

Isometries of the hypercube: a tool for Boolean regulatory networks analysis

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Introduction

Team MABioS

Biological and medical motivation: to develop tools for the analysis of regulatory networks controlling the cellular processes

- ↪ To get a better understanding of these processes
- ↪ To understand and predict the impact of given perturbations, such as disease-induced perturbations

Necessity of in-depth understanding of mathematical objects we use: Finite Dynamical Systems

Outline

- 1 Isometries of the hypercube
- 2 Boolean Finite Dynamical Systems (FDS)
- 3 Problematic and some runways
- 4 Action of the group $\Gamma(\mathcal{H}_n)$ of isometries of the hypercube on Boolean FDS
- 5 Transforming and classifying Boolean FDS
- 6 Some applications
 - Application to acyclic RG - Robert's theorem
 - Application to families of motifs
 - Application to the "negative Thomas's rule"

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Isometries of the hypercube

Geometrical point of view:

↪ Hypercube embedded in n dimensional euclidian space \mathbb{R}^n

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↪ Hypercube embedded in n dimensional euclidian space \mathbb{R}^n



Isometries of $\mathcal{H}_n = [0, 1]^n \subset \mathbb{R}^n$

Form a group $\Gamma(\mathcal{H}_n)$ whose elements are composed of

- ↪ a permutation of axes
- ↪ hyperplane symmetries exchanging parallel hyperfaces



From geometrical to symbolic point of view

Isometries of $\mathcal{H}_n = [0, 1]^n$ are isometries of $\{0, 1\}^n$

Given $f \in \Gamma(\mathcal{H}_n)$ and $x = (x_1, \dots, x_n) \in \{0, 1\}^n$,

$f(x) = (x_{\sigma^{-1}(1)}^{\varepsilon_1}, \dots, x_{\sigma^{-1}(n)}^{\varepsilon_n})$ (where $a^{-1} = 1 - a$, for $a \in \{0, 1\}$)

$\hookrightarrow \sigma$ codes for the permutation of axes

$\hookrightarrow (\varepsilon_1, \dots, \varepsilon_n) \in \{-1, +1\}^n$ codes for the hyperplane symmetries



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Boolean FDS

Boolean FDS: a map $S : X = \{0, 1\}^n \rightarrow X$

n underlying components g_1, \dots, g_n

↪ "processors"

↪ "genes"

Associated dynamics

$$S : X = \{0, 1\}^n \rightarrow X$$

States: elements $x = (x_1, \dots, x_n)$ of X

- Synchronous dynamics: iteration of S
 x has one successor $S(x)$ (deterministic)
- (Fully) asynchronous dynamics
one coordinate changes at a time (underlying delays,
non-deterministic)

State Transition Graphs (STG)

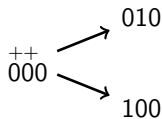
STG give successors of the states

- Synchronous STG
vertices = states x , edges give the successor $S(x)$
- Asynchronous STG
vertices = states x , edges give $Upd(x)$ successors

$$S(000) = 110$$

000 \longrightarrow 110

In the
synchronous
STG



In the
asynchronous
STG

Regulatory Graph associated to S

g_1, g_2, \dots, g_n are regulated through the dynamics:
at state x , coordinate $x_k =$ level of g_k

Given $x = (x_1, \dots, x_n)$ and $S(x) = (y_1, \dots, y_n)$

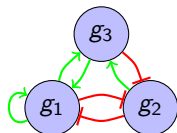
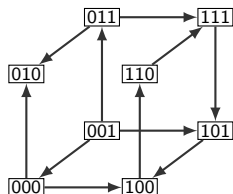
- ↪ if switching x_i implies that y_j switches in the same sense, g_i activates g_j (locally)
- ↪ if switching x_i implies that y_j switches in the other sense, g_i inhibites g_j (locally)

Regulatory Graph $\mathcal{RG}(S)$:

Obtained by superimposing local Regulatory Graphs
Signs of interactions may be undetermined

Example: S , asynchronous STG, Regulatory Graph (RG)

x	$S(x)$
$\begin{matrix} + & + \\ 0 & 0 & 0 \end{matrix}$	1 1 0
$\begin{matrix} + & + & - \\ 0 & 0 & 1 \end{matrix}$	1 1 0
$\begin{matrix} 0 & 1 & 0 \end{matrix}$	0 1 0
$\begin{matrix} 1 & 0 & 0 \\ + \end{matrix}$	1 1 0
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$\begin{matrix} 1 & 1 & 1 \\ - \end{matrix}$	1 0 1



- ↪ Same information in S and in the asynchronous STG
- ↪ Information lost in the Regulatory Graph

Logical formalism

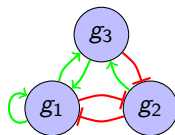
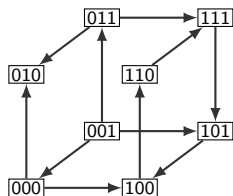
Logical formulas

Give necessary and sufficient conditions for the level of g_i to become equal to 1 under S

- ↪ In a disjunctive normal form
- ↪ Involving only regulators

Example: S , asynchronous STG, RG, logical formulas

x	$S(x)$
$\begin{matrix} + & + \\ 0 & 0 & 0 \end{matrix}$	1 1 0
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$\Leftrightarrow S(x)_1 = 1$ iff $(x_1 = 1) \vee (x_2 = 0) \vee (x_3 = 1)$

$\Leftrightarrow S(x)_2 = 1$ iff $(x_1 = 0) \vee (x_3 = 0)$

$\Leftrightarrow S(x)_3 = 1$ iff $(x_2 = 1) \wedge (x_3 = 1)$

Outline

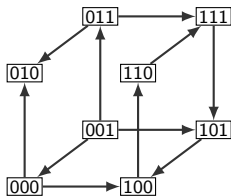
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Problematic

Main problematic:
determination of the attractors of the asynchronous STG

Attractors: terminal strongly connected components of the STG

- Stable states: attractors reduced to a single state
- Complex attractors: attractors with at least 2 states



Runways

Difficulty: combinatorial explosion of STG

Some runways:

- To reduce the number of components
- To find links between the dynamics and the Regulatory Graph (Thomas's rules)
- To focus on circuits (an acyclic RG implies a degenerated dynamics - F.Roberts)
- To analyze the functionality of circuits (isolated: positive 2 stable states, negative one complex attractor)
- To focus on more complex motifs and their functionality
- To use probabilistic methods (Monte Carlo)
- Other classical mathematical approaches:
to transform, to classify

Runways

Difficulty: combinatorial explosion of STG

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(no circuit implies degenerated dynamics - F.Roberts)
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Action of the group $\Gamma(\mathcal{H}_n)$ of isometries of the hypercube on asynchronous STG

A natural idea:

Asynchronous STG are embedded in the hypercube

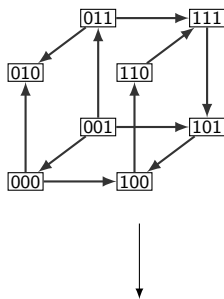
- Isometric STG introduced by dynamicist Leon Glass
- Recent works of Franck Delaplace, Elisa Tonello

Particular interest on the combinatorial tools of group action theory (Burnside formula for counting of "configurations")

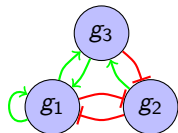
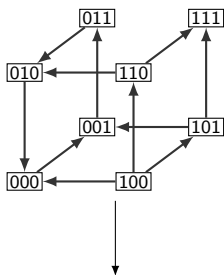
Jean Fabre-Monplaisir, Brigitte Mossé, and Elisabeth Remy. Isometries of the hypercube: a tool for boolean regulatory networks analysis. Physica D: Nonlinear Phenomena, 2021 (in press).

Action of the group $\Gamma(\mathcal{H}_n)$ on Boolean FDS giving "isometric" dynamics

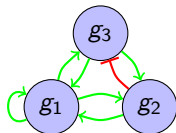
S Boolean FDS, f isometry of the hypercube



S becomes $f \circ S \circ f^{-1}$



Same topology, signs of circuits



For instance the central symmetry switches *vee* and *wedge* in all formulas

Some remarks

- Isometric is more than isomorphic (in the sense of graph theory).
- Two Boolean FDS such that their asynchronous graphs involve all the edges of \mathcal{H}_n are isometric iff they are isomorphic.

Idea of rigidity...

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To transform and to classify

Main ideas:

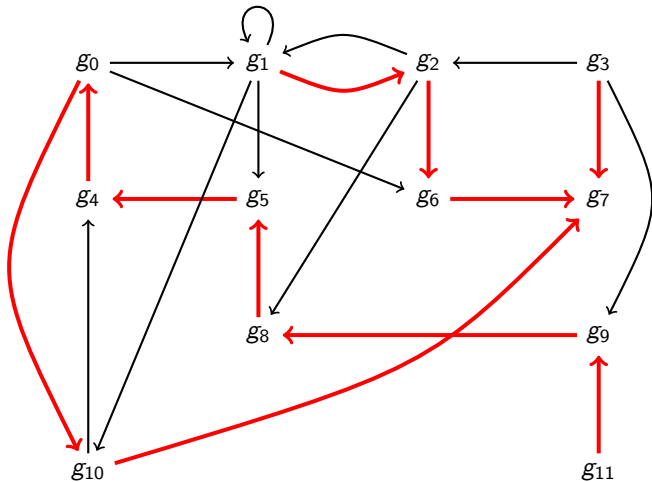
- ↪ To define classes gathering all isometric Boolean FDS
- ↪ To choose in each class a representative - the most appropriate
- ↪ To prioritise activations in this representative for mathematical questions

Major benefit of activations: rewriting

Typically, in the case of a positive circuit with only activations, S is simply the shift $S(x_1, \dots, x_n) = (x_n, x_1, \dots, x_{n-1})$

A key tool for the choice of representative

A way of identifying subgraphs of a RG, on which it is possible to choose the signs of the interactions after the action of some isometry



The red subgraph is "tree-supported"

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About Robert's theorem on acyclic RG

Robert's theorem

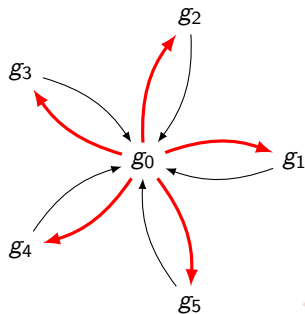
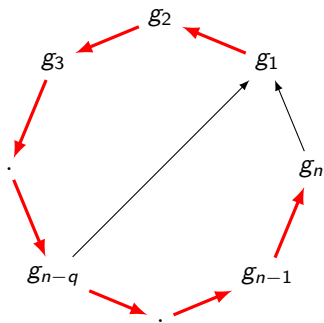
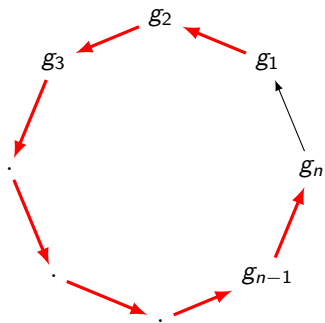
If $\mathcal{RG}(S)$ is acyclic and admits r genes without regulator g_1, \dots, g_r , then for each input the lonely related attractor in the asynchronous STG is a stable state.

Robert's proof via isometries

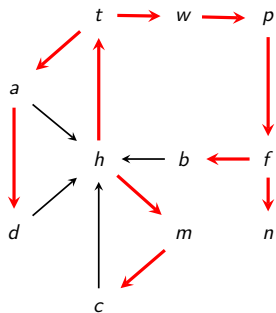
- Consider an isometry f reduced to a permutation σ of axes producing a topological sorting of the RG.
- Under f , the adjacency matrix $\mathcal{M}(S)$ of the RG is conjugated in $P_\sigma \mathcal{M}(S) P_\sigma^t =$ a nilpotent upper triangular matrix.
Consequence: $\mathcal{M}(S)$ is nilpotent.
- A basic inequality gives the proof: for x and y with same input

$$d(S^n(x), S^n(y)) \leq [\mathcal{M}(S)^t]^n d(x, y) = (0, \dots, 0)^t$$

Special motifs: circuits, chorded circuits, flower-graphs



Special motifs: Hub-graphs



Three types

1 stable state, 2 stable states, 1 cyclic attractor

Interpretation of the types

in terms of concurrences /cooperations of regulators of the hub

The negative Thomas's rule

New proof of this rule: "Given $S : X \rightarrow X$ a boolean FDS such that the asynchronous dynamics of S displays a cyclic attractor, then the Regulatory Graph of S contains a negative circuit."

Sketch of proof (by contraposition)

- Let $S : X \rightarrow X$ be a Boolean FDS such that all the interactions of $\mathcal{RG}(S)$ are activations (colaborative FDS). Then for any state x , there exists a stable state y such that $x \rightsquigarrow y$ in $\mathcal{G}_a(S)$.

- Cooperative system -

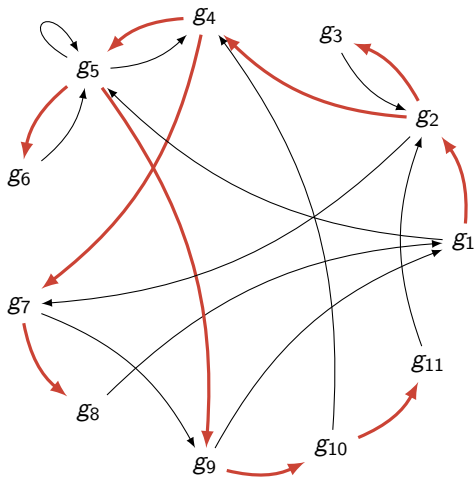
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- Let $S : X \rightarrow X$ be a Boolean FDS whose regulatory graph $\mathcal{RG}(S)$ is strongly connected, all the signs of the interactions are determined, and all the circuits are positive. There exists an isometry $f \in \Gamma(\mathcal{H}_n)$ such that all the interactions of $\mathcal{RG}(S)$ become activations under the conjugation by f .

- Key tool -



The negative Thomas's rule

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- A topological sorting of the graph of the strongly connected components of $\mathcal{RG}(S)$ gives the conclusion.

Thanks for your attention !

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