y = C_{lcm(p,z)}^{y \cdot \text{gcd}(p,z)}$ A divisor r of q is in the coins system iff:

$$r \le n$$
 and $gcd\left(p, \frac{q}{p} \cdot r\right) = r$ and $lcm\left(p, \frac{q}{p} \cdot r\right) = q$

SB-MDDS (SYMMETRY BREAKING)



THE MDD-BASED PIPELINE

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W-th Roots

MDDS & CONTRACTIONS STEPS

$$CS = \times_{j=1}^{m} CS_j$$

For each node of a level z, the value k is a possible label of an outgoing arc if

$$M_{p_z, p_j, \frac{k}{n_z}}$$

has solution.



For each monomial there is one level into the structure + one level for the final node.

The structure represents the generation of the $C_{p_j}^{n_j}$ cycles.

EXAMPLE

$$C_4^1 \odot \dot{X} \oplus C_2^1 \odot \dot{X} = C_2^4 \oplus C_4^4 \oplus C_6^7 \oplus C_{12}^7$$

- 33 Basic equations
- 27 Necessary equations

$$C_{2}^{1} \odot \dot{X} = C_{4}^{1} \qquad C_{2}^{1} \odot \dot{X} = C_{12}^{1} \qquad C_{2}^{1} \odot \dot{X} = C_{12}^{5}$$
$$C_{2}^{1} \odot \dot{X} = C_{4}^{3} \qquad C_{2}^{1} \odot \dot{X} = C_{12}^{3} \qquad C_{2}^{1} \odot \dot{X} = C_{12}^{7}$$

Contractions steps CS



THE MDD-BASED PIPELINE

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SOLVE A CONTRACTIONS STEP



INTERSECTION OF SB-MDDS



THE MDD-BASED PIPELINE

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N-th Roots

W-ROOTS OVER CYCLES

$$\dot{x}^{w} = C_{p_{1}}^{m_{1}} \bigoplus C_{p_{2}}^{m_{2}} \bigoplus \cdots \bigoplus C_{p_{h}}^{m_{h}} \qquad \stackrel{\bigvee}{\longrightarrow} \qquad \dot{x} = C_{q_{1}}^{s_{1}} \bigoplus C_{q_{2}}^{s_{2}} \bigoplus \cdots \bigoplus C_{q_{l}}^{s_{l}}$$
$$(0 < p_{1} < p_{2} < \dots < p_{h})$$

Consider that some components $C_{q_1}^{s_1} \oplus \cdots \oplus C_{q_i}^{s_i}$ of \dot{x} have been already computed (with 2 < i < l). $(C_{q_1}^{s_1} \oplus \cdots \oplus C_{q_i}^{s_i})^w = C_{p'_1}^{m'_1} \oplus C_{p'_2}^{m'_2} \oplus \cdots \oplus C_{p'_t}^{m'_t}$ with $i \leq t \leq h$. It holds that q_{i+1} is $\min\{p_j \in \{p_1, \dots, p_h\} | p_j > q_i \land ((p_j = p'_z \land m'_z < m_j) \text{ with } z \in \{1, \dots, t\} \lor p_j \notin \{p'_1, \dots, p'_t\})\}$

$$s_{i+1} \text{ integer solution of } \sum_{\substack{k_1+k_2+\dots+k_{i+1}=w\\0\le k_1,k_2,\dots,k_{i+1}\le w\\l(q_1,\dots,q_{i+1},k_1,\dots,k_{i+1})=q_{i+1}}} {\binom{w}{k_1,k_2,\dots,k_{i+1}}} \prod_{\substack{t=1\\k_t\neq 0}}^{i+1} q_t^{k_t-1} s_t^{k_t} \prod_{\substack{t=2\\k_t\neq 0}}^{i+1} \gcd(l(q_1,\dots,q_{t-1},k_1,\dots,k_{t-1}),q_t) = m_j$$

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THE MDD-BASED PIPELINE

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ABSTRACTION OVER THE TRANSIENT BEHAVIOUR



Considering the abstraction over cycles, we showed that to solve the abstraction it is necessary to solve two basic cases:

$$\alpha \cdot X = c$$

$$X^w = c$$

Also if we consider the transient parts involved in the initial equation we are interested in these simple cases.

 $\alpha \cdot X = c$

with α , *c* that are DDS and X with a possible cyclic behaviour.





OUR IDEA

Joint work with F. Doré and E. Formenti



CONCLUSIONS



TWO DIFFERENT ABSTRACTIONS SOLVED + ONE WORKING IN PROGRESS



A NEW **MDD APPROACH** COMPACT AND FASTER



A COMPLETE **PIPELINE** TO SOLVE GENERIC EQUATIONS OVER CYCLES



A NEW ALGORITHM TO COMPUTE **W-ROOTS** OVER THE LONG-TERM BEHAVIOUR

FUTURE DEVELOPMENTS

Parallel solutions computation

()

Improve the SB-Cartesian intersection

Test the approach over real biological networks

The abstraction over the transient parts of DDS

Interaction with different abstractions



THANKS FOR YOUR ATTENTION

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